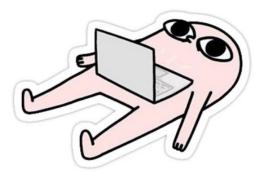


Special Topics in Manufacturing Slides With Notes

(1st Semester 2024/2025) Notes are written by Nada Ababneh



Chapter 1 Introduction

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(Not clear) (Not clear)

Fuzzy

- The word "fuzzy" means "not sharp, unclear, imprecise, approximate".
- Fuzziness occurs when the boundary of a piece of information is not clear-cut.
- Fuzzy vs vague (not specific, amorphous).
- Examples:

"see you in a few minutes" vs "see you soon".

Fuzzy vs vague (Nothing Specific) (approximetly) الله time الموجد (approximetly) يعني وقت مش معروف * example : * example : there is a quiz in 10 minutes there is a quiz

Note: * Part from the fuzziness comes from the probability

Fuzziness Reasoning

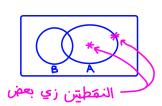
- Real world is too complex!
- Fuzziness introduced to obtain a reasonable model.
- Partial Success with 'quantitative' techniques.
- Expert knowledge' has become too important.



Crisp (classical) set

- It is defined by crisp (exact)
 boundaries (i.e. no uncertainty about the location of the set boundaries).
- Either an element belongs to the set or it does not. Either an for doesn't belong doesn't belong
- Used in digital system. as in computer either or zero

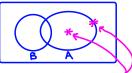
*Example:-crisp = { 1,2,3,4}



Fuzzy set

- It is defined by ambiguous boundaries (i.e. uncertainty about the location of the set boundaries).
- It contains objects that satisfy imprecise properties of membership (degree).
- Used in fuzzy controllers.

* Example :-Fuzzy = $\xi \frac{0.2}{1}, \frac{0.4}{2}, \frac{0.7}{3}$



Crisp vs Fuzzy Set

ExampleCrisp: Is water colourless? Yes

No

• Fuzzy: Is he honest? Extremely honest (0.3) Very honest (0.4) Sometimes (0.2) Dishonest (0.1)

Some examples of fuzzy applications

• Fuzzy Washing Machine:

✓ The first major consumer product to use 'fuzzy systems' (Matsushita Electric Industrial Company in Japan in 1991).

✓ The fuzzy system included 3 main input variables (the extent of dirt, the dirt type and the load size), which were measured using optical sensors, and one output (choice of the correct cycle).

Some examples of fuzzy applications

- Fuzzy Control of Subway Train (Sendai Subway in Japan):
 - ✓ Two controllers: Constant speed controller (Starts the train and keeps speed below its safety limit) and Automatic stopping controller (Regulates the speed limit to stop at a target position).
 - ✓ Sample Fuzzy Rules:
 - ≻<u>For Safety</u>

IF the speed of the train is approaching the limit speed, THEN select the maximum brake notch.

➢ For Riding Comfort

IF the speed is in the allowed range, THEN do not change the control notch.

Chapter 2 Crisp (Classical) Sets and Fuzzy Sets

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Crisp Set: Definitions

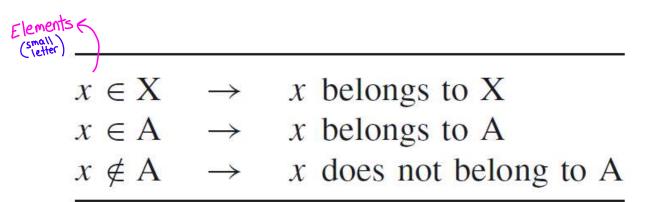
- Universe of discourse (X): A collection of objects having the same characteristics.
- The elements (x) of a universe are either discrete or continuous.
- Cardinal number (n_x) : The total number of elements in a universe.
- Discrete universes have a finite cardinal number, whereas continuous universes have an infinite cardinality.
- Set: Collections of elements within a UNIVERSE.
- Subset: Collections of elements within SETS.
- The whole set: collection of all elements in the set.



Crisp Set: Notations

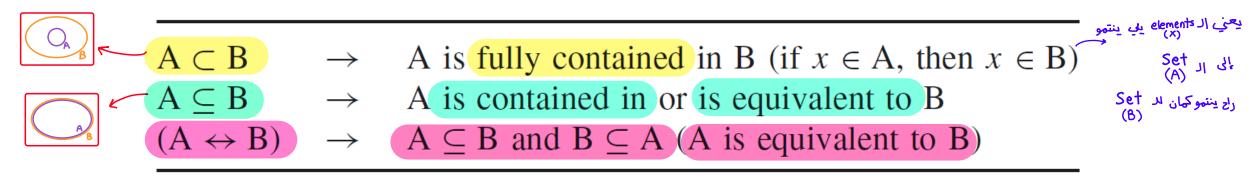
• Suppose that A and B consist of collections of some elements in X, then

() That means that A, B are sets



Continue...

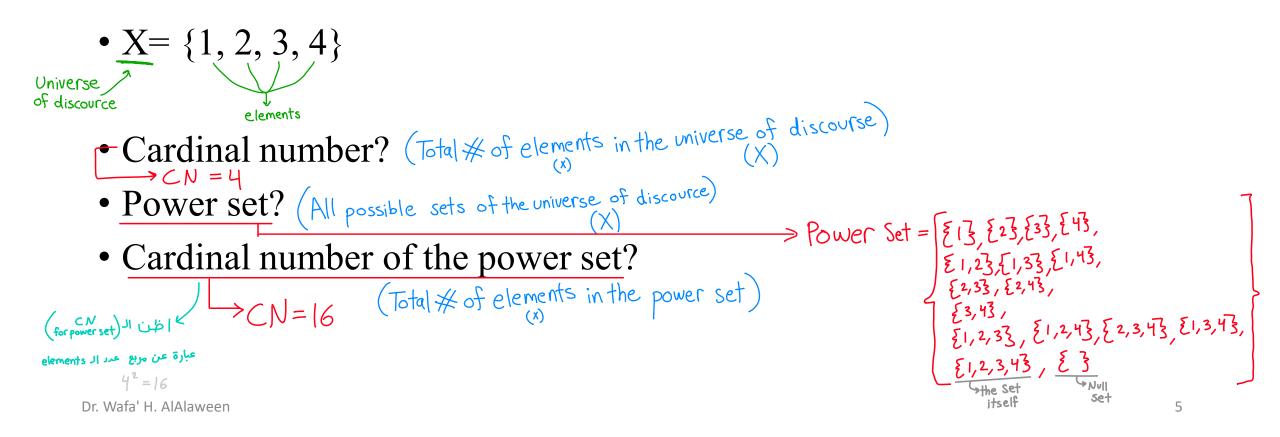
• Also



- Null set (Ø): The set that contains no elements.
- Power set (P(X)): All possible sets of X.

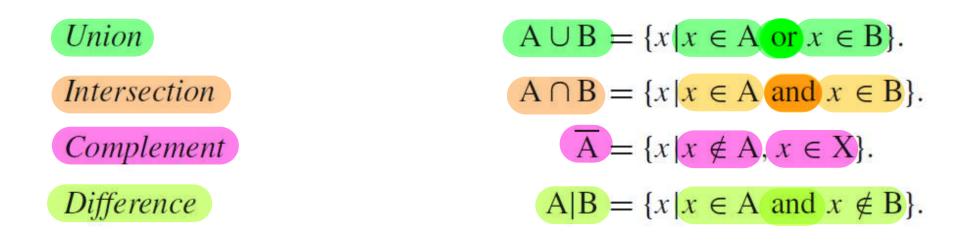
Continue...

• Example



Crisp Sets: Operations

• Suppose that A and B two sets on the universe X, then



• Such operations can be easily presented using Venn diagrams.

Set Operation	Venn Diagram	Interpretation
Union	A B	$A \cup B$, is the set of all values that are a member of A , or B , or both.
Intersection	AB	$A \cap B$, is the set of all values that are members of both A and B .
Difference	AB	$A \setminus B$, is the set of all values of A that are not members of B
X Symmetric Difference	AB	A riangle B, is the set of all values which are in one of the sets, but not both.

• Commutativity:
$$A \cup B = B \cup A$$

 $A \cap B = B \cap A.$



 $A \cup (B \cup C) = (A \cup B) \cup C$ $A \cap (B \cap C) = (A \cap B) \cap C.$



$$\underline{A \cup (B \cap C)} = (A \cup B) \cap (A \cup C)$$
$$\underline{A \cap (B \cup C)} = (A \cap B) \cup (A \cap C).$$

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Continue...

الفاعلية

• Idempotency:
$$A \cup A = A$$

 $A \cap A = A$

•

$$A \cup \emptyset = A$$
$$A \cap X = A$$
$$A \cap \emptyset = \emptyset.$$
$$A \cup X = X.$$

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Continue...

 A is contained in or is equivalent to B

 • Transitivity:
 If
$$(A \subseteq B)$$
 and $B \subseteq C$, then $A \subseteq C$.

 • Involution:
 $\overline{A} = A$.

 • Axiom of excluded middle:
 $A \cup \overline{A} = X$.

 • Axiom of contradiction:
 $A \cap \overline{A} = \emptyset$.

Continue...

• De Morgan's principles: The complement of a union or an intersection is equal to the intersection or union, respectively.

 $\overline{A \cap B} = \overline{A} \cup \overline{B}.$ $\overline{A \cup B} = \overline{A} \cap \overline{B}.$

Note for Fuzzy Sets (not from the slides)

0 and 1.

Membership Functions – Introduction

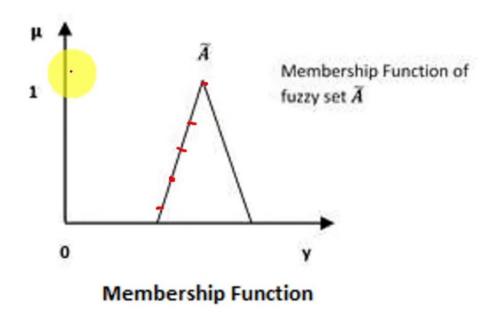
 Fuzzy sets may be viewed as an extension and generalization of the basic concepts of crisp sets.

 $A = \{\underline{1}, \underline{2}, 3, 4\} \subseteq$

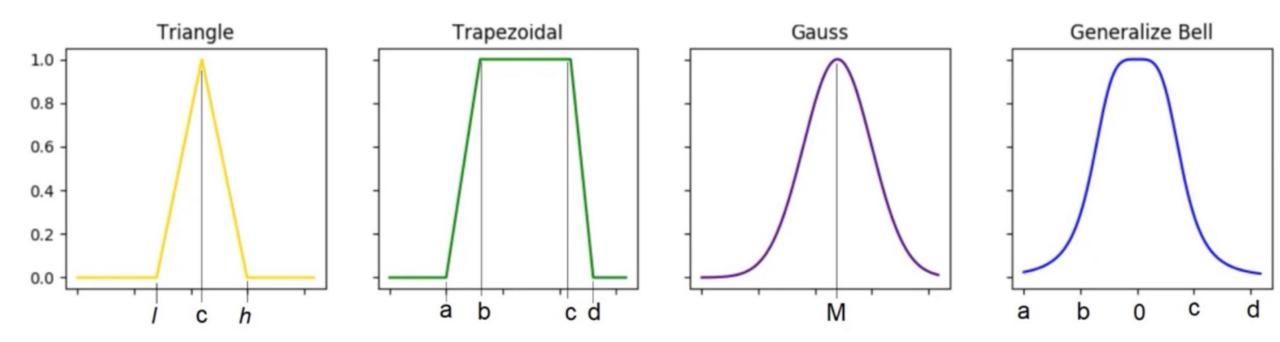
- An important property of fuzzy set is that it allows partial membership.
- A fuzzy set is a set having degrees of membership between 0 and 1.
- A membership function (MF) is a curve that defines

how each point in the input space is mapped to a

membership value (or degree of membership) between



Type of membership functions



à

- Each of the above membership functions are also known as fuzzy sets
- We normally choose the type of membership function that suites our application

Mapping of Crisp Sets to Functions

- Relating set-theoretic forms to function-theoretic terms.
- Mapping elements (subsets) in an universe of discourse to elements (subsets) in another one.
- Membership function is a mapping for a crisp set:

$$= \begin{cases} 1, & x \in A \\ 0, & x \notin A \end{cases}$$

Continue...

• Suppose that A and B are two sets on the universe X, then the function-theoretic terms:

Containment $A \subseteq B \longrightarrow \chi_A(x) \le \chi_B(x)$.

Membership degree with respect to B

> <u>* example</u> A= E orange, green, black B= E green CB CA

> > $M_{B}(green) \leq M_{A}(green)$

<u>*Note</u> & ussually the compliment is (one - membership degree) (crisp) ويكون البواب واحد أو صغر في ال



- Fuzzy sets contain elements that have varying degrees of membership.
- For discrete universe: $A = \left\{ \frac{\mu_{A}(x_{1})}{x_{1}} \oplus \frac{\mu_{A}(x_{2})}{x_{2}} \oplus \cdots \right\} = \left\{ \sum_{i} \frac{\mu_{A}(x_{i})}{x_{i}} \right\}$
- For continuous universe:

$$A_{\approx} = \left\{ \int \frac{\mu_{A}(x)}{x} \right\}$$

The summation and the integral signs are not algebraic symbols.

(X) universe of is All of the colors discorse

$$A = \begin{cases} \frac{0.8}{\text{orange}}, \frac{0.6}{9^{\text{reen}}}, \frac{0.2}{\text{black}} \end{cases}$$

$$A = \begin{cases} \frac{0.8}{9^{\text{reen}}}, \frac{0.2}{9^{\text{reen}}}, \frac{0.2}{9^{\text{black}}} \end{cases}$$

$$B = \begin{cases} \frac{0.4}{9^{\text{reen}}}, \frac{0.3}{\text{red}} \end{cases}$$

$$B = \begin{cases} \frac{0.4}{9^{\text{reen}}}, \frac{0.3}{\text{red}} \end{cases}$$

$$Union \rightarrow (A \cup B) = \begin{cases} \frac{0.8}{9^{\text{reen}}}, \frac{0.6}{9^{\text{reen}}}, \frac{0.3}{7^{\text{ed}}}, \frac{0.2}{9^{\text{black}}} \end{cases}$$

$$Intersection \rightarrow (A \cap B) = \begin{cases} \frac{0}{9^{\text{orange}}}, \frac{0.6}{9^{\text{reen}}}, \frac{0.3}{7^{\text{ed}}}, \frac{0.2}{9^{\text{lack}}} \end{cases}$$

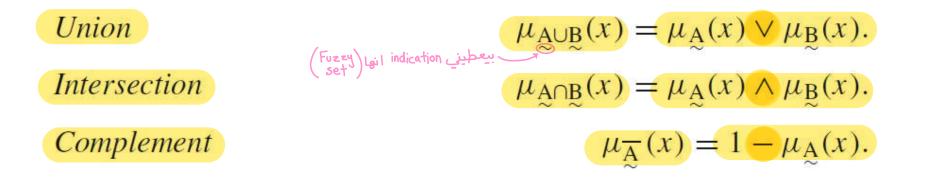
$$Intersection \rightarrow (A \cap B) = \begin{cases} \frac{0}{9^{\text{orange}}}, \frac{0.4}{9^{\text{reen}}}, \frac{0.4}{9^{\text{reen}}}, \frac{0.4}{9^{\text{reen}}}, \frac{0.2}{9^{\text{lack}}} \end{cases}$$

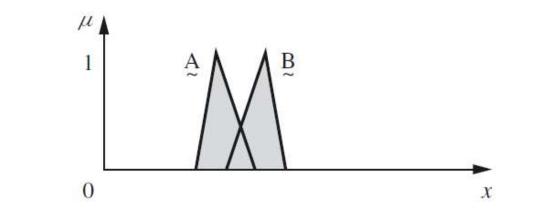
$$Intersection \rightarrow (A \cap B) = \begin{cases} \frac{0.2}{9^{\text{orange}}}, \frac{0.4}{9^{\text{reen}}}, \frac{0.8}{7^{\text{ed}}}, \frac{1}{9^{\text{lack}}}, \frac{1}{7^{\text{ed}}}, \frac{1}{7^{\text{ed}}} \end{cases}$$

$$Intersection \rightarrow (A \cap B) = \begin{cases} \frac{0.2}{9^{\text{orange}}}, \frac{0.4}{9^{\text{reen}}}, \frac{0.8}{9^{\text{reen}}}, \frac{1}{9^{\text{lack}}}, \frac{1}{7^{\text{ed}}}, \frac{1}{7^{\text{ed$$

Fuzzy Sets: Operations

• Suppose that \underline{A} and \underline{B} are two sets on the universe X, then the function-theoretic terms:





The excluded
$$\longrightarrow$$
 $A \cup \overline{A} = X.$
middle Axioms $A \cap \overline{A} = \emptyset.$ $A \cap \overline{A} = \emptyset.$

Continue...

- All the operations for classical sets are valid for fuzzy sets EXCEPT for the excluded middle axioms.
- The excluded middle axioms have been extended for fuzzy sets:

$$\begin{array}{l} \underbrace{A}{\approx} \cup \overline{A} \neq X. \\ \underbrace{A}{\approx} \cap \overline{A} \neq \emptyset. \end{array} \xrightarrow{} \text{ in Fuzzy} \end{array}$$

- De Morgan's principles for crisp sets are valid for fuzzy sets.
- Fuzzy intersections and unions can be represented as t-norms and t- conorms, respectively.

Union (L

Fuzzy Sets: Question

★ Power Set → All possible Sets of A
★ Cardinal number → The number of elements in the set

For a collection of fuzzy sets and subsets on a universe, what is:

- The fuzzy power set? 🔗
- The cardinal number of the fuzzy power set? \sim

• Suppose that we have two discrete fuzzy sets:

$$\left(A = \left\{ \frac{1}{2} + \frac{0.5}{3} + \frac{0.3}{4} + \frac{0.2}{5} \right\} \text{ and } \left(B = \left\{ \frac{1}{2} + \frac{0.7}{3} + \frac{0.2}{4} + \frac{0.4}{5} \right\} \right)$$

- Note that the membership function of 1 is Zero. <
- Calculate: <u>Complement</u>, <u>union</u>, <u>intersection</u> and <u>difference</u>.

Continue...

Complement	$\overline{A}_{\approx} = \left\{ \frac{1}{1} + \frac{0}{2} + \frac{0.5}{3} + \frac{0.7}{4} + \frac{0.8}{5} \right\}.$
	$\overline{\mathbf{B}} = \left\{ \frac{1}{1} + \frac{0.5}{2} + \frac{0.3}{3} + \frac{0.8}{4} + \frac{0.6}{5} \right\}.$
Union	$A_{\sim} \cup B_{\sim} = \left\{ \frac{1}{2} + \frac{0.7}{3} + \frac{0.3}{4} + \frac{0.4}{5} \right\}.$
Intersection	$A_{\sim} \cap B_{\sim} = \left\{ \frac{0.5}{2} + \frac{0.5}{3} + \frac{0.2}{4} + \frac{0.2}{5} \right\}.$
Difference	$\underline{A} \underline{B} = \underline{A} \cap \overline{\underline{B}} = \left\{ \frac{0.5}{2} + \frac{0.3}{3} + \frac{0.3}{4} + \frac{0.2}{5} \right\}.$ $\underline{B} \underline{A} = \underline{B} \cap \overline{\underline{A}} = \left\{ \frac{0}{2} + \frac{0.5}{3} + \frac{0.2}{4} + \frac{0.4}{5} \right\}.$
	$\underline{\mathbf{B}} \underline{\mathbf{A}} = \underline{\mathbf{B}} \cap \overline{\underline{\mathbf{A}}} = \left\{ \frac{0}{2} + \frac{0.5}{3} + \frac{0.2}{4} + \frac{0.4}{5} \right\}.$

Chapter 3 Crisp (Classical) Relations and Fuzzy Relations

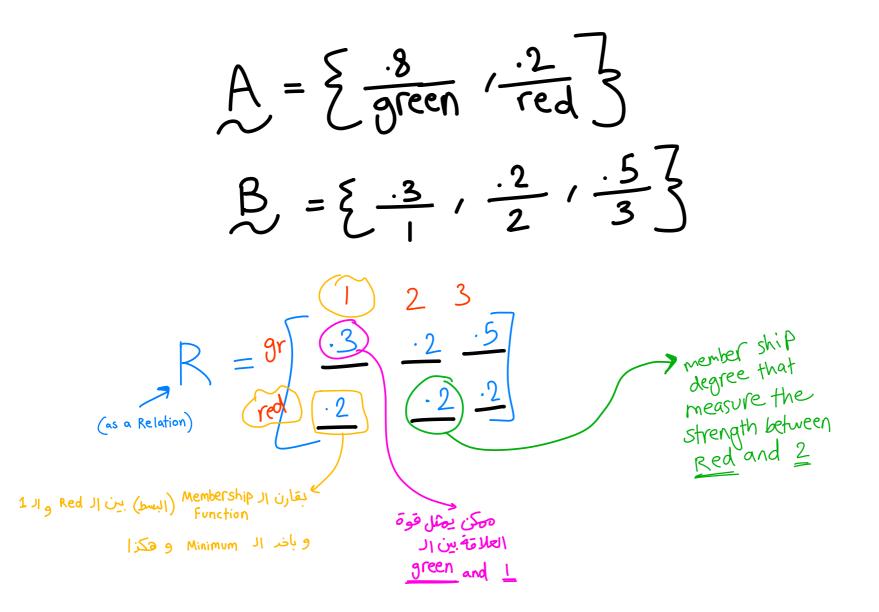
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Fuzzy Relations

- Fuzzy relations map elements of one universe to elements of another universe through the Cartesian product.
- The strength of the relation between ordered pairs of the two universes is measured with a membership function ($\mu_R(x, y)$).
- <u>The cardinality of fuzzy sets is infinity</u>, the <u>cardinality of a fuzzy relation</u> between two or more universes is also infinity.

* CN for
$$\frac{fuzzy}{Sets} \longrightarrow \infty$$

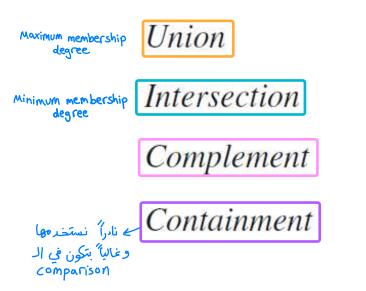
* CN for Fuzzy $\longrightarrow \infty$
Relations





• Let \mathbb{R} and \mathbb{S} be fuzzy relations on the <u>Cartesian space</u> $X \times Y$, then the following operations apply for the membership values:

R



$$\mu_{\mathbb{R}\cup\mathbb{S}}(x, y) = \max(\mu_{\mathbb{R}}(x, y), \mu_{\mathbb{S}}(x, y)).$$
$$\mu_{\mathbb{R}\cap\mathbb{S}}(x, y) = \min(\mu_{\mathbb{R}}(x, y), \mu_{\mathbb{S}}(x, y)).$$
$$\mu_{\mathbb{R}}(x, y) = 1 - \mu_{\mathbb{R}}(x, y).$$
$$\subset \underline{S} \Rightarrow \mu_{\mathbb{R}}(x, y) \le \mu_{\mathbb{S}}(x, y).$$

Fuzzy Relations: Properties

- As is the case in crisp relations, the properties of commutativity, associativity, distributivity, involution and idempotency are applicable for fuzzy relations.
- De Morgan's principles are applicable for fuzzy relations.

• Fuzzy relations are not constrained by the excluded middle axioms:

$$\begin{array}{c}
\mathbf{R} \bigcup_{x \downarrow x} \overline{\mathbf{R}} \neq \mathbf{E}. \\
\mathbf{N} \bigoplus_{x \downarrow x} \overline{\mathbf{R}} \neq \mathbf{O}. \\
\begin{array}{c}
\mathbf{O} = \begin{bmatrix}
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0
\end{array} \quad \mathbf{E} = \begin{bmatrix}
1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1
\end{array}$$



• Suppose A and B are <u>fuzzy sets</u> on <u>universes</u> X and Y, respectively, then the Cartesian product is presented as follows:

$$\underline{\mathbf{A}} \times \underline{\mathbf{B}} = \underline{\mathbf{R}} \subset X \times Y,$$

• The fuzzy relation R has the following membership function:

$$\mu_{\mathbb{R}}(x, y) = \mu_{\mathbb{A} \times \mathbb{B}}(x, y) = \min(\underline{\mu_{\mathbb{A}}(x)}, \underline{\mu_{\mathbb{B}}(y)}).$$

С

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Example

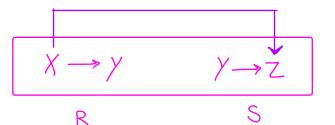
• Suppose that

$$A_{\approx} = \frac{0.2}{x_1} + \frac{0.5}{x_2} + \frac{1}{x_3}$$
 and $B_{\approx} = \frac{0.3}{y_1} + \frac{0.9}{y_2}$.

•
$$A \otimes B = ?$$

Cartesian Product
 $\begin{pmatrix} y_1 & y_2 \\ 0.2 & 0.2 \\ 0.3 & 0.5 \\ 0.3 & 0.9 \end{bmatrix}$
Minimum A
 $A \otimes B = ?$
 $(A \otimes B = ?)$
 $(A \otimes B = ?)$

6



(we use it when we don't have a direct Relation) • Suppose that \mathbb{R} and \mathbb{S} are fuzzy relations on the Cartesian space (X×Y) and (Y×Z), respectively, and \mathbb{T} is a fuzzy relation on (X×Z), then

• max—min composition can be defined as follows:

Fuzzy Relations: Composition

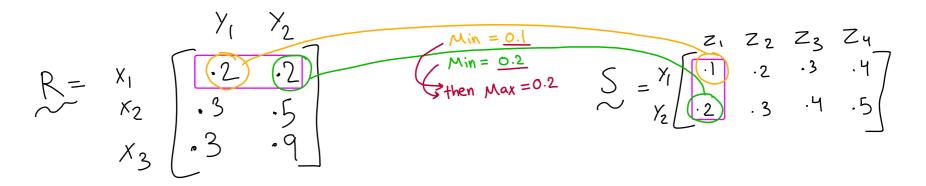
$$\underline{\mathbf{T}} = \underline{\mathbf{R}} \circ \underline{\mathbf{S}},$$

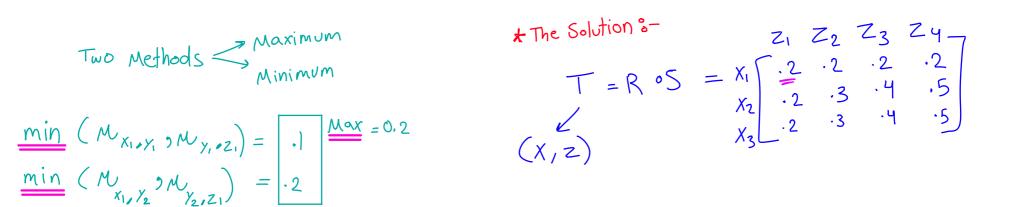
composition

$$\mu_{\widetilde{\mathbf{L}}}(x,z) = \bigvee_{\mathbf{y} \in \mathbf{Y}} (\mu_{\widetilde{\mathbf{R}}}(x,y) \wedge \mu_{\widetilde{\mathbf{S}}}(y,z)),$$



Max-Min Composition





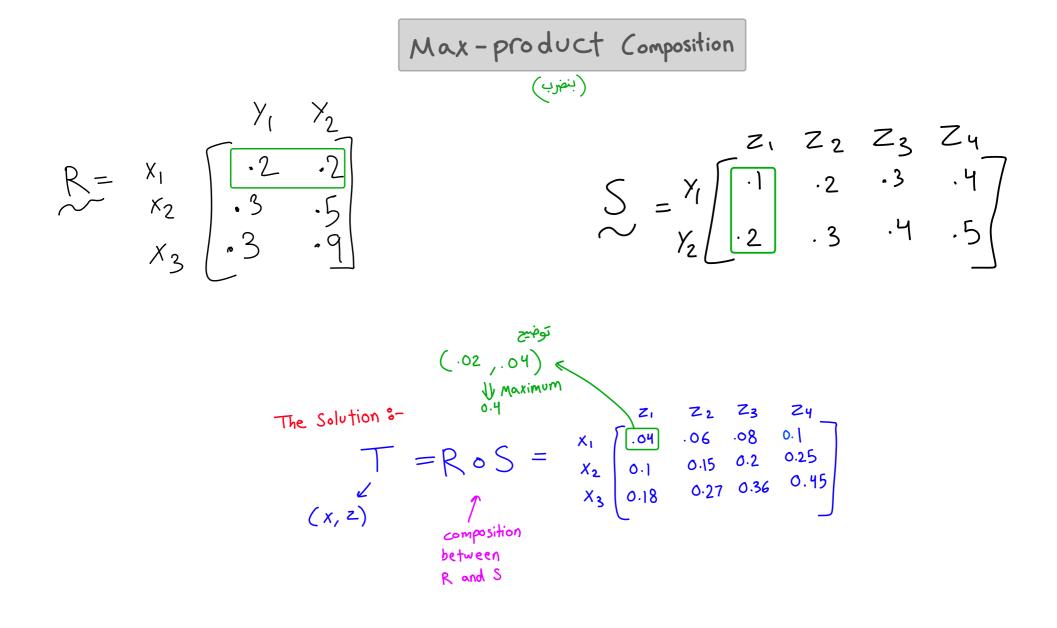
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• max–product composition can be defined as follows:

$$\mu_{\widetilde{\mathbb{T}}}(x,z) = \bigvee_{y \in \mathbb{Y}} (\mu_{\widetilde{\mathbb{R}}}(x,y) \bullet \mu_{\widetilde{\mathbb{S}}}(y,z)).$$

• Note that fuzzy composition is NOT commutative:

$$\underset{\sim}{\mathbb{R}}\circ\underset{\sim}{\mathbb{S}}\neq\underset{\sim}{\mathbb{S}}\circ\underset{\sim}{\mathbb{R}}.$$



Example

- Suppose that $X = \{x_1, x_2\}$, $Y = \{y_1, y_2\}$, and $Z = \{z_1, z_2, z_3\}$
- The fuzzy relations are as follows:

$$R_{\sim} = \frac{x_1}{x_2} \begin{bmatrix} 0.7 & 0.5\\ 0.8 & 0.4 \end{bmatrix} \text{ and } S_{\sim} = \frac{y_1}{y_2} \begin{bmatrix} 0.9 & 0.6 & 0.2\\ 0.1 & 0.7 & 0.5 \end{bmatrix}.$$

Maximum) à Minimum

• Using the <u>max-min</u> composition and max-product composition find the relation that relates the elements of universe X to the elements of universe Z.

Example (The Solution)

- Suppose that $X = \{x_1, x_2\}$, $Y = \{y_1, y_2\}$, and $Z = \{z_1, z_2, z_3\}$
- The fuzzy relations are as follows:

$$\Re = \frac{x_1}{x_2} \begin{bmatrix} y_1 & y_2 \\ 0.7 & 0.5 \\ 0.8 & 0.4 \end{bmatrix} \text{ and } \Re = \frac{y_1}{y_2} \begin{bmatrix} z_1 & z_2 & z_3 \\ 0.9 & 0.6 & 0.2 \\ 0.1 & 0.7 & 0.5 \end{bmatrix}.$$

• by Max-Min composition

$$\sum_{i=1}^{z_1} z_i z_i z_i z_i$$

$$\sum_{i=1}^{z_1} \sum_{i=1}^{z_2} z_i z_i$$

$$\sum_{i=1}^{z_1} \sum_{i=1}^{z_2} z_i z_i$$

$$\sum_{i=1}^{z_1} \sum_{i=1}^{z_2} z_i z_i$$

• by Max product Composition $T = R \circ S = X_1 \begin{bmatrix} 0.63 & 0.42 & 0.25 \\ 0.72 & 0.48 & 0.20 \end{bmatrix}$

Example(3.7) page(58)

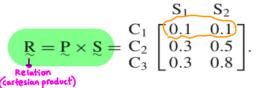
Example 3.7. A certain type of virus attacks cells of the human body. The infected cells can be visualized using a special microscope. The microscope generates digital images that medical doctors can analyze and identify the infected cells. The virus causes the infected cells to have a black spot, within a darker gray region (Figure 3.6).

A digital image process can be applied to the image. This processing generates two variables: the first variable, P, is related to black spot quantity (black pixels) and the second variable, S, is related to the shape of the black spot, that is, if they are circular or elliptic. In these images, it is often difficult to actually count the number of black pixels, or to identify a perfect circular cluster of pixels; hence, both these variables must be estimated in a linguistic way.

Suppose that we have <u>two fuzzy sets</u>: P that represents the number of black pixels (e.g., none with black pixels, C_1 , a few with black pixels, C_2 , and a lot of black pixels, C_3) and S that represents the shape of the black pixel clusters (e.g., S_1 is an ellipse and S_2 is a circle). So, we have

$$\underset{\text{spot}}{\overset{\text{P}}{=}} = \left\{ \underbrace{\frac{0.1}{C_1}}_{\text{none}} + \frac{0.5}{C_2} + \frac{1.0}{C_3} \right\} \text{ and } \underset{\text{shape of black spot}}{\overset{\text{shape of }}{=}} = \left\{ \underbrace{\frac{0.3}{S_1}}_{\text{ellipse}} + \frac{0.8}{S_2} \right\},$$

and we want to find the relationship between quantity of black pixels in the virus and the shape of the black pixel clusters. Using a Cartesian product between P and S gives



Now, suppose another microscope image is taken and the number of black pixels is slightly different; let the new black pixel quantity be represented by a fuzzy set, P':

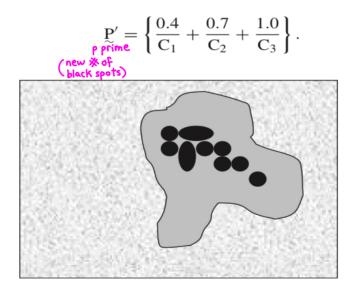


FIGURE 3.6

An infected cell shows black spots with different shapes in a micrograph.

Using max-min composition with the relation \mathbb{R} will yield a <u>new value for the fuzzy set of</u> pixel cluster shapes that are associated with the new black pixel quantity:

$$S'_{sprime} = P' \circ R = \begin{bmatrix} 0.4 & 0.7 & 1.0 \end{bmatrix} \circ \begin{bmatrix} 0.1 & 0.1 \\ 0.3 & 0.5 \\ 0.3 & 0.8 \end{bmatrix} = \begin{bmatrix} 0.3 & 0.8 \end{bmatrix}. \implies S' = \begin{cases} \frac{0.3}{S_1} & \frac{0.8}{S_2} \end{cases}$$

$$(0.1) = \begin{bmatrix} 0.1 & 0.1 \\ 0.3 & 0.5 \\ 0.3 & 0.8 \end{bmatrix} = \begin{bmatrix} 0.3 & 0.8 \end{bmatrix}.$$

Example(3.8) page(59)

Example 3.8. Suppose we are interested in understanding the speed control of the DC (direct current) shunt motor under no-load condition, as shown diagrammatically in Figure 3.7. Initially, the series resistance R_{se} in Figure 3.7 should be kept in the cut-in position for the following reasons:

- 1. The back electromagnetic force, given by $E_b = kN\phi$, where k is a constant of proportionality, N is the motor speed, and ϕ is the flux (which is proportional to input voltage, V), is equal to zero because the motor speed is equal to zero initially.
- 2. We have $V = E_b + I_a(R_a + R_{se})$, therefore $I_a = (V E_b)/(R_a + R_{se})$, where I_a is the armature current and R_a is the armature resistance. Since E_b is equal to zero initially, the armature current will be $I_a = V/(R_a + R_{se})$, which is going to be quite large initially and may destroy the armature.

On the basis of both cases 1 and 2, keeping the series resistance R_{se} in the cut-in position will restrict the speed to a very low value. Hence, if the rated no-load speed of the motor is 1500 rpm, then the resistance in series with the armature, or the shunt resistance R_{sh} , has to be varied.

Two methods provide this type of control: armature control and field control. For example, in armature control, suppose that ϕ (flux) is maintained at some constant value, then motor speed N is proportional to $E_{\rm b}$.

If R_{se} is decreased step by step from its high value, I_a (armature current) increases. Hence, this method increases I_a . On the other hand, as I_a is increased the motor speed N increases. These two possible approaches to control could have been done manually or automatically. Either way, however, results in at least two problems, presuming we do not want to change the design of the armature:

What should be the minimum and maximum level of R_{se} ? What should be the minimum and maximum value of I_a ?

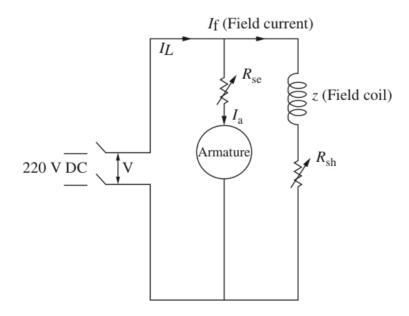


FIGURE 3.7 A DC shunt motor system.

Self

study

Now let us suppose that load on the motor is taken into consideration. Then the problem of control becomes twofold. First, owing to fluctuations in the load, the armature current may change, resulting in change in the motor speed. Second, as a result of changes in speed, the armature resistance control must be accomplished in order to maintain the motor's rated speed. Such control issues become very important in applications involving electric trains and a large number of consumer appliances making use of small batteries to run their motors.

We wish to use concepts of fuzzy sets to address this problem. Let R_{se} be a fuzzy set representing a number of possible values for series resistance, say s_n values, given as

$$\mathbf{R}_{se} = \{R_{s_1}, R_{s_2}, R_{s_3}, \dots, R_{s_n}\},\$$

and let \underline{I}_a be a fuzzy set having a number of possible values of the armature current, say *m* values, given as

$$I_{a} = \{I_1, I_2, I_3, \dots, I_m\}.$$

The fuzzy sets \underline{R}_{se} and \underline{I}_{a} can be related through a fuzzy relation, say \underline{R} , which would allow for the establishment of various degrees of relationship between pairs of resistance and current. In this way, the resistance–current pairings could conform to the modeler's intuition about the trade-offs involved in control of the armature.

Let \underbrace{N} be another fuzzy set having numerous values for the motor speed, say v values, given as

$$\mathbf{N} = \{N_1, N_2, N_3, \dots, N_v\}.$$

Now, we can determine another fuzzy relation, say \underline{S} , to relate current to motor speed, that is, \underline{I}_a to \underline{N} .

Using the operation of composition, we could then compute a relation, say \underline{T} , to be used to relate series resistance to motor speed, that is, \underline{R}_{se} to \underline{N} . The operations needed to develop these relations are as follows – two fuzzy Cartesian products and one composition:

$$\begin{split} &\underset{\approx}{\mathbb{R}} = \underset{se}{\mathbb{R}} \times \underset{se}{\mathbb{I}}_{a}, \\ &\underset{\approx}{\mathbb{S}} = \underset{a}{\mathbb{I}}_{a} \times \underset{\approx}{\mathbb{N}}, \\ &\underset{\approx}{\mathbb{T}} = \underset{\approx}{\mathbb{R}} \circ \underset{\approx}{\mathbb{S}}. \end{split}$$

Suppose the membership functions for both series resistance \underline{R}_{se} and armature current \underline{I}_{a} are given in terms of percentages *of their respective rated values*, that is,

$$\mu_{\rm R_{se}}(\% {\rm se}) = \frac{0.3}{30} + \frac{0.7}{60} + \frac{1.0}{100} + \frac{0.2}{120}$$

and

$$\mu_{I_a}(\%a) = \frac{0.2}{20} + \frac{0.4}{40} + \frac{0.6}{60} + \frac{0.8}{80} + \frac{1.0}{100} + \frac{0.1}{120},$$

and the membership value for N is given in units of motor speed in rpm,

$$\mu_{\rm N}(\rm rpm) = \frac{0.33}{500} + \frac{0.67}{1000} + \frac{1.0}{1500} + \frac{0.15}{1800}.$$

The following relations then result from use of the Cartesian product to determine \mathbb{R} and \mathbb{S} :

							120
$\underset{\sim}{\mathbb{R}} =$	30	[0.2]	0.3	0.3	0.3	0.3	0.1 7
	60	0.2	0.4	0.6	0.7	0.7	0.1
	100	0.2	0.4	0.6	0.8	1	0.1
	120	0.2	0.2	0.2	0.2	0.2	0.1

and

		500	1000	1500	1800
	20	□ 0.2	0.2	0.2	0.15 T
$\tilde{S} =$	40	$\begin{bmatrix} 0.2 \\ 0.33 \end{bmatrix}$	0.4	0.4	0.15
	60	0.33	0.6	0.6	0.15
	80	0.33	0.67	0.8	0.15
	100	0.33	0.67	1	0.15
	120	L 0.1	0.1	0.1	0.1

For example, $\mu_{\rm R}(60, 40) = \min(0.7, 0.4) = 0.4$, $\mu_{\rm R}(100, 80) = \min(1.0, 0.8) = 0.8$, and $\mu_{\rm S}(80, 1000) = \min(0.8, 0.67) = 0.67$.

The following relation results from a max-min composition for \underline{T} :

$$\mathbf{\tilde{T}} = \mathbf{R} \circ \mathbf{\tilde{S}} = \begin{bmatrix} 30 & 1000 & 1500 & 1800 \\ 30 & 0.3 & 0.3 & 0.3 & 0.15 \\ 0.33 & 0.67 & 0.7 & 0.15 \\ 0.33 & 0.67 & 1 & 0.15 \\ 0.2 & 0.2 & 0.2 & 0.15 \end{bmatrix}.$$

For instance,

$$\mu_{\widetilde{L}}(60, 1500) = \max[\min(0.2, 0.2), \min(0.4, 0.4), \min(0.6, 0.6), \\ \min(0.7, 0.8), \min(0.7, 1.0), \min(0.1, 0.1)]. \\ = \max[0.2, 0.4, 0.6, 0.7, 0.7, 0.1] = 0.7.$$

Crisp Relations: Tolerance and Equivalence Relation

• <u>A relation is considered as an</u> equivalence relation if it has the following three properties:

 $\xrightarrow{0}{\longrightarrow} Reflexivity$ $\xrightarrow{2}{\longrightarrow} Symmetry$

 $\xrightarrow{3} Transitivity$ $\overset{\zeta}{}_{3 \text{ elements}}$

$$\begin{aligned} (x_i, x_i) \in \mathbb{R} \text{ or } \chi_{\mathbb{R}}(x_i, x_i) &= 1. \\ (x_i, x_j) \in \mathbb{R} \longrightarrow (x_j, x_i) \in \mathbb{R} \\ \text{or } \left(\chi_{\mathbb{R}}(x_i, x_j) = \chi_{\mathbb{R}}(x_j, x_i). \right) &\leftarrow \text{Membership degree} \\ (x_i, x_j) \in \mathbb{R} \text{ and } (x_j, x_k) \in \mathbb{R} \longrightarrow (x_i, x_k) \in \mathbb{R} \\ \text{or } \chi_{\mathbb{R}}(x_i, x_j) \text{ and } \chi_{\mathbb{R}}(x_j, x_k) &= 1 \longrightarrow \chi_{\mathbb{R}}(x_i, x_k) = 1. \end{aligned}$$

Continue...

• A tolerance (proximity) relation: A relation that exhibits only the properties of reflexivity and symmetry.

• It can be reformed into an equivalence relation by AT MOST (CN-1) compositions with itself, as follows:

$$\mathbf{R}_1^{n-1} = \mathbf{R}_1 \circ \mathbf{R}_1 \circ \cdots \circ \mathbf{R}_1 = \mathbf{R}$$

Fuzzy Relations: Tolerance and Equivalence Relation

• A fuzzy relation is considered as a fuzzy equivalence relation if it has the following properties:

Reflexivity
$$\mu_{\mathbb{R}}(x_i, x_i) = 1.$$
Symmetry $\mu_{\mathbb{R}}(x_i, x_j) = \mu_{\mathbb{R}}(x_j, x_i).$ in a matrix
the upper = lower
partTransitivity $\mu_{\mathbb{R}}(x_i, x_j) = \lambda_1$ and $\mu_{\mathbb{R}}(x_j, x_k) = \lambda_2 \longrightarrow \mu_{\mathbb{R}}(x_i, x_k) = \lambda,$
where $\lambda \ge \min[\lambda_1, \lambda_2].$ where $\lambda \ge \min[\lambda_1, \lambda_2].$ $\omega_{\mathbb{R}}(x_i)$ is a state of the upper state of the

Continue...

• A fuzzy tolerance (proximity) relation: A fuzzy relation that exhibits only the properties of reflexivity and symmetry.

X تنطرة

• It can be reformed into an equivalence fuzzy relation by AT MOST (CN-1) compositions with itself, as follows:

$$\mathbf{R}_1^{n-1} = \mathbf{R}_1 \circ \mathbf{R}_1 \circ \cdots \circ \mathbf{R}_1 = \mathbf{R}$$



• A fuzzy relation is as follows:

$$\mathbf{R}_1 = \begin{bmatrix} 1 & 0.8 & 0 & 0.1 & 0.2 \\ 0.8 & 1 & 0.4 & 0 & 0.9 \\ 0 & 0.4 & 1 & 0 & 0 \\ 0.1 & 0 & 0 & 1 & 0.5 \\ 0.2 & 0.9 & 0 & 0.5 & 1 \end{bmatrix}$$

• Is it reflexive, symmetric, transitive?

The Solution 8-

where $\lambda \geq \min[\lambda_1, \lambda_2]$.

is <u>reflexive</u> and <u>symmetric</u>. However, it is not transitive, for example,

main Diagonal is one in the Matrix upper $\mu_{\mathbb{R}}(x_1, x_2) = 0.8$, $\mu_{\mathbb{R}}(x_2, x_5) = 0.9 \ge 0.8$, part = part

but

$$\mu_{\mathbf{R}}(x_1, x_5) = 0.2 \le \min(0.8, 0.9).$$

One composition results in the following relation:

$$\mathbb{R}^{2}_{1} = \mathbb{R}_{1} \circ \mathbb{R}_{1} = \begin{bmatrix} 1 & 0.8 & 0.4 & 0.2 & 0.8 \\ 0.8 & 1 & 0.4 & 0.5 & 0.9 \\ 0.4 & 0.4 & 1 & 0 & 0.4 \\ 0.2 & 0.5 & 0 & 1 & 0.5 \\ 0.8 & 0.9 & 0.4 & 0.5 & 1 \end{bmatrix},$$

where transitivity still does not result; for example,

لازم کل ال possibilities يتحققو

$$\mu_{\mathbb{R}^2}(x_1, x_2) = 0.8 \ge 0.5$$
 and $\mu_{\mathbb{R}^2}(x_2, x_4) = 0.5$,

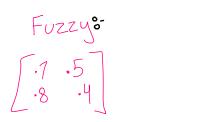
but

$$\mu_{\mathbb{R}^2}(x_1, x_4) = 0.2 \le \min(0.8, 0.5).$$

Finally, after one or two more compositions, transitivity results:

$$\mathbf{R}_{1}^{3} = \mathbf{R}_{1}^{4} = \mathbf{R} = \begin{bmatrix} 1 & 0.8 & 0.4 & 0.5 & 0.8 \\ 0.8 & 1 & 0.4 & 0.5 & 0.9 \\ 0.4 & 0.4 & 1 & 0.4 & 0.4 \\ 0.5 & 0.5 & 0.4 & 1 & 0.5 \\ 0.8 & 0.9 & 0.4 & 0.5 & 1 \end{bmatrix}$$

$$\begin{aligned} &\mathbb{R}_{1}^{3}(x_{1}, x_{2}) = 0.8 \ge 0.5. \\ &\mathbb{R}_{1}^{3}(x_{2}, x_{4}) = 0.5 \ge 0.5. \\ &\mathbb{R}_{1}^{3}(x_{1}, x_{4}) = 0.5 \ge 0.5. \end{aligned}$$





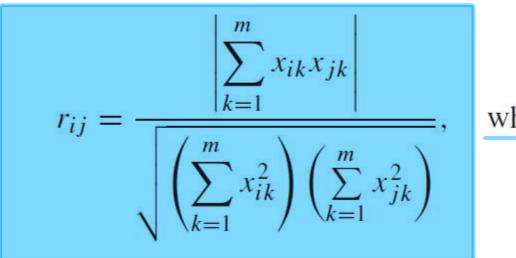
- Cartesian product,
- → <u>Closed-form expression</u>,
- → Lookup table,
- Linguistic rules of knowledge,
- → Classification,
- -• Automated methods from input/output data,

Value Assignment Methods

-• Similarity methods in data manipulation.

Cosine Amplitude Method (Similarity Method)

- A similarity metric that uses a collection of data samples.
- It can be presented as follows:



where i, j = 1, 2, ..., n.

- A similarity metric that uses a collection of data samples. It is computationally simpler than the cosine amplitude method.
- It can be presented as follows:

$$r_{ij} = \frac{\sum_{k=1}^{m} \min(x_{ik}, x_{jk})}{\sum_{k=1}^{m} \max(x_{ik}, x_{jk})},$$

where
$$i, j = 1, 2, ..., n$$

Example (3.12) page (71)

Five separate regions along the San Andreas fault in California have suffered damage from a recent earthquake. For purposes of assessing payouts from insurance companies to building owners, the five regions must be classified as to their damage levels. Expression of the damage in terms of relations will prove helpful. Surveys are conducted of the buildings in each region. All the buildings in each region are described as being in one of three damage states: no damage, medium damage, and serious damage. Each region has each of these three damage states expressed as a percentage (ratio) of the total number of buildings. The following table summarizes the findings of the survey team:

مستحيل الجواب يكون أكبر من واحر

Minimum q:5) Maximum

Continue...

Regions	<i>x</i> ₁	x_2	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> 5
x_{i1} – Ratio with no damage	0.3	0.2	0.1	0.7	0.4
x_{i2} – Ratio with medium damage	0.6	0.4	0.6	0.2	0.6
x_{i3} – Ratio with serious damage	<mark>0.</mark> 1	0.4	0.3	0.1	0.0

By using the cosine amplitude and max-min methods, express these data as a fuzzy relation.

Continue...

Cosine amplitude method:

Max-min method:

R	1 0.836 0.914	1	1	sym		$\mathbf{R}_1 =$	1 0.538 0.667		1	sym		
	0.682 0.982	0.6	0.441	1 0.774	1		0.429	0.333	0.250 0.538	1 0.429	1	

	Cosine Ampli	itude	Meth	od) واحر)	of Relation) اکبر مز of Relation
	Regions	x_1	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅
	x_{i1} – Ratio with no damage x_{i2} – Ratio with medium damage x_{i3} – Ratio with serious damage	0.3 0.6 0.1	0.2 0.4 0.4	0.1 0.6 0.3	0.7 0.2 0.1	0.4 0.6 0.0
$R = X_{i} \prod_{i=1}^{N_{i}}$	X2 X3 X4 X5 155 symmetric	ن أكتر وه '	ق التي تض _{رر}	ايجاد الهناط		
$\begin{array}{c} X_{2} \\ X_{2} \\ X_{3} \\ X_{4} \\ X_{5} \end{array}$	56 Symmetric		r _{ij} =		X _{ik} X _{ji}	$\frac{k}{\left(\sum_{K=1}^{m} X^{2}_{jK}\right)}$
$\Gamma_{12} = \left (\cdot 3_{X}, 2) + (\cdot 6_{X}) \right $		0.34 0.46×0.3		836		
$r_{13} = \left \left(\cdot 3 \times \cdot 1 \right) + \left(\cdot \right) \right $	$ \frac{1^{2}}{\chi(\cdot 2^{2} + 4^{2} + 4^{2})} = 0.914 $ $ \frac{1^{2}}{\chi(\cdot 2^{2} + 4^{2} + 4^{2})} = 0.914 $ $ \frac{1^{2}}{\chi(\cdot 1^{2} + 6^{2} + 3)^{2}} = 0.914 $		$\frac{R}{\sim}$ 1		inal Result 36 1 14 0.93 82 0.6 82 0.74	sym 54 1 5 0.441 1 4 0.818 0.774 1

Max-Min Method

Regions	x_1	x_2	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅
x_{i1} – Ratio with no damage	0.3	0.2	0.1	0.7	0.4
x_{i2} – Ratio with medium damage	0.6	0.4	0.6	0.2	0.6
x_{i3} – Ratio with serious damage	0.1	0.4	0.3	0.1	0.0

$$R = X_{1} | X_{2} | X_{3} | X_{4} | X_{5} | X_{2} | X_{3} | X_{4} | X_{5} | X_{2} | 0.5385 | X_{3} | 0.667 | 0.667 | X_{4} | X_{5} | U_{5} |$$

$$\Gamma_{ij} = \frac{\sum_{k=1}^{m} \min(X_{ik}, X_{jk})}{\sum_{k=1}^{m} \max(X_{ik}, X_{jk})}$$

$$r_{12} = \frac{0.2 + 0.4 + 0.1}{0.3 + 0.6 + 0.4} = 0.5385$$

$$r_{13} = \frac{0.1 + 0.6 + 0.1}{0.3 + 0.6 + 0.3} = 0.667$$

$$r_{23} = \frac{0.1 + 0.4 + 0.3}{0.2 + 0.6 + 0.4} = 0.667$$

*The	Final Res	ult "-				
Г	1					-
	0.538	1		sym		
$R_1 =$	0.667	0.667	1			
~-	0.429	0.333	0.250	1		
			0.538	0.429	1	
100						-

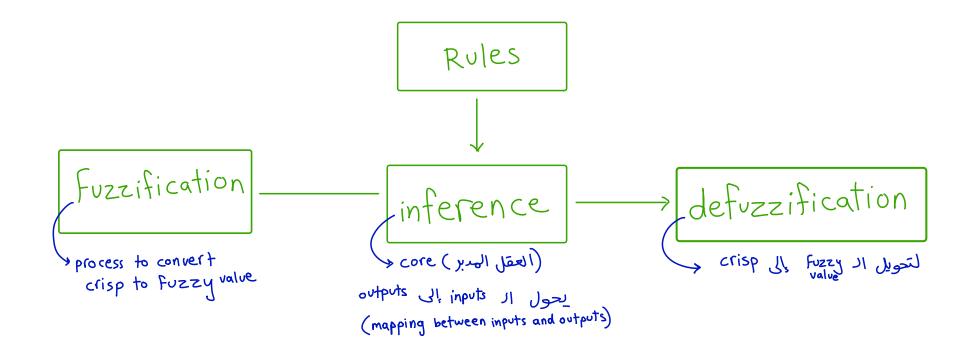
Chapter 4 Properties of Membership Functions, Fuzzification and Defuzzification

Chapter 4,5,6 talks about Fuzzy Systems

Dr. Wafa' H. AlAlaween wafa.alalaween@gmail.com

 $F S \longrightarrow fuzzy System$ $F I S \longrightarrow Fuzzy inference system$

Blocks of fuzzy



Membership Function: Definition

- A membership function: The values assigned to elements of a universal set fall within a specified range.
- It describes the information contained in a fuzzy set.
- Larger values indicate higher degrees of membership.
- The core: The region (element) of a universe that is characterized by full membership in a set. الحرم المساعة الحرم المساعة الحرم المساعة الحرم المساعة الحرم المساعة ال
- The support: The region (element) of a universe that is characterized by nonzero membership in a set.

مدى انتماء التي لديني محمد Membership

کل *ما* کانت ال values أکبر

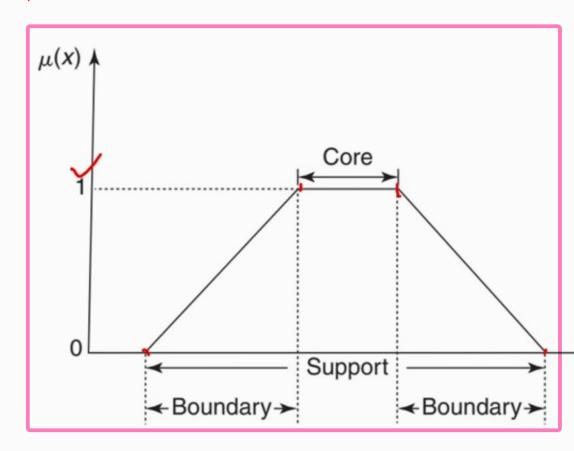
degree معتقد المعامة ال المعامة المعامة

Features of Membership Functions

- Core: The core of a membership function for some fuzzy set <u>A</u> is defined as that region of universe that is characterized by complete membership in the set <u>A</u>.
- The core has elements x of the universe such that

$$\mu_{\underline{A}}(x) = \mathbf{1}$$

: reget



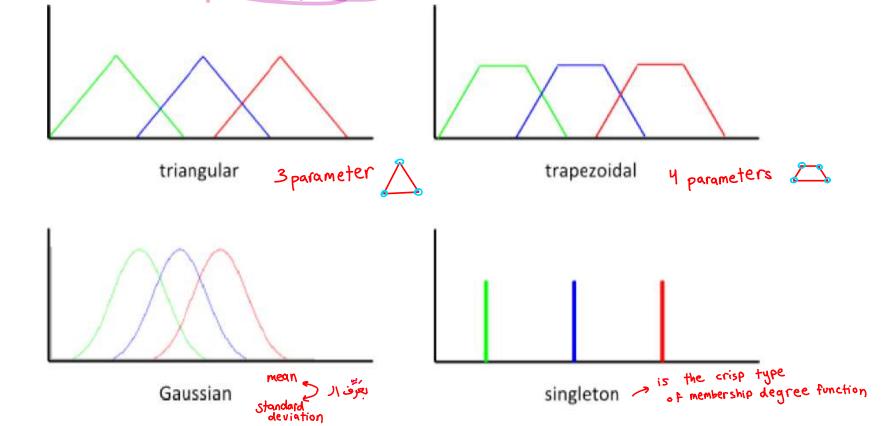
Continue...

- A normal fuzzy set: A set whose membership function has at least one element whose membership value is unity.
- Prototype: It is an element (only one element) that has a membership value that is equal to one.
- A convex fuzzy set: It is a set which is described by a membership function whose values are (1) strictly monotonically increasing, (2) strictly monotonically decreasing, or (3) monotonically increasing then decreasing with increasing the elements values.
- The height of a fuzzy set is the maximum value of the membership function.

Membership Functions: Types

- Membership functions can be symmetrical or asymmetrical.
- They can also be defined as 1D or nD membership functions.

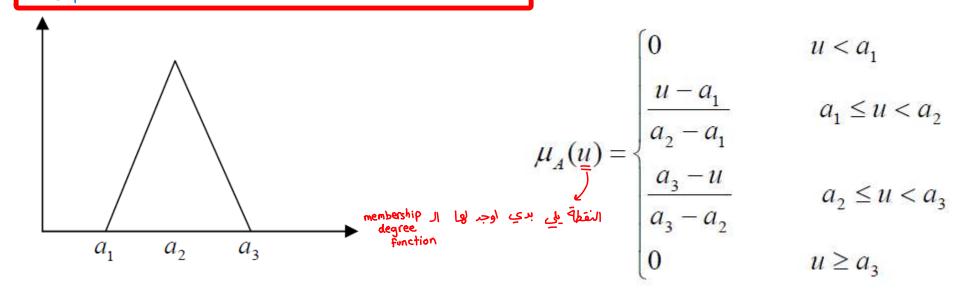
In Matlab, the fuzzy logic toolbox includes 11 built-in membership function types.



Fuzzification

• Fuzzification represents the process of mapping crisp values to fuzzy sets.

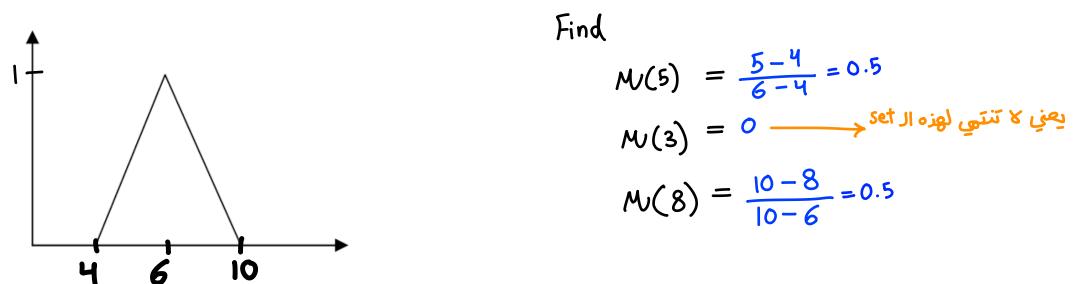
a) <u>Triangular</u> Membership Function:



Examp

Fuzzification

- Fuzzification represents the process of mapping crisp values to fuzzy sets.
- a) Triangular Membership Function:

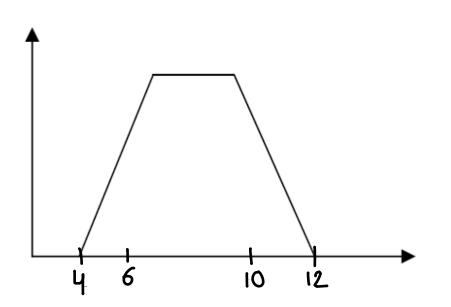


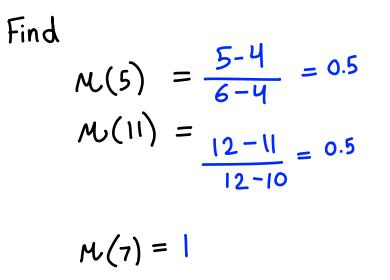
$$\mu_{A}(u) = \begin{cases} 0 & u < a_{1} \\ u = a_{1} \\ a_{1} \\ a_{2} \\ a_{3} \\ a_{4} \\ 0 \\ u \ge a_{4} \end{cases}$$

$$\mu_{A}(u) = \begin{cases} 0 & u < a_{1} \\ u = a_{1} \\ a_{2} \\ a_{3} \\ a_{4} \\ u \ge a_{4} \\ 0 \\ u \ge a_{4} \\ u \ge a_{4} \\ u \ge a_{4} \end{cases}$$

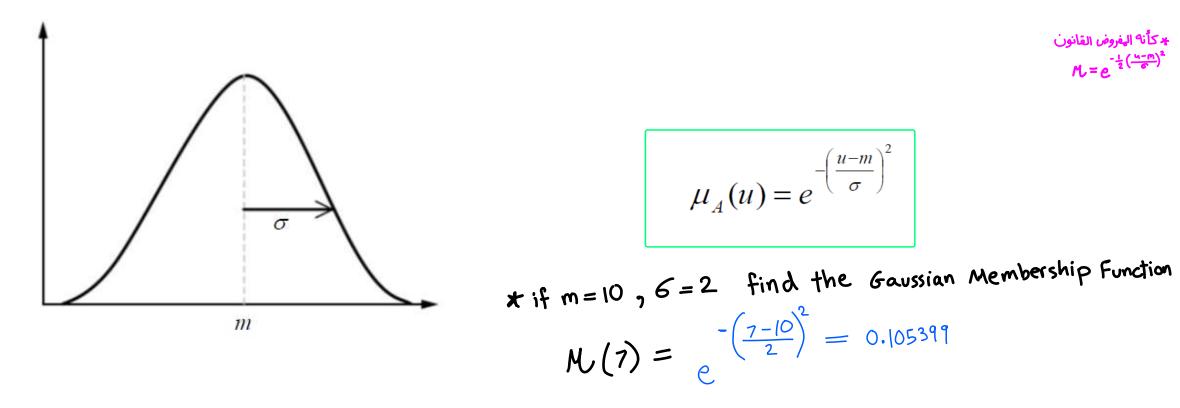


b) Trapezoidal Membership Function:





c) Gaussian Membership Function:



اذا كان عنري Fuzzy Valve جن كيف الاقي العامه crisp Valve جن

Defuzzification

- Defuzzification represents the process of mapping fuzzy values to crisp ones.
- Methods (common):

a) Max membership (the height method): $\mu_{\mathbb{C}}(z^*) \ge \mu_{\mathbb{C}}(z)$

ل disadvantage الله نفس ال height التو نفس الر

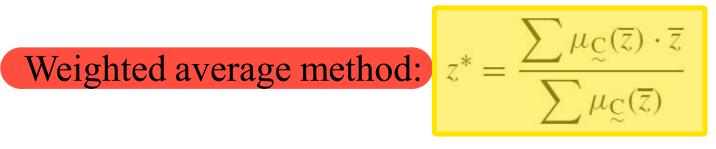
کی بالعادة بستخدمها میس یکون عنا ^eprototype

(نفطة وحدة عالية)

b) Centroid method (centre of area/gravity):

$$z^* = \frac{\int \mu_{\mathbb{C}}(z) \cdot z \, \mathrm{d}z}{\int \mu_{\mathbb{C}}(z) \, \mathrm{d}z}$$







Sum of Membership function

$$Z^{*} = \frac{(2.5_{\chi}0.3) + (5_{\chi}.5) + (6.5_{\chi}1)}{0.3 + 0.5 + 1}$$

Mean max membership: This method is similar to the maximum (d رالفرق بین³و بین ^{Max} به membership یفضل استخدادها membership method, except that the locations of the maximum لها يكون عندي أكتر من قيمة بنروح لأعلى قيمة Membership و باخذ إل Mean membership can be non-unique.

ntinue...
Proposed A rea =
$$\frac{1}{2} \times \left(\frac{1}{2} \times \frac{1$$

 $\frac{1}{2}(5+3) \times \cdot 3 + \frac{1}{2}(2+4) \times 0.5 + \frac{1}{2}(3+1) \times 1$

Note: Two drawbacks to this method are that the intersecting areas are added twice, and the method also involves finding the centroids of the individual membership functions.

Co

e) (

f) Centre of largest area:
$$z^* = \int \mu_{\mathbb{C}_m}(z) z \, dz$$
 it will give me almost the centroid in the convex region X (we will not use it) $\int \mu_{\mathbb{C}_m}(z) \, dz$ It is a CONVEX sub region

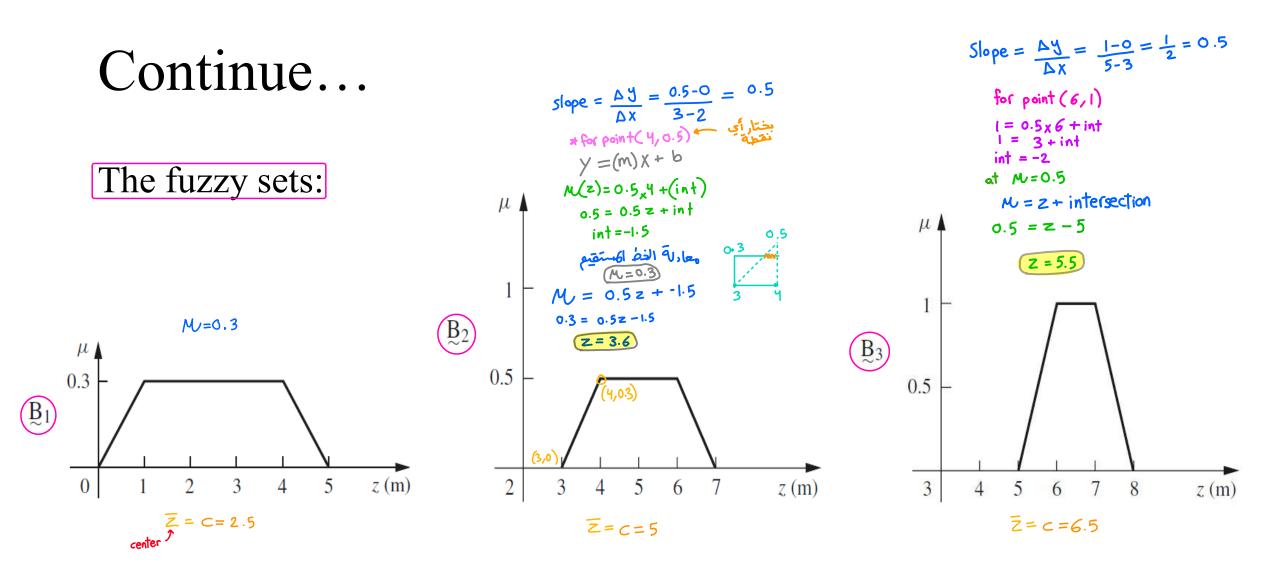
g) First (or last) of maxima: The value of the domain with maximized membership degree.

$$hgt(\underline{C}_k) = \sup_{z \in Z} \mu_{\underline{C}_k}(z) \longrightarrow z^* = \inf_{z \in Z} \{z \in Z | \mu_{\underline{C}_k}(z) = hgt(\underline{C}_k) \}$$

Example

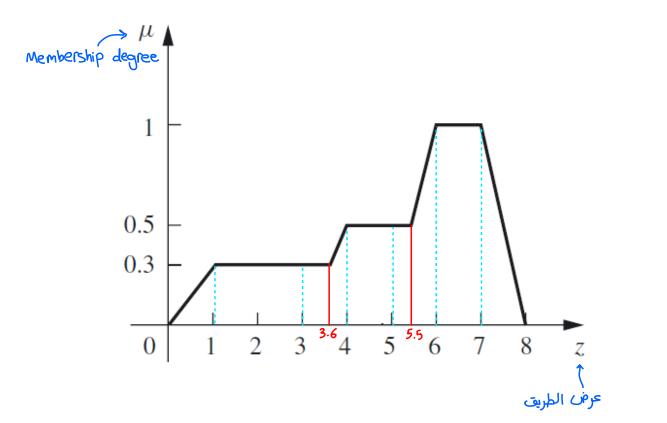
بدنا نتحمل طريق و لازم نلاحي عرض الطريق B1 جدنا نتحمل طع¹ B2 علنا ^{B1} B3 B3 it is asking me to deffuzify each value B1 B3 B3

A railroad company intends to lay a new rail line in a particular part of a county. The whole area through which the new line is passing must be purchased for right-of-way considerations. It is surveyed in three stretches, and the data are collected for analysis. The surveyed data for the road are given by the sets: B1, B2 and B3, where the sets are defined on the universe of right-of-way widths, in meters. For the railroad to purchase the land, it must have an assessment of the amount of land to be bought. The three surveys on right-of-way width are ambiguous, however, because some of the land along the proposed railway route is already public domain and will not need to be purchased. Additionally, the original surveys are so old (circa 1860) that some ambiguity exists on boundaries and public right-of-way for old utility lines and old roads. The three fuzzy sets shown in the Figures below, represent the uncertainty in each survey as to the membership of right-of-way width, in meters, in privately owned land.



Continue... union for the three fuzzy sets

Find the single most nearly representative right-of-way width (z).



Continue...
Using the centroid
method:

$$\vec{z}^* = \frac{\int \mu_{\mathbb{R}}(z) \cdot z \, dz}{\int \mu_{\mathbb{R}}(z) \, dz}$$

 $z^* = \frac{\int \mu_{\mathbb{R}}(z) \cdot z \, dz}{\int \mu_{\mathbb{R}}(z) \, dz}$
 $z^* = \frac{\int \mu_{\mathbb{R}}(z) \cdot z \, dz}{\int \mu_{\mathbb{R}}(z) \, dz}$
 $z^* = \frac{\int \mu_{\mathbb{R}}(z) \cdot z \, dz}{\int \mu_{\mathbb{R}}(z) \, dz}$
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 $z^* = \frac{\int \mu_{\mathbb{R}}(z) \cdot z \, dz}{\int \mu_{\mathbb{R}}(z) \, dz}$
 $z^* = \frac{\int \mu_{\mathbb{R}}(z) \cdot z \, dz}{\int \mu_{\mathbb{R}}(z) \, dz}$
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 $z^* = \frac{\int \mu_$

Using the weighted average method: $z^* = \frac{(0.3 \times 2.5) + (0.5 \times 5) + (1 \times 6.5)}{0.3 + 0.5 + 1} = 5.41 \text{ m},$

Using the centre of sum method:
$$z^* = \frac{[2.5 \times 0.5 \times 0.3(3+5) + 5 \times 0.5 \times 0.5(2+4) + 6.5 \times 0.5 \times 1(3+1)]}{[0.5 \times 0.3(3+5) + 0.5 \times 0.5(2+4) + 0.5 \times 1(3+1)]}$$
$$= 5.0 \text{ m},$$

The centre of largest area method provides the same result as the centroid method ($z^{*}=4.9$).

Using the first of maxima method $z^*= 6$.

Using the last of maxima method z = 7.

Dr. Wafa' H. AlAlaween

4.14. Often, in chemical processing plants, there will be more than one type of instrumentation measuring the same variable at the same instance during the process. Owing to the nature of measurements, they are almost never exact, and hence can be represented as a fuzzy set. Owing to the differences in instrumentation, the measurements will usually not be the same. Take, for example, two types of temperature sensors, namely, a thermocouple (TC) and a resistance temperature detector (RTD) measuring the same stream temperature. The membership function of the two types of temperature sensors may look as in Figure P4.14.

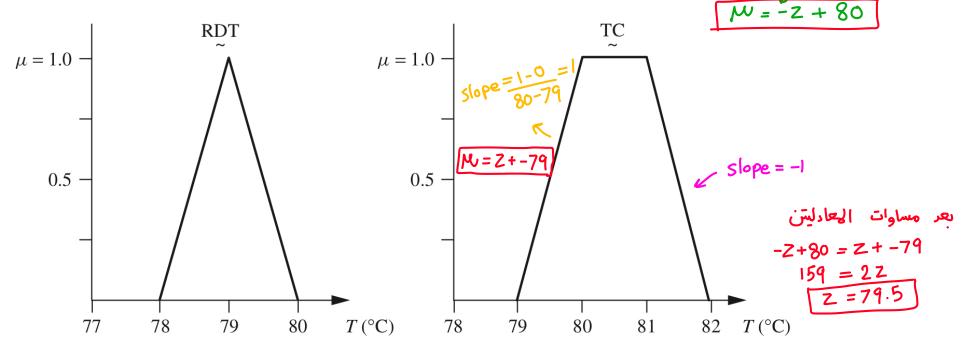


FIGURE P4.14

Max Membership Method
$$\longrightarrow$$
 lossil and polytype 93
not polytype 93
Not convex Area
Not convex Area
(z) Not conv

Last Maximum -> 81

Chapter 5 Logic and Fuzzy Systems

Dr. Wafa' H. AlAlaween wafa.alalaween@gmail.com

Logic: Definition

- Logic is a small part of the human capacity to reason.
- Fuzzy logic is a method to formalize the human capacity of imprecise (approximate) reasoning.
- Reasoning represents the human ability to judge under uncertainty.
- Not Yes or No it is something in between Not Yes or No Interpolating between the binary extremes of true and false is represented by the ability of fuzzy logic to encapsulate partial truths.
 - Proposition is associated with the concepts of truth sets, <u>tautologies</u>, and رویده این مورد این



- A proposition (P) is a linguistic (declarative) statement contained within a universe of elements (X) that can be identified as being a collection of elements in X, which are strictly true or strictly false.
- The veracity of an element in the proposition P can be assigned a binary (Boolean) truth value, T (P).
- Assume that U is the universe of all propositions, then one can consider T is a mapping of the elements (u):

$$T: u \in \mathbf{U} \longrightarrow (0, 1)$$

$$U = \xi \text{ black, blue, red, white, green 3}$$

$$P \rightarrow \text{red belongs to } U \rightarrow \text{so } \underbrace{T(P)}_{\text{Tork value}} = 1$$

$$\inf_{\text{for the proposition}} T(P) = \xi \text{ i } \text{ if } x \in U$$

$$e \text{ the proposition}$$

$$(B) = \lim_{x \neq 1} \lim_{x \neq 1} e \text{ kements } \text{ black, blue 3}$$

$$\int_{\text{set}} \xi \text{ red, white, green 3}$$

Truth set for the Universe is the universe
$$(U)$$

and the falsity set = φ

- Truth set, T(P): all elements u in U that are true for proposition P.
- Falsity set: all elements u in U that are false for proposition P.
- So what are:

$$T(U) = ? = I$$

 $T(\emptyset) = ? = 0$

م المحم هيك عشان بسوو ربط Crisp Logic: Connectives

• Assume that P and Q are two propositions on the same universe of discourse, such propositions can be combined using the following connectives:

$$Max$$
 Max Max Min Min

• Equivalence comes from dual implication.

- Let us define sets A and B on a universe X, and propositions P and Q measure the truth of the statement that an element is contained in sets A and B, respectively, or more conventionally:
 - P: truth that $x \in A$ if $x \in A$, T(P) = 1; otherwise, T(P) = 0Q: truth that $x \in B$ if $x \in B$, T(Q) = 1; otherwise, T(Q) = 0

• Using a characteristic function:
$$\chi_A(x) = \begin{cases} 1, & x \in A \\ 0, & x \notin A \end{cases}$$

Continue	•
T-Norm <i>Lisjunction اتح</i> اد (or)	$P \lor Q : x \in A \text{ or } x \in B;$ hence, $T(P \lor Q) = \max(T(P), T(Q)).$
T-conorme Conjunction تقاطع (AND)	P \land Q : $x \in A$ and $x \in B$; hence, $T(P \land Q) = \min(T(P), T(Q)).$
Negation	

If $T(\mathbf{P}) = 1$, then $T(\overline{\mathbf{P}}) = 0$; if $T(\mathbf{P}) = 0$, then $T(\overline{\mathbf{P}}) = 1$.

Continue...
Implication applicable between two propositions
$$\stackrel{\text{Mar}}{\longrightarrow} \stackrel{\text{P}}{\bigcirc}$$

Implication applicable between two propositions $\stackrel{\text{Mar}}{\longrightarrow} \stackrel{\text{P}}{\bigcirc}$
 $(P \rightarrow Q) : x \notin A \text{ or } x \in B;$
hence, $T(P \rightarrow Q) = T(\overline{P} \cup Q)$.
Equivalence
 $\stackrel{\text{Requivalence}}{\longrightarrow} (P \leftrightarrow Q) : T(P \leftrightarrow Q) = \begin{cases} 1, \text{ for } T(P) = T \\ 0, \text{ for } T(P) \neq T \end{cases}$

• If $T(P) \cap T(Q) = \emptyset$ and the truth of P always implies the falsity of Q and vice versa, then P and Q are mutually exclusive propositions.

• Truth table for various compound propositions:

P Q \overline{P} $P \bigvee_{ord}^{(Max)} Q$ $P \xrightarrow{(Max)} Q$ $P \rightarrow Q$ $P \leftrightarrow Q$ T (1) T (1) F (0) T (1) T (1) T (1) T (1) T (1) F (0) F (0) T (1) T (1) T (1) T (1) T (1) F (0) F (0) T (1) F (0) F (0) F (0) F (0) T (1) T (1) T (1) F (0) F (0) F (0) F (0) T (1) T (1) T (1) F (0) F (0) F (0) F (0) T (1) T (1) T (1) F (0) T (1) F (0) F (0) T (1) T (1) T (1) T (1) F (0) T (1) F (0)	ادا متساويير الجواب ا مر Q V P		1				
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\leftrightarrow \mathbf{Q} \qquad \qquad \mathbf{Q} \rightarrow \mathbf{P}$	$-P \rightarrow Q$	$\mathbf{P} \wedge \mathbf{Q}$		P	Q	Р
F(0) $T(1)$ $T(1)$ $F(0)$ $T(1)$ $F(0)$	(1)	T (1)	T (1)	T (1)	F (0)	T (1)	T (1)
	(0)	F (0)	F (0)	T (1)	F (0)	F (0)	T (1)
$\mathbf{E}(0) = \mathbf{E}(0) = \mathbf{E}(0) = \mathbf{E}(0) = \mathbf{E}(0) = \mathbf{E}(0)$	(0) 0	T (1)	F (0)	T (1)	T (1)	T (1)	F (0)
F(0) $F(0)$ $T(1)$ $F(0)$ $F(0)$ $T(1)$	(1)	T (1)	F (0)	F (0)	T (1)	F (0)	F (0)

Truth Table for 3 propositions

p	q	r	$p \lor q$	$p \lor r$	$q \wedge r$	$(p \vee q) \wedge (p \vee r)$	$p \vee (q \wedge r)$	$P \rightarrow Q$	$Q \to R$	$(P \to Q) \land (Q \to R)$
Т	Т	Т	Т	Т	Т	Т	Т	Т	Т	Т
Т	F	Т	Т	Т	F	Т	Т	Т	F	F
Т	Т	F	Т	Т	F	Т	Т	F	Т	F
Т	F	F	Т	Т	F	Т	Т	F	Т	F
F	Т	Т	Т	Т	Т	Т	Т	Т	Т	Т
F	F	Т	F	Т	F	F	F	т	F	F
F	Т	F	Т	F	F	F	F	Т	Т	Т
F	F	F	F	F	F	F	F	Т	Т	Т

Max \bigvee



Min



negation Job اتحاد (max) مع الكاني

اذا متشابهين ولحر اذاغير متشابهين جفر

False/True في ال crisp الما بالد Fuzzy بيفرق 1/0

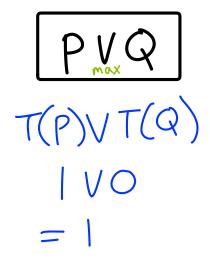
* ما بتفرق بال Troth لو کتبت

في حالة ال Equivelance لاحالتان فقط ((p e Q) e R) 1 131 1 7 1 0 0) 1 0 J 1

*Question &-A= {1, 2, 3, 4, 5, 63 $B = \xi 3, 4, 6, 8, 9, 103$ P->3EA Q->IEB

Find 8-

if



- Tautologies are compound propositions that are <u>always true</u> irrespective of the truth values of the individual simple propositions.
 ريغن النظر عن ال Proposition الموجودة بإذا محيطة أو عالما محيطة أو عالما معن النظر عن الرامة المحيطة أو عالما محيطة أو عالما محيطة المحيطة المحيحيحيطة المحيطة المحيطة المحيطة المحيطة المحيطالمحيحيطة المحيطة
- Tautologies are useful for reasoning, proving theorems, and making deductive inferences.

Tautology التي غلط وج ذلا Monkey التي من "All humans are mammals"

"Prime numbers are not divisible by 6"

• Assignment: Using the truth table, represent a tautology.

autology

A valid argument is a list أشياء تؤبي	of prem	ises fro	m which th	ne conclusion follows.
الى اشي Modus ponens: is a very	common	schem	ne used in fo	orward-chaining rule-
based expert systems. It i	s an ope	ration t	o find the tr	ruth value of a
consequent given the trut	h value o	of the a	ntecedent in	n a rule. if A then B
Form: If A, then B.				Antecedent leads 1 to Consequent
A.	Α	В	$A \rightarrow B$	$(\mathbf{A} \land (\mathbf{A} \rightarrow \mathbf{B}))$
	0	0	1	0 Modus Ponens
Therefore, B.	0 0	0 1	1	0 0 0 1 is an (Forward chaining)
	0 0 1	0 1 0	1 1 0	

<u>مال</u>ہ"۔ اذا زدنا سرعة القطع و زدنا ال depth الے Surface بتصير سيئة Roughness

• Modus Tollens: is a very common scheme used in backward-chaining expert systems. if B didn't happen so A didn't happen

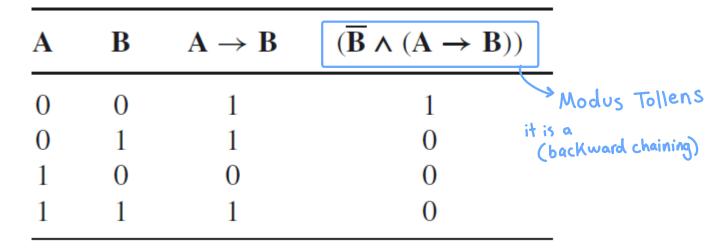
Form:

If A, then B.

~B.

Therefore, ~A.

 $(\overline{\mathbf{B}} \land (\mathbf{A} \longrightarrow \mathbf{B}))$



ال B ما مارت معناته ال A ما مارت

Modus ponens

Forward Chaining if (A) then (B)

 $(A \land (A \rightarrow B))$ $= (A \land (A \land B))$

Modus Tollens

Backward Chaining if (B) didn't happen so (A) didn't happen

 $(\overline{B} \wedge (A \longrightarrow B))$ $= (\overline{B} \wedge (\overline{A} \vee B))$

Crisp Logic: Contradictions and Equivalence

• Contradictions are compound propositions that are always false. regardless of the truth value of the individual propositions constituting the compound proposition.

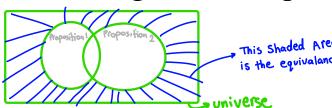
this statement is always incorrect Proposition النظر عن صحة إل "Proposition 1 proposition 2 "Prime numbers are a multiple of 4" Always False

0

13

 \bigcirc

- Propositions P and Q are equivalent $(P \leftrightarrow Q)$ when both P and Q are true or when both P and Q are false. $P = Q + \tau$
- اذا حرم عندابون مع معلمة • Assignment: Using the truth table, represent a contradiction.
- Assignment: plot the Venn diagram for equivalence.



$$Example Suppose we consider the universe of positive integersand No membership degreesgiven so it's crisp
$$X = \{1 \le n \le 8\}. \text{ Let}$$

$$P = "n \text{ is an even number" and let $Q = "(3 \le n \le 7) \land (n \ne 6)." \text{ Then } \frac{T(P)}{T(P)} = \{2, 4, 6, 8\}$
and $T(Q) = \{3, 4, 5, 7\}.$ The equivalence $P \leftrightarrow Q$ has the truth set
$$T(P \leftrightarrow Q) = (T(P) \cap T(Q)) \cup (\overline{T(P)} \cap \overline{T(Q)}) = \{4\} \cup \{1\} = \{1, 4\}$$

$$X = \{1, 2, 3, 4, 5, 6, 7, 8\}$$

$$P = \{2, 2, 4, 6, 7, 8\},$$

$$P = \{2, 3, 4, 5, 7, 7, 7\},$$

$$P = \{2, 3, 4, 5, 7, 7, 7\},$$

$$P = \{2, 4, 6, 7, 8\},$$

$$P = \{2, 3, 4, 5, 7, 7, 7\},$$

$$P = \{2, 4, 6, 7, 8\},$$

$$P = \{2, 3, 4, 5, 7, 7, 7\},$$

$$P = \{2, 3, 4, 5, 7, 7, 7\},$$

$$P = \{2, 3, 4, 5, 7, 7, 7\},$$

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$$P = \{3, 4, 5, 7, 8\},$$

$$P = \{3, 4, 5, 7, 8\},$$

$$P = \{2, 3, 4, 5, 7, 7, 7\},$$

$$P = \{3, 4, 5, 7, 8\},$$

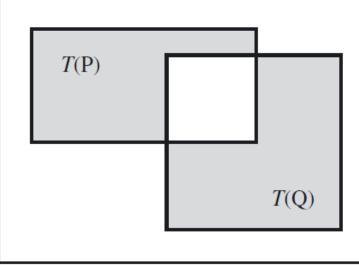
$$P = \{3, 4, 5, 7, 7, 8\},$$$$$$

Crisp Logic: Exclusive or (XC



محوحدة منهع فقط لازم تصير

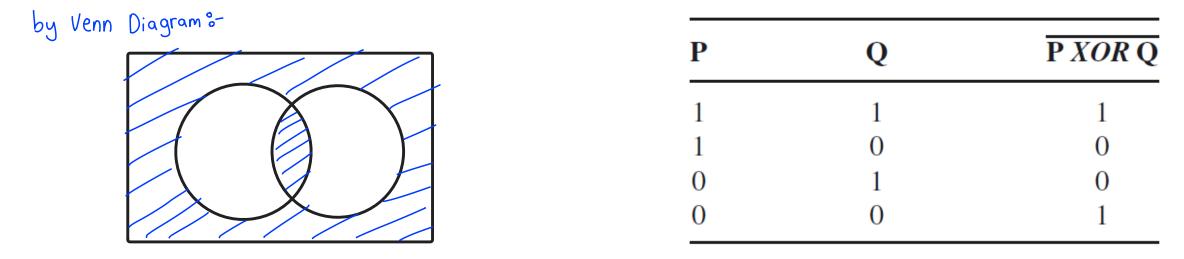
- Exclusive or (XOR): it arises in many situations involving natural language and human reasoning.
- This situation involves the exclusive or; it does not involve the intersection.
- Assignment: Using the truth table and Venn diagram, represent the equivelance "Exclusive or \Box



		$\rightarrow (PVQ) \land (PAQ)$
Р	Q	P XOR Q
1	1	0
1	0	1
0	1	1
0	0	0

Crisp Logic: Exclusive nor

- Assignment: Using the truth table and Venn diagram, represent the "Exclusive nor":



Logical Proofs

- Inference: the process of making certain conclusions from some given hypotheses.
 How?
 - 1. The linguistic statement (compound proposition) is made.
 - 2. The statement is decomposed into its respective single propositions.
 - 3. The statement is expressed algebraically with logical connectives.
 - 4. A truth table is used to establish the veracity of the statement.

Deductive inferences

The *modus ponens* deduction is used as a tool for making inferences in rule-based systems. A typical if-then rule is used to determine whether an antecedent (cause or action) infers a consequent (effect or reaction). Suppose we have a rule of the form IF A, THEN B, where A is a set defined on universe X and B is a set defined on universe Y. As discussed before, this rule can be translated into a relation between sets A and B; that is, recalling Equation (5.4), $R = (A \times B) \cup (\overline{A} \times Y)$. Now suppose a new antecedent, say A', is known. Can we use *modus ponens* deduction, Equation (5.7), to infer a new consequent, say B', resulting from the new antecedent? That is, can we deduce, in rule form, IF A', THEN B'? The answer, of course, is yes, through the use of the composition operation (defined initially in Chapter 3). Since "A implies B" is defined on the Cartesian space X × Y, B' can be found through the following set-theoretic formulation, again from Equation (5.4):

$$B' = A' \circ R = A' \circ ((A \times B) \cup (\overline{A} \times Y)),$$

where the symbol $^{\circ}$ denotes the composition operation. *Modus ponens* deduction can also be used for the compound rule IF A, THEN B, ELSE C, where this compound rule is equivalent to the relation defined in Equation (5.6) as $R = (A \times B) \cup (\overline{A} \times C)$. For this compound rule, if we define another antecedent A', the following possibilities exist, depending on whether (1) A' is fully contained in the original antecedent A, (2) A' is contained only in the complement of A, or (3) A' and A overlap to some extent as described next:

IF
$$A' \subset A$$
, THEN $y = B$
IF $A' \subset \overline{A}$, THEN $y = C$
IF $A' \cap A \neq \emptyset$, $A' \cap \overline{A} \neq \emptyset$, THEN $y = B \cup C$

The rule IF A, THEN B (proposition P is defined on set A in universe X, and proposition Q is defined on set B in universe Y), that is, $(P \rightarrow Q) = R = (A \times B) \cup (\overline{A} \times Y)$, is then defined in function-theoretic terms as

$$\chi_{\rm R}(x, y) = \max[(\chi_{\rm A}(x) \land \chi_{\rm B}(y)), ((1 - \chi_{\rm A}(x)) \land 1)],$$
(5.9)

where χ () is the characteristic function as defined before.

Example 5.7. Suppose we have two universes of discourse for a heat exchanger problem described by the following collection of elements: $X = \{1, 2, 3, 4\}$ and $Y = \{1, 2, 3, 4, 5, 6\}$. Suppose X is a universe of normalized temperatures and Y is a universe of normalized

pressures. Define crisp set A on universe X and crisp set B on universe Y as follows: A = {2, 3} and B = {3, 4}. The deductive inference IF A, THEN B (i.e., IF temperature is A, THEN pressure is B) will yield a matrix describing the membership values of the relation R, that is, $\chi_R(x, y)$, through the use of Equation (5.9). That is, the matrix R represents the rule IF A, THEN B as a matrix of characteristic (crisp membership) values.

Crisp sets A and B can be written using Zadeh's notation,

$$A = \left\{ \frac{0}{1} + \frac{1}{2} + \frac{1}{3} + \frac{0}{4} \right\}.$$
$$B = \left\{ \frac{0}{1} + \frac{0}{2} + \frac{1}{3} + \frac{1}{4} + \frac{0}{5} + \frac{0}{6} \right\}.$$

If we treat set A as a column vector and set B as a row vector, the following matrix results from the Cartesian product of $A \times B$, using Equation (3.16):

$$\mathbf{A} \times \mathbf{B} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The Cartesian product $\overline{A} \times Y$ can be determined using Equation (3.16) by arranging \overline{A} as a column vector and the universe Y as a row vector (sets \overline{A} and Y can be written using Zadeh's notation):

Then, the full relation R describing the implication IF A, THEN B is the maximum of the two matrices $A \times B$ and $\overline{A} \times Y$, or, using Equation (5.9),

$$R = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ 1 & 1 & 1 & 1 & 1 & 1 \\ 2 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

The compound rule IF A, THEN B, ELSE C can also be defined in terms of a matrix relation as $R = (A \times B) \cup (\overline{A} \times C) \Rightarrow (P \rightarrow Q) \land (\overline{P} \rightarrow S)$, as given by Equations (5.5) and (5.6), where the membership function is determined as

$$\chi_{\rm R}(x, y) = \max[(\chi_{\rm A}(x) \land \chi_{\rm B}(y)), ((1 - \chi_{\rm A}(x)) \land \chi_{\rm C}(y))].$$
(5.10)

Example 5.8. Continuing with the previous heat exchanger example, suppose we define a crisp set C on the universe of normalized temperatures Y as $C = \{5, 6\}$, or, using Zadeh's notation,

$$\mathbf{C} = \left\{ \frac{0}{1} + \frac{0}{2} + \frac{0}{3} + \frac{0}{4} + \frac{1}{5} + \frac{1}{6} \right\},\$$

The deductive inference IF A, THEN B, ELSE C (i.e., IF pressure is A, THEN temperature is B, ELSE temperature is C) will yield a relational matrix R, with characteristic values $\chi_R(x, y)$ obtained using Equation (5.10). The first half of the expression in Equation (5.10)

(i.e., $A \times B$) has already been determined in the previous example. The Cartesian product $\overline{A} \times C$ can be determined using Equation (3.16) by arranging the set \overline{A} as a column vector and the set C as a row vector (see set \overline{A} in Example 5.7), or

Then, the full relation R describing the implication IF A, THEN B, ELSE C is the maximum of the two matrices $A \times B$ and $\overline{A} \times C$ (Equation (5.10)):

$$R = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ 1 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

Logical Proofs: Example

sis a compound of propositions

- Hypotheses: Engineers are mathematicians. Logical thinkers do not believe in magic. Mathematicians are logical thinkers. $\sqrt{5}$
- Conclusion: Engineers do not believe in magic.
- Decomposing the hypotheses:
 - P : a person is an engineer.
 - Q : a person is a mathematician.
 - R : a person is a logical thinker.
 - S : a person believes in magic.

$$((P \longrightarrow Q) \wedge (R \longrightarrow \overline{S}) \wedge (Q \longrightarrow R)) \longrightarrow (P \longrightarrow \overline{S})$$



- A fuzzy logic proposition (P) is a statement involving some concept without clearly defined boundaries.
- The truth value assigned to P can be any value on the interval [0, 1].
- Fuzzy propositions are assigned to fuzzy sets. Suppose proposition \underline{P} is assigned to fuzzy set \underline{A} , then, the truth value of a proposition is given as follows:

$$T(\underset{\widetilde{\mathcal{Y}}}{\mathbb{P}}) = \mu_{\underset{\widetilde{\mathcal{X}}}{\mathbb{P}}}(x), \text{ where } 0 \le \mu_{\underset{\widetilde{\mathcal{X}}}{\mathbb{P}}} \le 1$$

indicate that its Fuzzy





• The logical connectives:

 $T(\overline{\underline{\mathbf{P}}}) = 1 - T(\underline{\underline{\mathbf{P}}}).$

Disjunction

Negation

$$\mathbb{P} \lor \mathbb{Q} : x \text{ is } \mathbb{A} \text{ or } \mathbb{B}$$
 $T(\mathbb{P} \lor \mathbb{Q}) = \max(T(\mathbb{P}), T(\mathbb{Q}))$

Conjunction

$$\underline{\mathbb{P}} \wedge \underline{\mathbb{Q}} : x \text{ is } \underline{\mathbb{A}} \text{ and } \underline{\mathbb{B}} \quad T(\underline{\mathbb{P}} \wedge \underline{\mathbb{Q}}) = \underline{\min}(T(\underline{\mathbb{P}}), T(\underline{\mathbb{Q}}))$$

Implication

$$\underbrace{P}_{\infty} \to \underbrace{Q}_{\infty} : x \text{ is } \underbrace{A}_{\infty}, \text{ then } x \text{ is } \underbrace{B}_{\infty}$$
$$T(\underbrace{P}_{\infty} \to \underbrace{Q}_{\infty}) = T(\underbrace{\overline{P}}_{\infty} \lor \underbrace{Q}_{\infty}) = \max(T(\underbrace{\overline{P}}_{\infty}), T(\underbrace{Q}))$$

• As in the crisp logic, the implication can be modelled in rule-based form:

$$\underbrace{\mathbb{P}}_{\mathbb{N}} \to \underbrace{\mathbb{Q}}_{\mathbb{N}} \text{ is IF } x \text{ is } \underbrace{\mathbb{A}}_{\mathbb{N}}, \text{ THEN } y \text{ is } \underbrace{\mathbb{R}}_{\mathbb{N}}$$

• Note: it is equivalent to
$$\underbrace{\mathbb{R}}_{\mathbb{R}} = (\underbrace{\mathbb{A}}_{\mathbb{N}} \times \underbrace{\mathbb{R}}_{\mathbb{N}}) \cup (\underbrace{\mathbb{A}}_{\mathbb{N}} \times \underbrace{\mathbb{N}}_{\mathbb{N}})$$

Example

Example Suppose we are evaluating a new invention to determine its commercial potential. We will use two metrics to make our decisions regarding the innovation of the idea. Our metrics are the "uniqueness" of the invention, denoted by a universe of novelty scales, $X = \{1, 2, 3, 4\}$, and the "market size" of the invention's commercial market, denoted on a universe of scaled market sizes, $Y = \{1, 2, 3, 4, 5, 6\}$. In both universes, the lowest numbers are the "highest uniqueness" and the "largest market," respectively. A new invention in your group, say a compressible liquid of very useful temperature and viscosity conditions, has just received scores of "medium uniqueness," denoted by fuzzy set A, and "medium market size," denoted fuzzy set B. We wish to determine the implication of such a result, that is, IF A, THEN B. We assign the invention the following fuzzy sets to represent its ratings:

$Y = \{ \frac{1}{2}, \frac{1}{2}, \frac{1}{3}, \frac{1}{4}, \frac{1}{5}, \frac{1}{6}, \frac{7}{3} \}$

Continue...

$$\begin{split} & \underset{\sim}{A} = \text{medium uniqueness} = \left\{ \frac{0.6}{2} + \frac{1}{3} + \frac{0.2}{4} \right\}. \\ & \underset{\sim}{B} = \text{medium market size} = \left\{ \frac{0.4}{2} + \frac{1}{3} + \frac{0.8}{4} + \frac{0.3}{5} \right\}. \\ & \underset{\sim}{C} = \text{diffuse market size} = \left\{ \frac{0.3}{1} + \frac{0.5}{2} + \frac{0.6}{3} + \frac{0.6}{4} + \frac{0.5}{5} + \frac{0.3}{6} \right\}. \end{split}$$

if A then B is represented by Find $\mathbf{R} = (\mathbf{A} \times \mathbf{B}) \cup (\mathbf{\overline{A}} \times \mathbf{Y})$



- When the logical conditional implication is of the compound form: $(\underline{A} \times \underline{B}) \cup (\overline{A} \times \underline{Q})$ IF x is \underline{A} , THEN y is \underline{B} , ELSE y is \underline{C} ,
- Then, the fuzzy relation can be presented as

 $\underline{\mathbf{R}} = (\underline{\mathbf{A}} \times \underline{\mathbf{B}}) \cup (\overline{\underline{\mathbf{A}}} \times \underline{\mathbf{C}}).$

$$A = \begin{bmatrix} 0 & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

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$$A = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

$$B = \begin{bmatrix} 0 & \frac{1}{2} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

$$F = \begin{bmatrix} A \times B \\ 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

$$A \times B = \begin{bmatrix} 1 & \frac{2}{3} & \frac{3}{4} & \frac{5}{6} & \frac{6}{3} & \frac{1}{3} & \frac{2}{3} & \frac{3}{4} & \frac{5}{6} & \frac{6}{3} & \frac{1}{3} & \frac{2}{3} & \frac{3}{4} & \frac{5}{6} & \frac{6}{3} & \frac{1}{3} & \frac{2}{3} & \frac{3}{4} & \frac{5}{6} & \frac{6}{3} & \frac{1}{3} & \frac{2}{3} & \frac{3}{4} & \frac{5}{6} & \frac{6}{3} & \frac{6}{3} & \frac{1}{3} & \frac{2}{3} & \frac{1}{3} & \frac{2}{3} & \frac{3}{4} & \frac{5}{6} & \frac{6}{3} & \frac{1}{3} & \frac{2}{3} & \frac{$$

R =

Approximate Reasoning

- Approximate reasoning is about imprecise propositions.
- It deals with partial truth.
- Question: suppose we have a rule expressed as follows:

IF x is
$$\underline{A}$$
, THEN y is $\underline{B} \longrightarrow (A \times B) \cup (\overline{A} \times U)$ if x is A
they y is B

If we introduce a new antecedent, is it possible to derive the consequent?

IF x is \underline{A}' , THEN y is \underline{B}'

• By using the composition operation $(\underline{B}' = \underline{A}' \circ \underline{R})$, the answer is YES.

• For the previous example, what market size would be associated with a uniqueness score of "almost high uniqueness"

$$A' = \text{almost high uniqueness} = \left\{ \frac{0.5}{1} + \frac{1}{2} + \frac{0.3}{3} + \frac{0}{4} \right\}$$

how can I find the market Size?
By using the max-min composition:

$$\mathbf{B}' = \mathbf{A}' \circ \mathbf{R} = \left\{ \frac{0.5}{1} + \frac{0.5}{2} + \frac{0.6}{3} + \frac{0.6}{4} + \frac{0.5}{5} + \frac{0.5}{6} \right\}$$

$$A = \xi \frac{0.5}{1}, \frac{1}{2}, \frac{0.3}{3}, \frac{0.7}{4}$$

$$R = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ .4 & .4 & .6 & .6 & .4 & .4 \\ 0 & .4 & 1 & .8 & .3 & 0 \\ 0 & .4 & 1 & .8 & .8 & .8 \end{bmatrix}$$

Solution

$$\dot{B} = \dot{A} \circ R = \left\{ \frac{0.5}{1}, \frac{0.5}{2}, \frac{0.6}{3}, \frac{0.6}{4}, \frac{0.5}{5}, \frac{0.5}{6} \right\}$$

market size for almost high uniqueness

Fuzzy Implication Operations

- There are other techniques one can use to obtaining the fuzzy relation (\mathbb{R}) based on a fuzzy rule.
- The membership function values of \mathbb{R} can be presented as follows:

$$\mu_{\mathbb{R}}(x, y) = \max[\mu_{\mathbb{R}}(y), 1 - \mu_{\mathbb{R}}(x)]$$

$$(\lim_{x \to y} \mu_{\mathbb{R}}(x, y) = \min[\mu_{\mathbb{R}}(x), \mu_{\mathbb{R}}(y)]$$

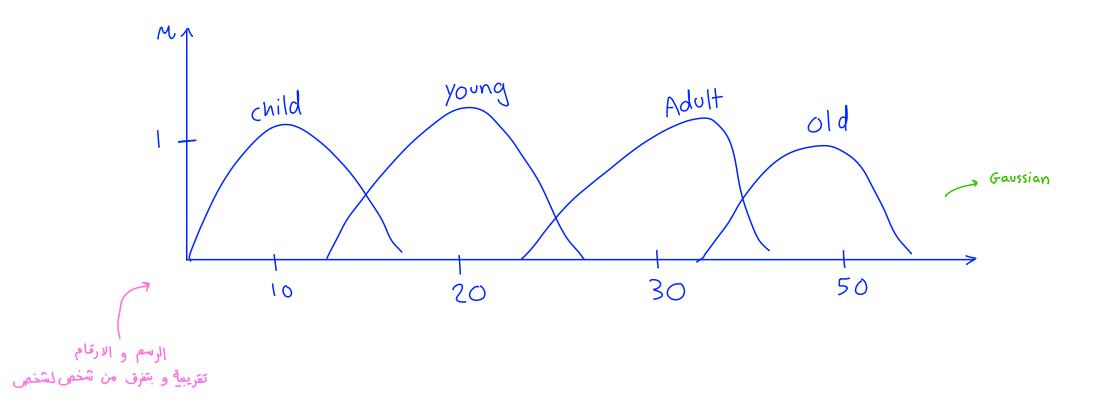
$$\mu_{\mathbb{R}}(x, y) = \min\{1, [1 - \mu_{\mathbb{R}}(x) + \mu_{\mathbb{R}}(y)]\}$$

$$\frac{\text{Example :-}}{A_{c}} = \underbrace{\mathcal{E}}_{1}^{O}, \underbrace{\frac{O.6}{2}}_{1}, \frac{1}{3}, \frac{O.2}{4}, \frac{7}{3}, \frac{O.3}{4}, \frac{O.3}{5}, \frac{O}{6}, \frac{7}{3}, \frac{O.4}{2}, \frac{1}{3}, \frac{O.8}{4}, \frac{O.3}{5}, \frac{O}{6}, \frac{7}{3}, \frac{O}{6}, \frac{7}{3}, \frac{O}{6}, \frac{7}{3}, \frac{O}{6}, \frac{1}{3}, \frac{O}{6}, \frac{O}{6},$$

- Natural language: it vague and ambiguous, however, one can understand it.
- Example: "young" is a term that can be linguistically interpreted in terms of age.

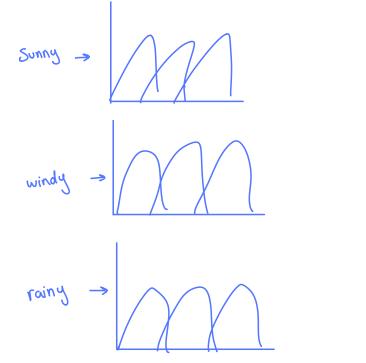
$$\mu_{\underline{M}}(\text{young, } y) = \begin{cases} \left[1 + \left(\frac{y-25}{5}\right)^2 \right]^{-1}, & y > 25 \text{ years}; \\ 1, & y \le 25 \text{ years}; \\ y \le 25 \text{ years}. \end{cases}$$

* Describe the age of people linguisticly then represent it in a membership Function?



Question 1: Various fuzzy sets for the weather in Jordan can be defined, such as rainy, sunny, windy, etc. Discus and draw membership functions to describe the weather in Jordan, and discuss whether fizzy logic is the best technique to describe it. (Hint: define different universes)

سے اعرف universes windy rainy SUNNY





- A composite is a collection (set) of terms combined by various linguistic connectives such as and, or, and not.
- For the two terms α and β , the interpretation of the composite can be defined by using theoretic operations as follows:

$$\bigcup \alpha \text{ or } \beta: \mu_{\alpha} \text{ or } \beta(y) = \max(\mu_{\alpha}(y), \mu_{\beta}(y)),$$

$$\cap \alpha \text{ and } \beta: \mu_{\alpha} \text{ and } \beta(y) = \min(\mu_{\alpha}(y), \mu_{\beta}(y)),$$

$$Not \alpha = \overline{\alpha}: \mu_{\overline{\alpha}}(y) = 1 - \mu_{\alpha}(y).$$

FS: If-Then Rule-Based System

Knowledge is usually represented using If-Then rule-based form.

IF premise (antecedent), THEN conclusion (consequent)

- The fuzzy rule-based system is useful in modelling complex systems that can be observed by humans, thus linguistic variables can be used to describe the antecedents and consequents.
- The linguistic variables can be naturally represented by fuzzy sets and logical connectives of these sets.

FS: Multiple Conjunctive Antecedents

• Suppose that the rule is as follows:

IF x is A^1 and A^2 ... and A^L THEN y is B^s

• A new fuzzy set can be defined as follows:

 $\underline{A}^{s} = \underline{A}^{1} \cap \underline{A}^{2} \cap \dots \cap \underline{A}^{L} \qquad \mu_{\underline{A}^{s}}(x) = \min[\mu_{\underline{A}^{1}}(x), \mu_{\underline{A}^{2}}(x), \dots, \mu_{\underline{A}^{L}}(x)]$

- بشبکهم به connectives
 - Then the compound rule can be represented as:

IF A^s THEN B^s

FS: Multiple Disjunctive Antecedents - IF I had one Rule (one Fuzzy Rule)

• Suppose that the rule is as follows:

IF x is A^1 OR x is A^2 ...OR x is A^L THEN y is B^s

• A new fuzzy set can be defined as follows:

 $\underline{A}^{s} = \underline{A}^{1} \cup \underline{A}^{2} \cup \dots \cup \underline{A}^{L} \qquad \qquad \mu_{\underline{A}^{s}}(x) = \max \left[\mu_{\underline{A}^{1}}(x), \mu_{\underline{A}^{2}}(x), \dots, \mu_{\underline{A}^{L}}(x)\right]$

• Then the compound rule can be represented as:

IF \underline{A}^s THEN \underline{B}^s

FS: Aggregation of Fuzzy Rules \rightarrow For multiple Rules

- Aggregation: The process of obtaining the overall consequent from the individual consequents contributed by each rule.
- Two aggregation strategies:
 - 1. Conjunctive system of rules -> depends on Minimum operation
 - 2. Disjunctive system of rules ---- depends on Maximum operation

- Conjunctive system of rules
 - $y = y^1$ and y^2 and ... and y^r $y = y^1 \cap y^2 \cap \cdots \cap y^r$

 $\mu_{y}(y) = \min(\mu_{y^{1}}(y), \mu_{y^{2}}(y), \dots, \mu_{y^{r}}(y)), \text{ for } y \in Y$

- Disjunctive system of rules
 - $y = y^1$ or y^2 or ... or y^r $y = y^1 \cup y^2 \cup \cdots \cup y^r$

 $\mu_{y}(y) = \max(\mu_{y^{1}}(y), \mu_{y^{2}}(y), \dots, \mu_{y^{r}}(y)), \text{ for } y \in Y$

Inference: Graphical Techniques

- Have you read "Deductive inference"? Self Reading from the book
- Graphical methods usually make the manual computations of the inference easy and straightforward (with a few rules).
- Three common methods for fuzzy systems based on linguistic rules:
 - 1. Mamdani systems
 - 2. Takagi Sugeno systems
 - 3. Tsukamoto systems

Inference: Mamdani Systems

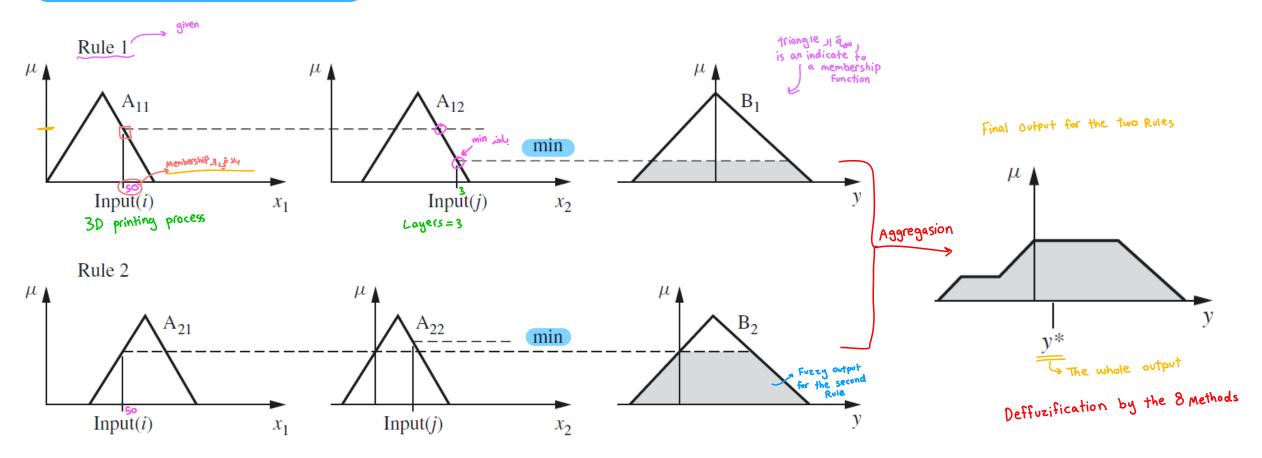
• Let us consider a simple two-rule system where each rule comprises of two antecedents and one consequent, the Mamdani form is given as:

IF x_1 is A_1^k and x_2 is A_2^k THEN y^k is B_2^k , for k = 1, 2, ..., r,

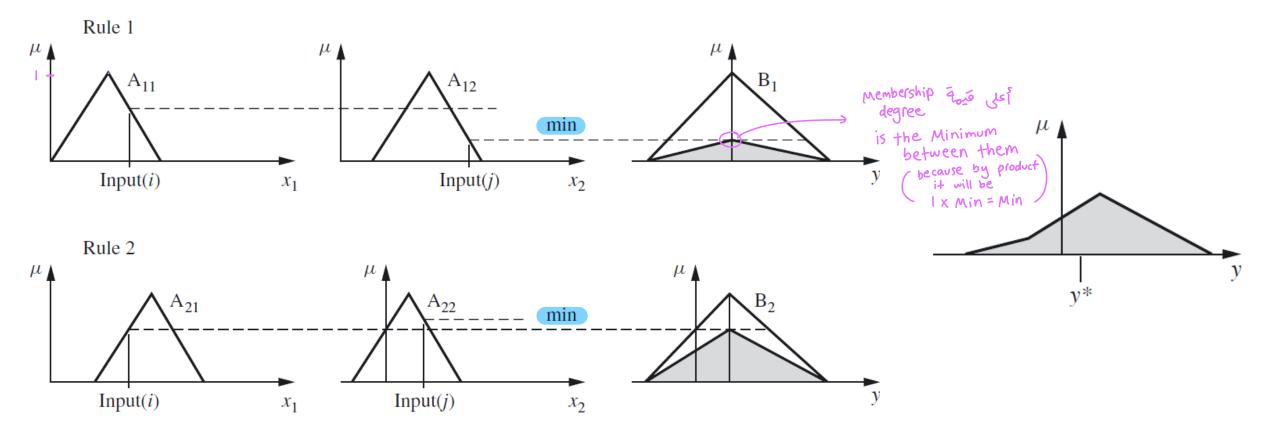
- For the Mamdani system, two cases can be considered:
 - A max–min inference method
 - A max–product inference method

Continue...

A max-min inference method:



A max-product inference method



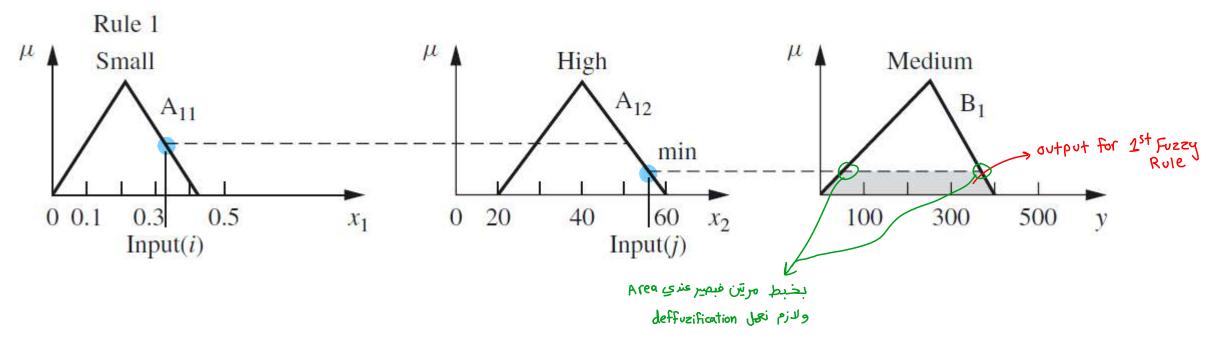
Example

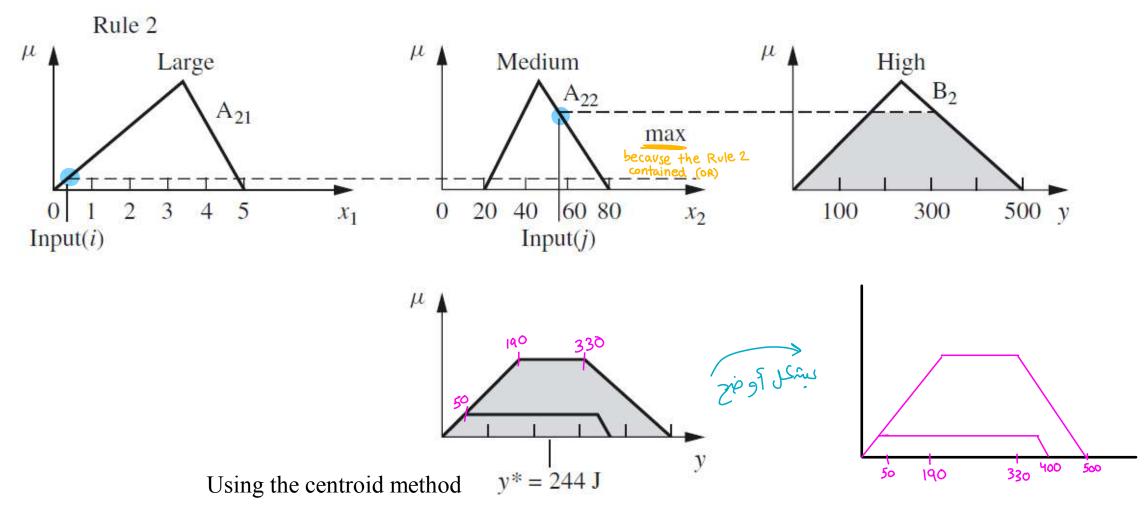
Example In mechanics, the energy of a moving body is called kinetic energy. If an object of mass m (kilograms) is moving with a velocity v (meters per second), then the kinetic energy k (in joules) is given by the equation $k = \frac{1}{2}mv^2$. Suppose we model the mass and velocity as inputs to a system (moving body) and the energy as output, then observe the system for a while and deduce the following two disjunctive rules of inference based on our observations:

Rule 1 : IF x_1 is A_1^1 (small mass) <u>and</u> x_2 is A_2^1 (high velocity), THEN y is B^1 (medium energy). Rule 2 : IF x_1 is A_1^2 (large mass) <u>or</u> x_2 is A_2^2 (high velocity), THEN y is B^2 (high energy).

• Assume that mass=0.35 kg and velocity=55m/s.

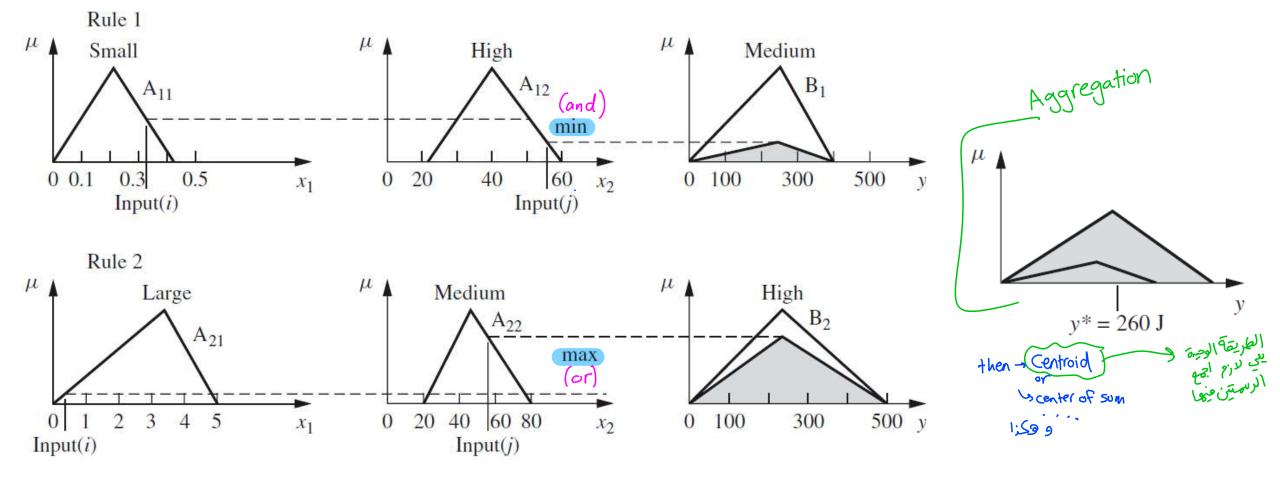
• By using the max-min inference:





• By using the max-min inference:

 $\frac{1}{2} \times .35 \times 55^2 = 529.375$ Toleal الطريقة الثانية بتعطيني اقرب لله المعالم number The Comment ->



5.32. In finding the Nusselt number (a dimensionless number for determining heat transfer) for an hexagonal cylinder in cross flow, there are two correlations (which are to be used as the consequent terms in a Sugeno inference method):

$$Nu_1 = 0.16Re^{0.638}Pr^{1/3} \quad 5000 < Re < 19650,$$

$$Nu_2 = 0.0385Re^{0.728}Pr^{1/3} \quad Re > 19650,$$

Re is the Reynolds number and *Pr* is the Prandtl number. In the equations above, we seek to know whether *Nu* is low (Nu_1) or is *Nu* medium (Nu_2)? The Nusselt number is a function of convective heat transfer (*h*), diameter of the hexagonal cylinder (*D*) over which cooling fluid travels, and the conductivity of the material (*K*):

$$Nu = \frac{hD}{K}.$$

Both Re and Pr can be fuzzy due to uncertainty in the variables in velocity. It would be convenient to find Nu (output) based on Re and Pr (inputs) without having to do all the calculations. More specifically, there is uncertainty in calculating the Reynolds number because velocity is not known exactly:

$$Re = \frac{\rho VD}{\mu},$$

where ρ is the density, V is the velocity, D is the characteristic length (or pipe diameter), and μ is the dynamic viscosity. And there is also uncertainty in the value for the Prandtl number due to its constituents

$$Pr = \frac{v}{\alpha},$$

where ν is the kinematic viscosity and α is the specific gravity.

Calculation of Nu is very involved and the incorporation of a rule-base can be used to bypass these calculations; we have the following rules to govern this process:

Reynold is low in the result of the second second

For this problem, conduct a Mamdani and a Sugeno inference, based on the membership functions given in Figure P5.32(a-c), and use the following inputs:

$$Re = 1.965 \times 10^4.$$

 $Pr = 275.$

Comment on the differences in the results.

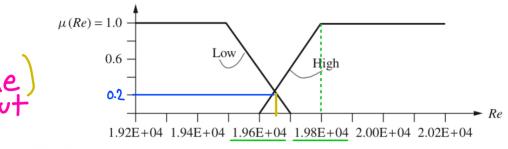


FIGURE P5.32a Input for Reynolds number

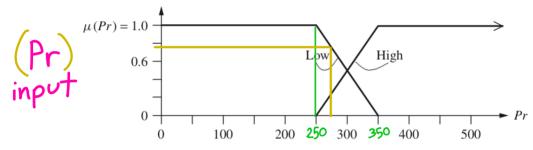


FIGURE P5.32b Input for Prandtl number

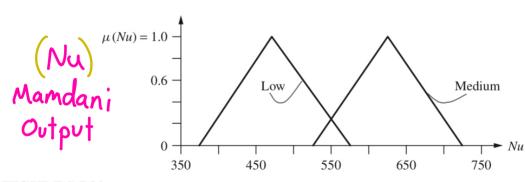


FIGURE P5.32c Output for Mamdani inference

5.32

L

In finding the Nusselt number (a dimensionless number for determining heat transfer) for a hexagonal cylinder in cross flow, there are two correlations.

$$N_{u1} = 0.16 R_e^{0.638} P r^{\frac{1}{3}}$$
 5000 < R_e < 19650

 $N_{u2} = 0.0385 R_e^{0.728} P r^{\frac{1}{5}} R_e < 19650$

 R_e is the Reynolds number and P_r is the Prandtl number.

The Nusselt number is a function of convective heat transfer (h), diameter of the hexagonal cylinder (D) over which cooling fluid travels, and the conductivity of the material (K).

$$N_u = \frac{hD}{K},$$

 R_e 's and P_r 's both can be fuzzy due to uncertainty in the variables in velocity. It would be convenient to find N_u (Output) based on R_e and P_r (inputs) without having to do all the calculations.

Rules:

If R_e is high and P_r is low $\rightarrow N_u$ is low If R_e is low and P_r is low $\rightarrow N_u$ is low If R_e is high and P_r is high $\rightarrow N_u$ is medium If R_e is low and P_r is high $\rightarrow N_u$ is medium

In the Mandami method:

3) $\mu(N_{s})=1.0$ $\frac{1}{0.6}$ $\frac{1}{0.6}$

And from our rule base and the following equations

INPUT and $P_r \rightarrow$ propagate minimum to μ (Nu) and use weighted average defuzzification.

INPUT Re =
$$19.65 \times 10^{3}$$

 μ (Re) = 0.25
Pr = 275 μ (Pr) = 0.25

In the Sugeno method:

Use the correlations N_{u1} and N_{u2} to get Z_1 and Z_2

$$Z = \frac{\mu(N_{u1})z_1 + \mu(N_{u2})z_2}{\mu(N_{u1}) + \mu(N_{u2})}$$

Mandami

Rule1: $N_{uL}min(0.25,0.75)=0.25$ Rule2: $N_{uL}=min(0.25,0.75)=0.25$ Rule 1 and 2 : max is 0.25

Defuzzification for N_{uL} =0.25 yields to z=487.5

Rule3:
$$N_{uH}$$
=min(0.25,0.25)=0.25
Rule4: N_{uH} =min(0.25,0.25)=0.25
Rule 3 and 4 : max is 0.25

Defuzzification for $N_{uH} {=} 0.25$ yields to z=612.5

Weighted average :

$$z = \frac{0.25 * 487.5 + 0.25 * 612.5}{0.5} = 550$$

 $N_{u1} = 0.16R_e^{0.638}Pr^{\frac{1}{5}}$ 5000 < R_e < 19650

 $N_{u2} = 0.0385 R_e^{-0.728} Pr^{\frac{1}{3}} R_e < 19650$

we have the following results:

Nu1 = 560.0993666

Nu2 = 559.5643482

z = 559.8318574

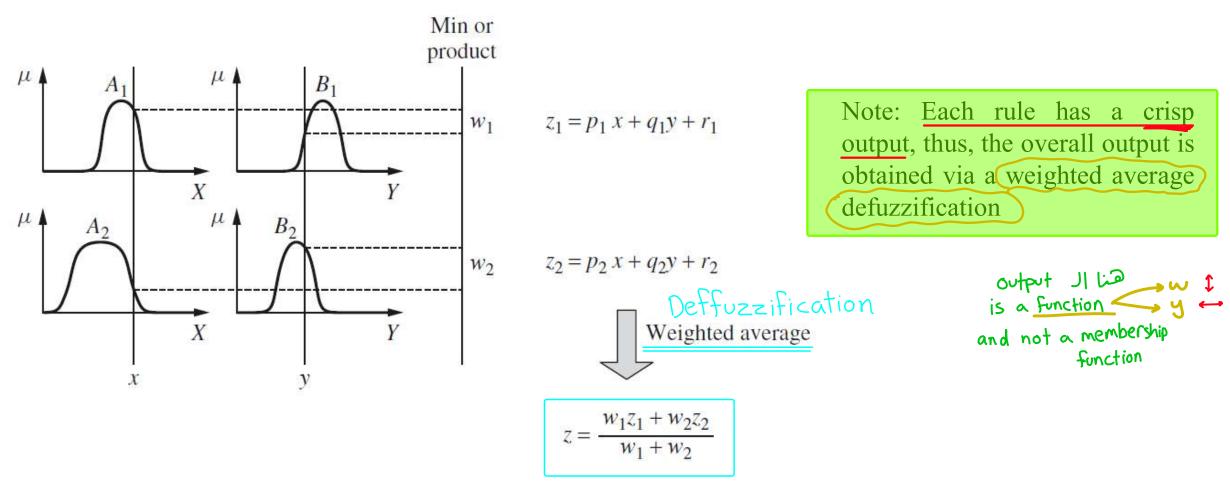
Inference: Takagi Sugeno Systems

• The Takagi Sugeno rule, which has two inputs x and y and output z, is given as:

IF x is A and y is B, THEN z is z = f(x, y)

- The f (x, y) can be any function that describes the output of the system. A polynomial function is common.
- A zero-order system (special case of Mamdani system): f(x, y) is constant.
- A first-order system: f(x, y) is a linear function.

And $\longrightarrow \min$



5.31. From thermodynamics it is known that for an ideal gas in an adiabatic reversible process

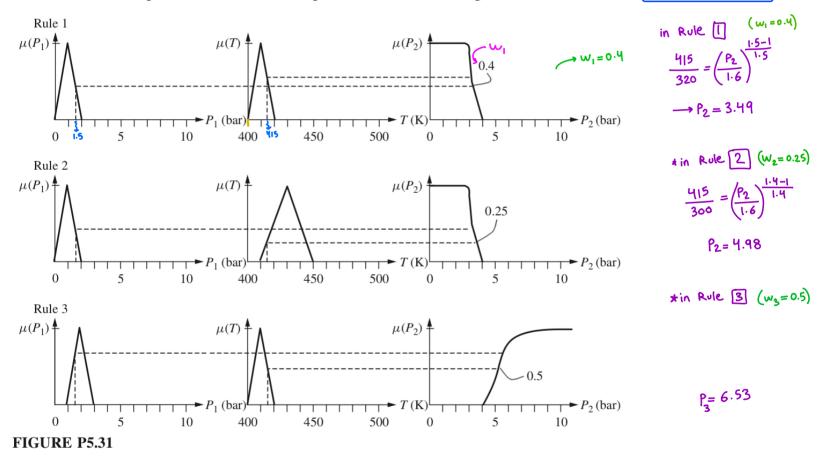
$$\frac{T_2}{T_1} = \left(\frac{P_2}{P_1}\right)^{\frac{\gamma - 1}{\gamma}}$$

By TaKagi Sugeno

where T_1 and T_2 are temperatures in kelvin (K) and P_1 and P_2 are pressures in bars and, for an ideal gas. For the Sugeno solution, use the following functions for the consequents of the three rules:

Rule 1 :
$$T_1 = 320$$
 K and $\gamma = 1.5$
Rule 2 : $T_1 = 300$ K and $\gamma = 1.4$
Rule 3 : $T_1 = 300$ K and $\gamma = 1.3$

For this problem, T_1 will be fixed at 300 K and the fuzzy model will predict P_2 for the given input variables P_1 and T_2 . In other words, we are interested in finding the final pressure, P_2 , of the system if the temperature of the system is changed to T_2 from an original pressure equal to P_1 . A real application could use a similar model built from experimental data to do a prediction on nonideal gases.



The rules used are

 $P_2 = 0.4 \times 3.49 + 0.25 \times 10^{-10}$ Rule 1: IF $P_1 = \text{atmP}$ AND $T_2 = \text{lowT}$ THEN $P_2 = \text{lowP}$. Rule 2: IF $P_1 = \text{atmP}$ AND $T_2 = \text{midT}$ THEN $P_2 = \text{lowP}$. Rule 3: IF $P_1 = \text{lowP}$ AND $T_2 = \text{lowT}$ THEN $P_2 = \text{very highP}$.

Given the rule-base, the membership functions shown in Figure P5.31, and the following pair of input values, $P_1 = 1.6$ bar and $T_2 = 415$ K, conduct a simulation to determine P_2 for the inference methods of Sugeno and Tsukamoto. For the Sugeno consequents use the ideal gas formula, given above. Ussing Taccagi Sogomo

Ł

5.31 For Sugeno method rules are as follows: Rule1: $T_1=320$ K Then $\gamma=1.5$

Rule1: $T_1=320K$ Then $\gamma=1.5$ Rule2: $T_1=300K$ Then $\gamma=1.4$

Rule3: T_1 =300K Then γ =1.3 For problem T_1 is fixed to 300K and the fuzzy model will predict P_2 for the given variable P_1 ad T_2 . In other words... what is the final pressure of the system if the temperature is changed to T_2 from a pressure equal to T_1 ?

Solution 8-

$$\frac{T_2}{T_1} = \left(\frac{P_2}{P_1}\right)^{\frac{\gamma-1}{\gamma}} \text{ or } P_2 = P_1 \left(\frac{T_2}{T_1}\right)^{\frac{\gamma}{\gamma-1}} \text{ and in this problem } T_1 = 300 \text{K}$$

$$\frac{\text{Input: P_1 = 1.6 \text{bar and } T_2 = 415 \text{K}}}{\text{Rule2 and Rule3 are fired since } T_1 = 300 \text{K}}.$$
From rule2: $\gamma = 1.4$ thus $P_2 = 5.0 \text{bar}$

From rule2: $\gamma = 1.4$ thus $P_2 = 5.00 \text{ ar}$ Weighted average: $P_2^* = \frac{0.25*5.0 + 0.5*6.5}{0.25+0.5} = 6.0bar$

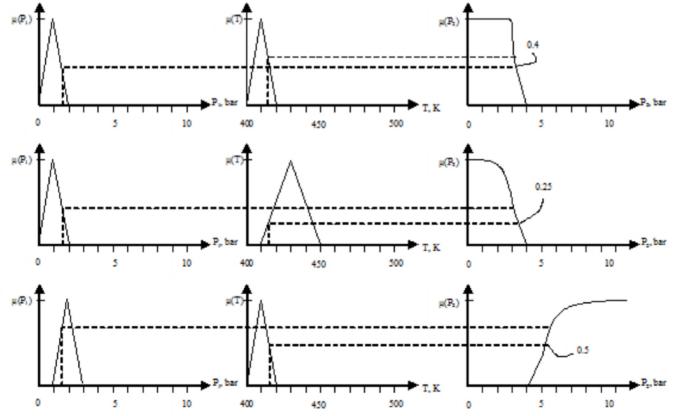
The rules used for Tsukamoto method are:

 $R1 \rightarrow IF P_1 = atmP AND T_2 = lowT THEN P_2 = lowP$

 $R2 \rightarrow IF P_1 = atmP AND T_2 = midT THEN P_2 = midP$

 $R3 \rightarrow IF P_1 = lowP AND T_2 = lowT THEN P_2 = very highP$

The above rules are shown in the below figure:



From the graph of rule2 and rule3 we have (P₂=3.5, $\mu_2=0.25$) and (P₂=5, $\mu_2=0.5$) respectively.

Thus from the weighted average:

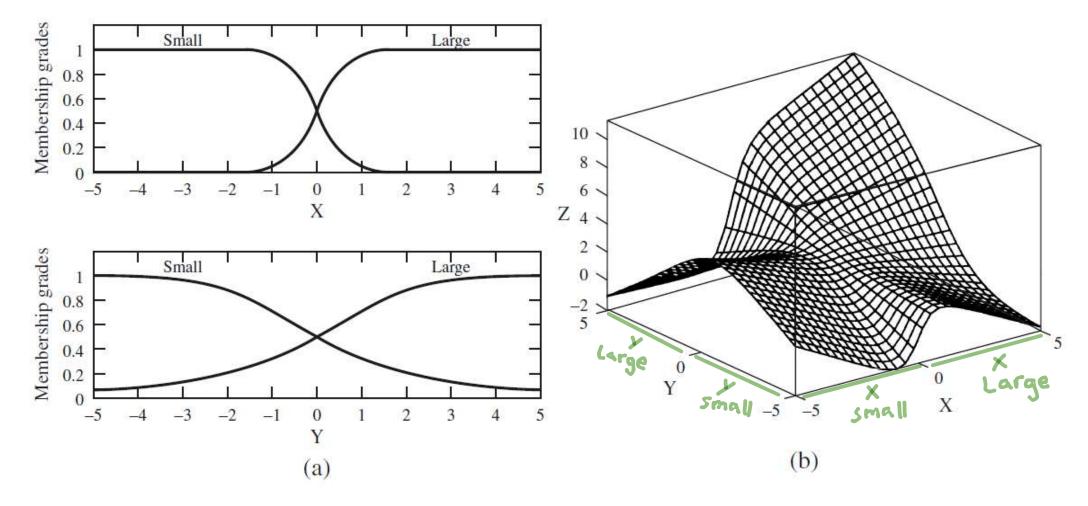
$$P_2^* = \frac{0.25*3.5+0.5*5}{0.25+0.5} = 4.5bar$$

Example in Fuzzy ussually?-Multi input -> single output

• A two-input, single-output Sugeno model with four rules is presented as follows (Jang *et al.*,1997):

IF X is small and Y is small, THEN z = -x + y + 1. IF X is small and Y is large, THEN z = -y + 3. IF X is large and Y is small, THEN z = -x + 3. IF X is large and Y is large, THEN z = x + y + 2.

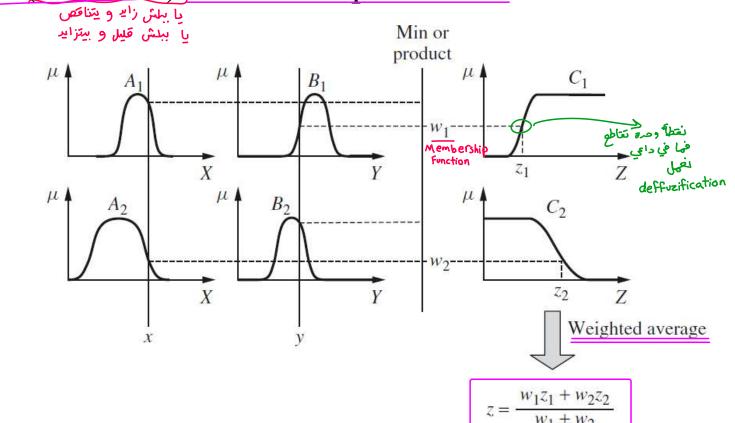
2 iputs <\$x



هنا ما عندي Fuction اعومن فيه

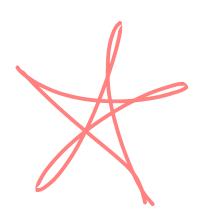
Inference: Tsukamoto Systems

• The consequent of each fuzzy rule is represented by a fuzzy set with a monotonic (shoulder) membership function.

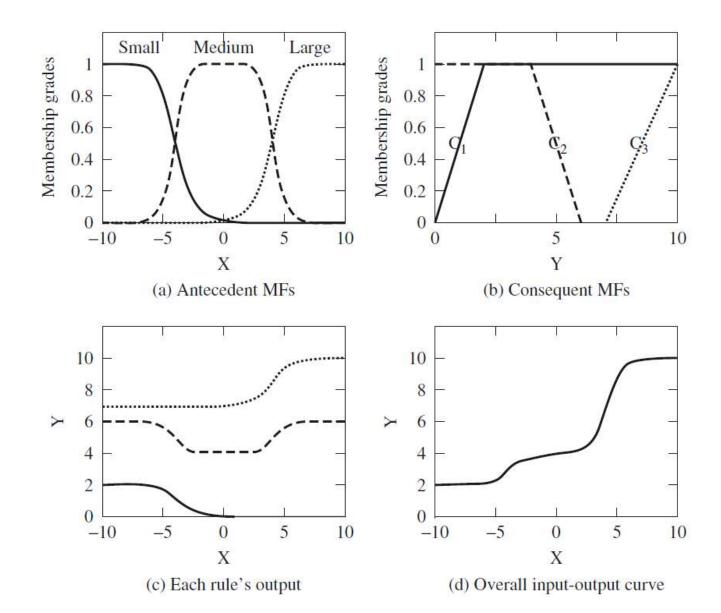


Example

• A single-input, single-output Tsukamoto fuzzy model is given as follows:



IF X is small, THEN Y is C_1 , IF X is medium, THEN Y is C_2 , IF X is large, THEN Y is C_3 ,



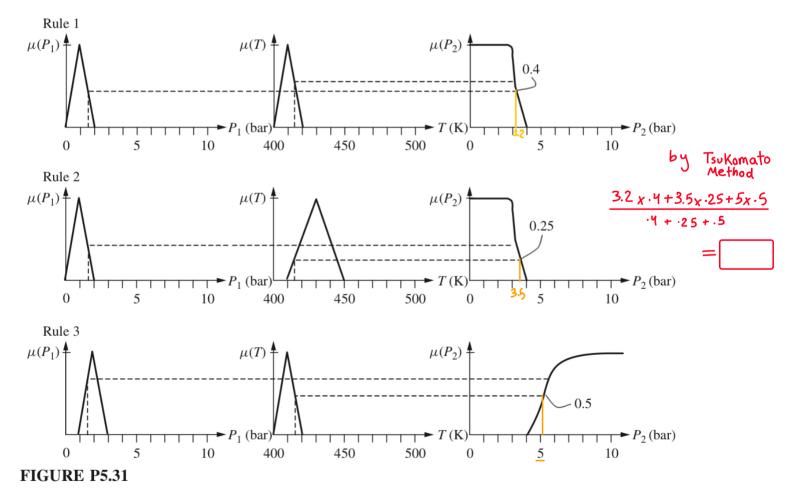
5.31. From thermodynamics it is known that for an ideal gas in an adiabatic reversible process

$$\frac{T_2}{T_1} = \left(\frac{P_2}{P_1}\right)^{\frac{\gamma - 1}{\gamma}},$$

where T_1 and T_2 are temperatures in kelvin (K) and P_1 and P_2 are pressures in bars and, for an ideal gas. For the Sugeno solution, use the following functions for the consequents of the three rules:

> Rule 1 : $T_1 = 320$ K and $\gamma = 1.5$ Rule 2 : $T_1 = 300$ K and $\gamma = 1.4$ Rule 3 : $T_1 = 300$ K and $\gamma = 1.3$

For this problem, T_1 will be fixed at 300 K and the fuzzy model will predict P_2 for the given input variables P_1 and T_2 . In other words, we are interested in finding the final pressure, P_2 , of the system if the temperature of the system is changed to T_2 from an original pressure equal to P_1 . A real application could use a similar model built from experimental data to do a prediction on nonideal gases.



Chapter 6 Development of Membership Functions

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Membership Value Assignments

• The assignment process can be intuitive or based on some algorithmic or logical operations.

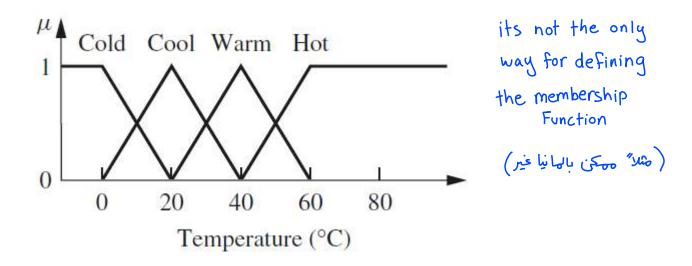
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2

- Common methods are:
 - 1. Intuition
 - 2. Inference
 - 3. Rank ordering
 - 4. Neural networks
 - 5. Genetic algorithms
 - 6. Inductive reasoning



- The membership values or functions can be derived from the capacity of humans to develop them through their own innate intelligence and understanding.
- Example: Develop fuzzy membership functions for the temperature.
 - Very cold
 - Cold
 - Normal
 - Hot
 - Very hot



Inference

متساوي السامين I Approximate isosceles triangle e

• Example: Let U be the universe of triangles, where the inner angles are A, B and C.

• Knowledge is utilised to perform deductive reasoning.

$$\widetilde{\mathbf{R}}$$
 Approximate right triangle
 $\widetilde{\mathbf{IR}}$ Approximate isosceles and right triangle
 $\widetilde{\mathbf{E}}$ Approximate equilateral triangle
 $\widetilde{\mathbf{T}}$ Other triangles.

$$\begin{split} \mu_{\widetilde{L}}(A, B, C) &= 1 - \frac{1}{60^{\circ}} \min(A - B, B - C) \\ \mu_{\widetilde{R}}(A, B, C) &= 1 - \frac{1}{90^{\circ}} |A - \underline{90^{\circ}}| \\ I\mathbb{R} &= \mathbb{I} \cap \mathbb{R}, \end{split}$$

$$\begin{split} \mu_{\widetilde{E}}(A, B, C) &= 1 - \frac{1}{180^{\circ}} (A - C) \end{split}$$

الرأي الشخصي حسب تجربتنا جــــــ intuition

inference ---- مبنيعلى الخبراء (experience Knowlege)

Question & Assume the Universe is the (GPA)
and we have
$$\begin{array}{c} & Excellent \rightarrow (3.65-4)\\ & Very Good \rightarrow (3-3.64)\\ & Good \rightarrow (2.5-2.91)\\ & Satisfaction \rightarrow (2-2.49)\\ \end{array}$$

by using inference (your own Knowledge)
(we have to write 4 equations of Membership)
Function

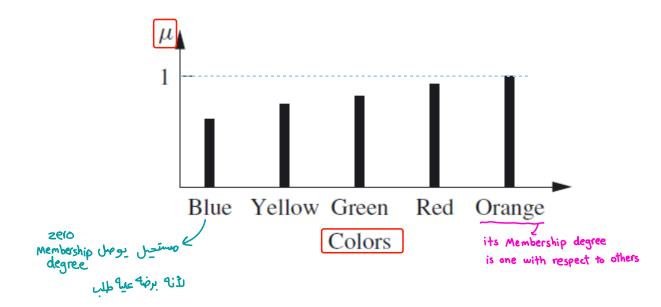


it is easier but the Knowledge is not as accurate as inference

- Preference is determined by pairwise comparisons, and these determine the ordering of the membership.
- Example: Suppose 1000 people respond to a@about their pairwise preferences among five colours, X = {red, orange, yellow, green, blue}.

	Number who preferred						حسب ترتيب ال Percentages	
	Red	Orange	Yellow	Green	Blue	Total	Percentage	Rank order
Red	27 <u>—18</u>	517	525	545	661	2 2 4 8	22.5	2
Orange	483		841	477	576	2377	23.8	1
Yellow	475	159	_	534	614	1782	17.8	4
Green	455	523	466	1 <u></u> 11	643	2087	20.9	3
Blue	339	424	386	357	_	1 506	15	5
Total						10 000		
					UP Svoj no is	ت الدَّنَّهُ السَّخر عم ينجع ا		

• Membership function for the best colour

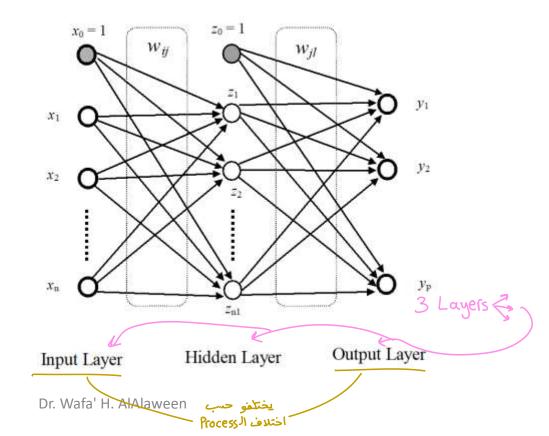


Rarely we use in development of membership Function

ע Neural Networks

There is an input and according to it there will be an output

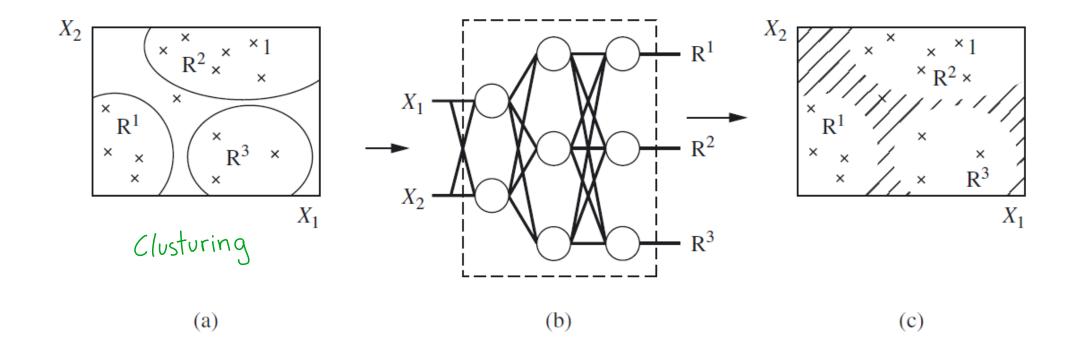
• A neural network: is a technique that builds an intelligent system by simulating the biological neural network.

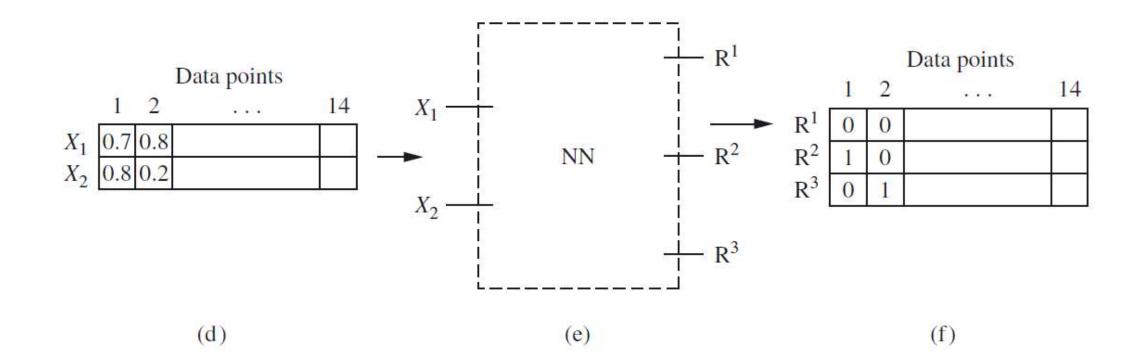


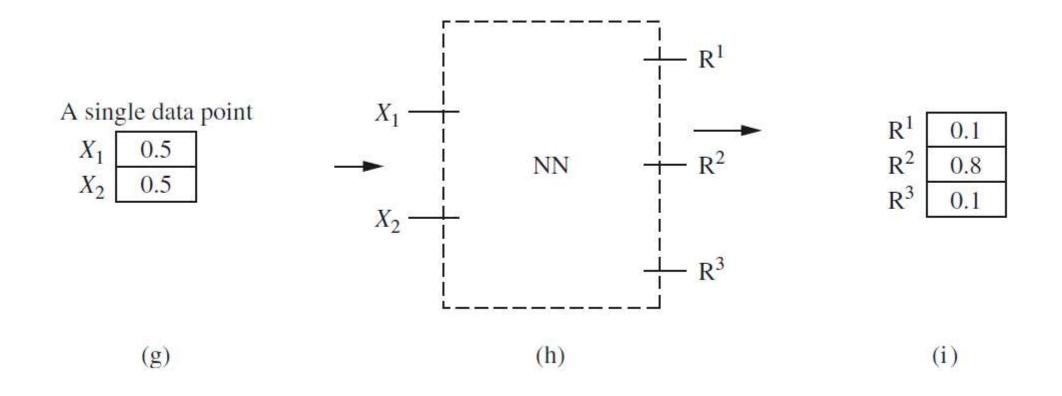
$$z_{j}(k) = f_{j}(\sum_{i=1}^{n} w_{ij}x_{i}(k) + b_{j}), \quad j = 1, 2, ..., n_{1}; \quad k = 1, 2, ...$$
$$y_{l}(k) = f_{l}(\sum_{j=1}^{n_{1}} w_{jl}z_{j}(k) + b_{l}); \quad l = 1, 2, ..., p; \quad k = 1, 2, ...$$
$$E(k) = \frac{1}{2}\sum_{l=1}^{p} (y_{l}(k) - y_{l}^{t}(k)))^{2}$$
$$w_{jl}(k+1) = w_{jl}(k) - \alpha \nabla_{w_{jl}} E(k)$$

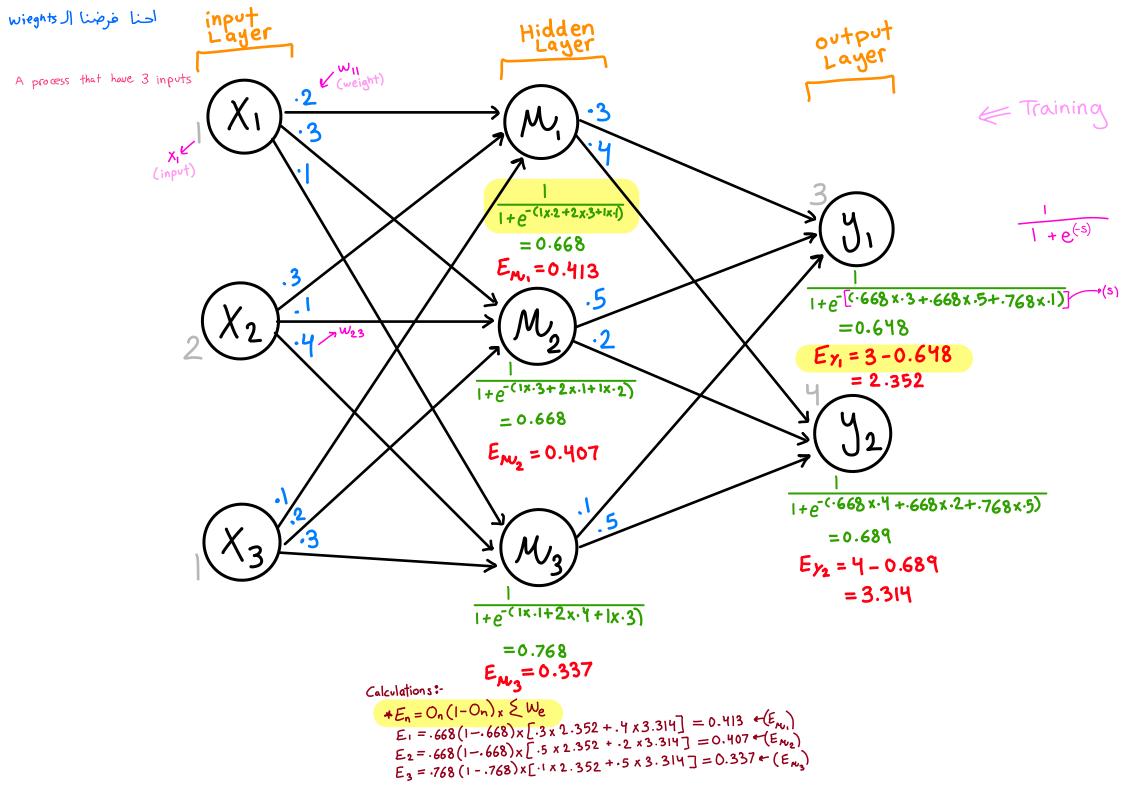
Distributing the error using back-propagation technique

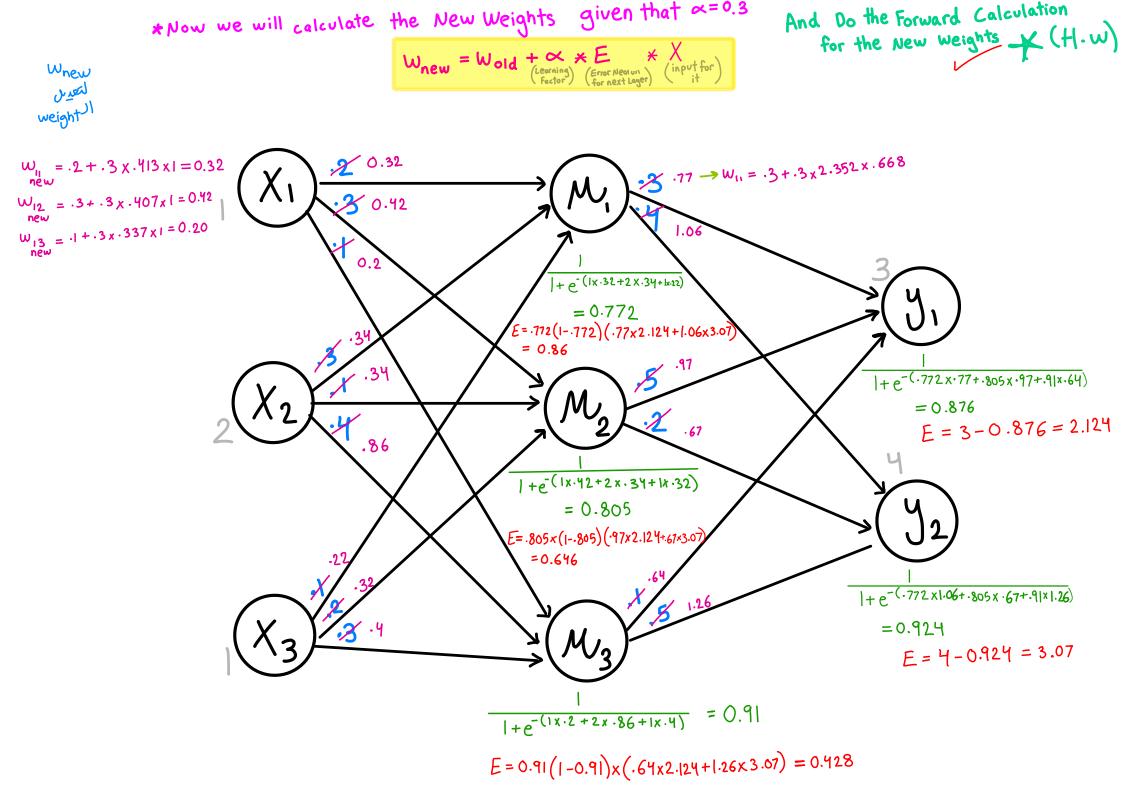
• Determining the membership function

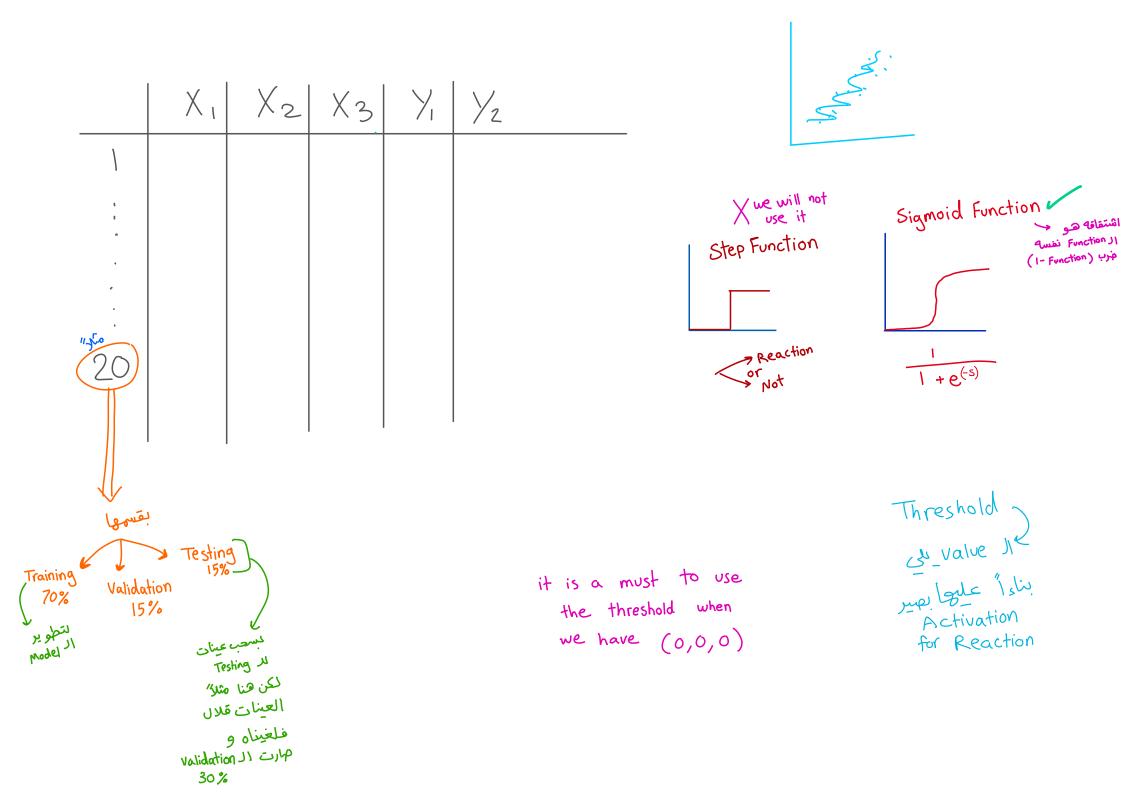


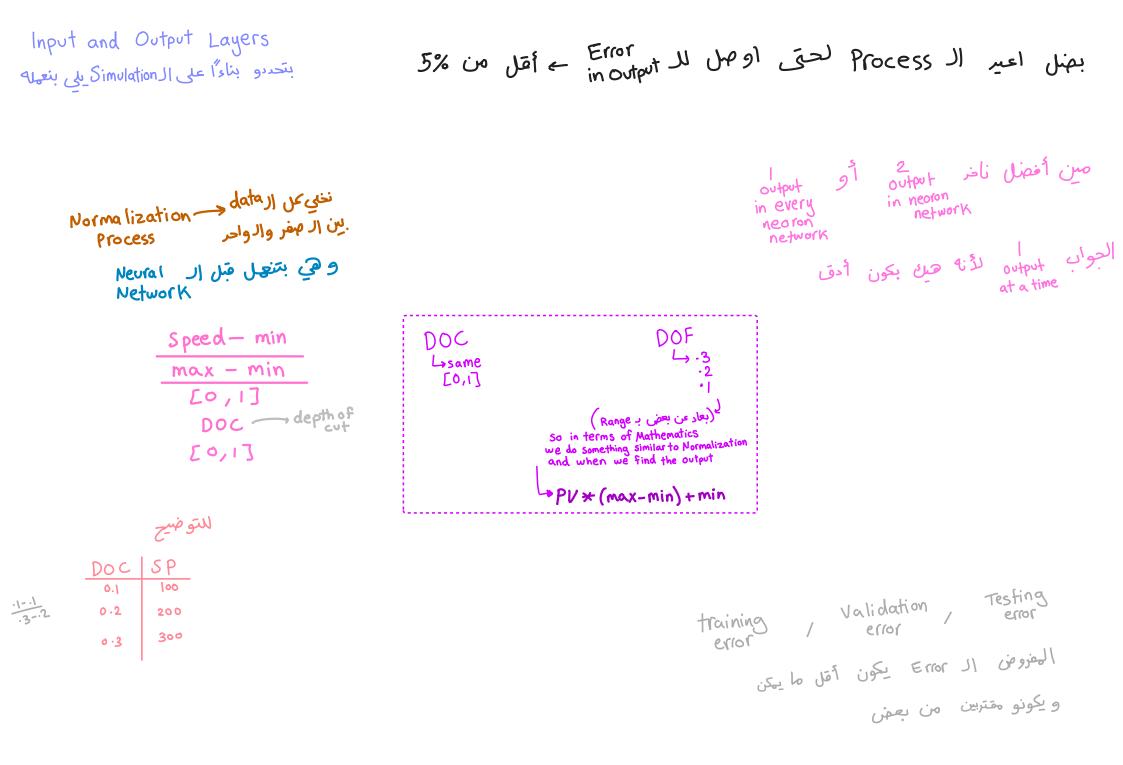


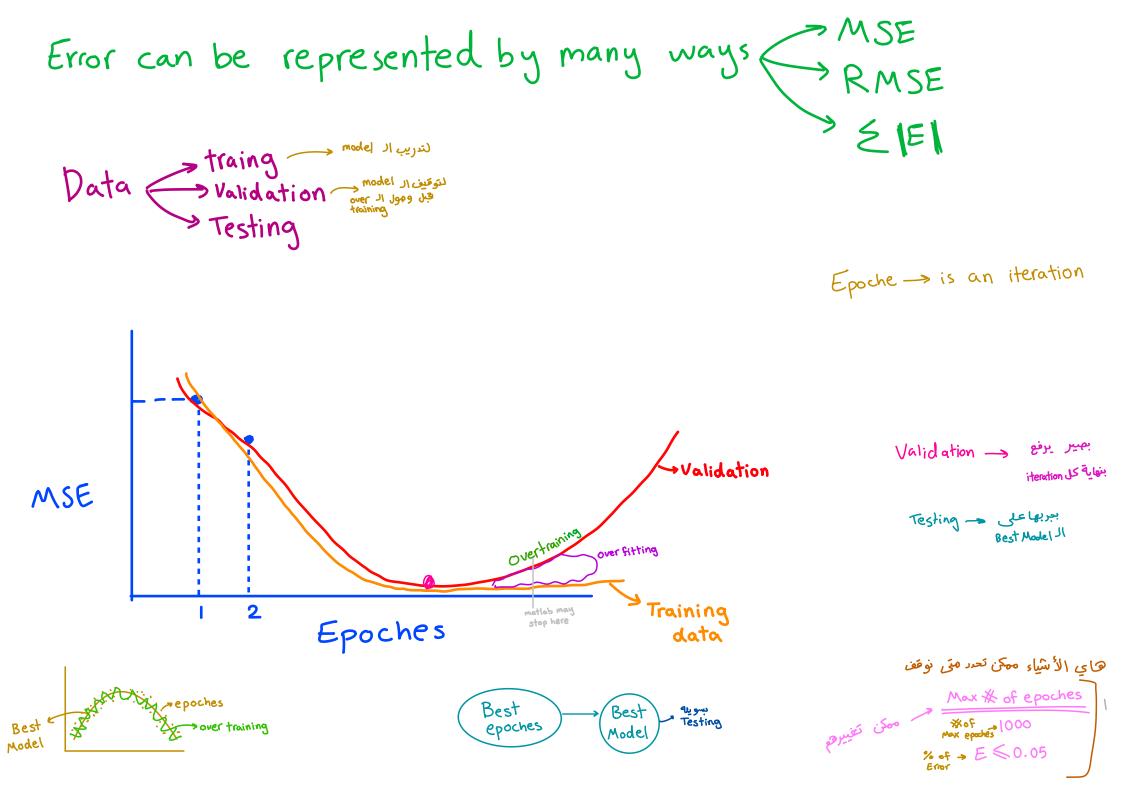










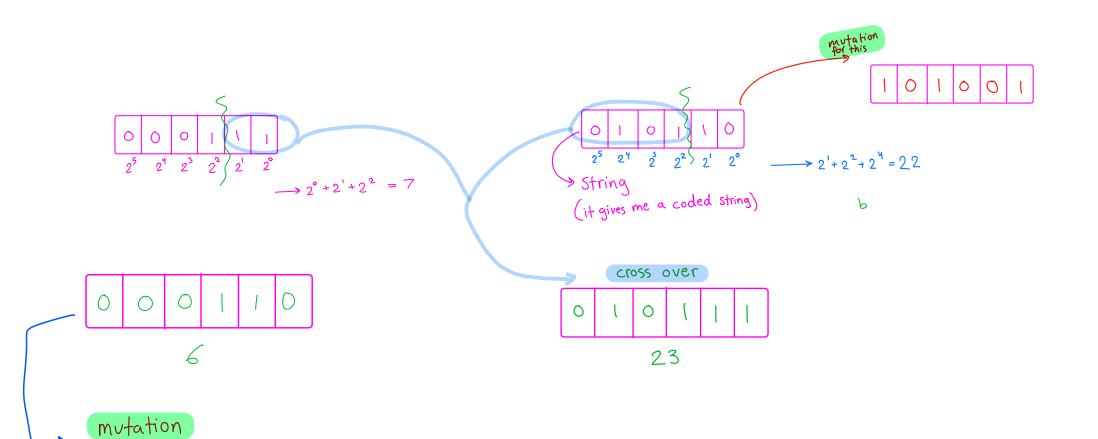


Genetic Algorithms

- New breeds or classes come into existence through the processes of reproduction, crossover, and mutation among existing organisms.
- The algorithms procedure can be summarized as follows:
 - Different possible solutions are created.
- 2 They are then tested for their performance.
 - Among all of them, a fraction of the good solutions is selected, and the others are eliminated.
- The selected solutions undergo the processes of reproduction, crossover, and mutation to create a new generation of possible solutions.

مستحيل المج المحون أكسوة من اله Previous الأني بعال آخد الأفعل stage

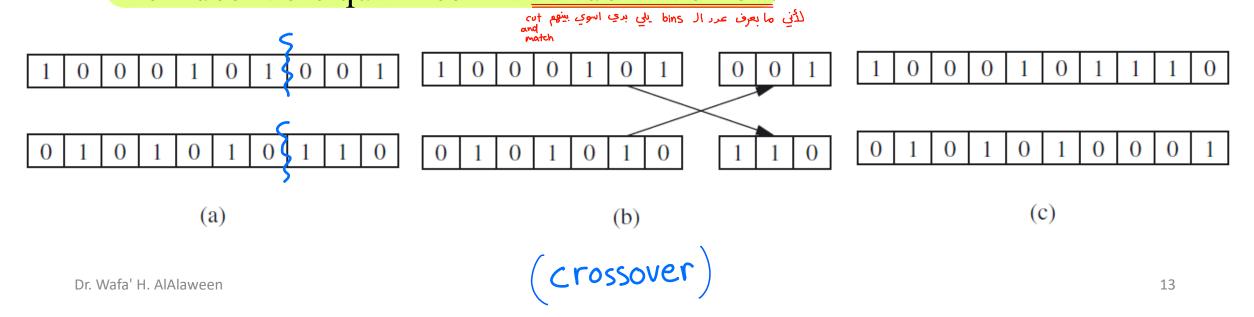
- In a genetic algorithm, the parameter set is coded as a finite string, which is presented as a combination of zeros and ones.
- For example, the number 7 requires a 3-bit string, that is, $2^3 1 = 7$, and the bit string would look like "111".
- So the number 10 would look like: "1010".



1 1 1 0 0 1

 \rightarrow

- Reproduction is the process by which strings with better fitness values receive correspondingly better copies in the new generation, to ensure that better solutions persist and contribute to better offspring (new strings).
- Crossover is the process in which the strings are able to mix and match their desirable qualities in a random fashion.



- Mutation is the process by which the value at a certain string location is changed; if there is a one originally at a location in the bit string, it is changed to a zero, or vice versa. $\stackrel{\circ}{\xrightarrow{}}_{1}$
- Mutation takes place very rarely, on the order of once in a thousand bit string locations.

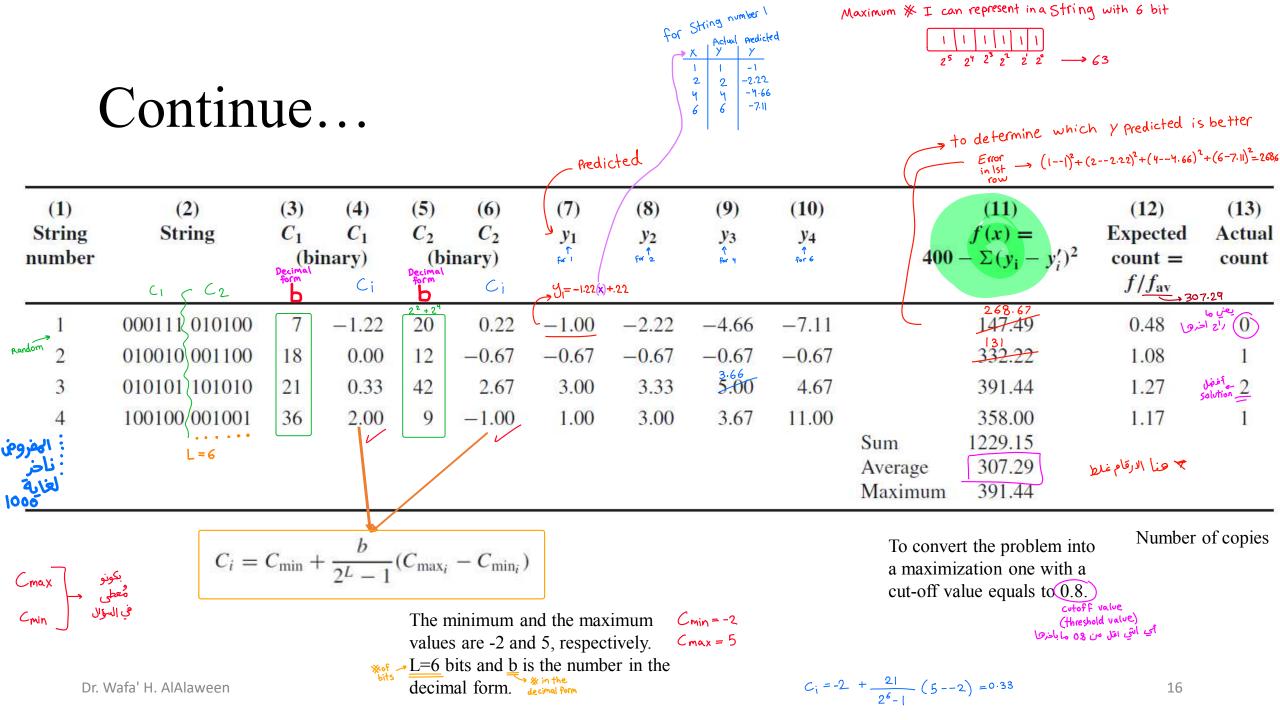
Genetic Algorithms: Example

• Using the data provided in the table below, perform a line fit $(y=C_1x+C_2)$.

		Actual
Data number	x	y′
1	1.0	1.0
2	2.0	2.0
3	4.0	4.0
4	6.0	6.0

The algorithms procedure can be summarized as follows:

- · Different possible solutions are created.
- They are then tested for their performance.
- Among all of them, a fraction of the good solutions is selected, and the others are eliminated.
- The selected solutions undergo the processes of reproduction, crossover, and mutation to create a new generation of possible solutions.





(1) Selected strings	(2) New strings	(3) C ₁ (b)	(4) C ₁ inary)	(5) C ₂ (b)	(6) C ₂ inary)	(7) y ₁	(8) ¥2	(9) ¥3	(10) y4	400	(11) $f(x) = -\Sigma(y_i - y'_i)^2$	(12) Expected count = f/f_{av}	(13) Actual count
0101 01 101010 0100 10 001100 010101 101 010 100100 001 001	010110 001100 010001 101010 010101 101001 100100 001010	22 17 21 36	0.44 -0.11 0.33 2.0	12 42 41 10	-0.67 2.67 2.56 -0.89	-0.22 2.56 2.89 1.11	0.22 2.44 3.22 3.11	1.11 2.22 3.89 7.11	2.00 2.00 4.56 11.11	Sum	375.78 380.78 292.06 255.73 1304.35	1.15 1.17 0.90 <u>0.78</u> آقل من 80	$ \begin{array}{c} 1\\ 2\\ 1\\ \rightarrow \\ 0\\ 1^{1c1} \end{array} $
										Average Maximum	326.09 380.78		

Membership Function

Genetic Algorithms: MF

• Membership functions and their shapes are assumed for various variables defined for a problem. They are then coded as bit strings.

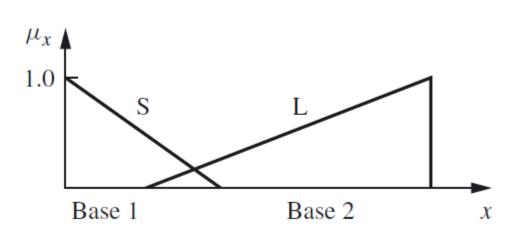


• Let us consider that we have a single-input (x), single-output (y) system with input-output values as shown below:

x	1	2	3	4	5
y	1	4	9	16	25

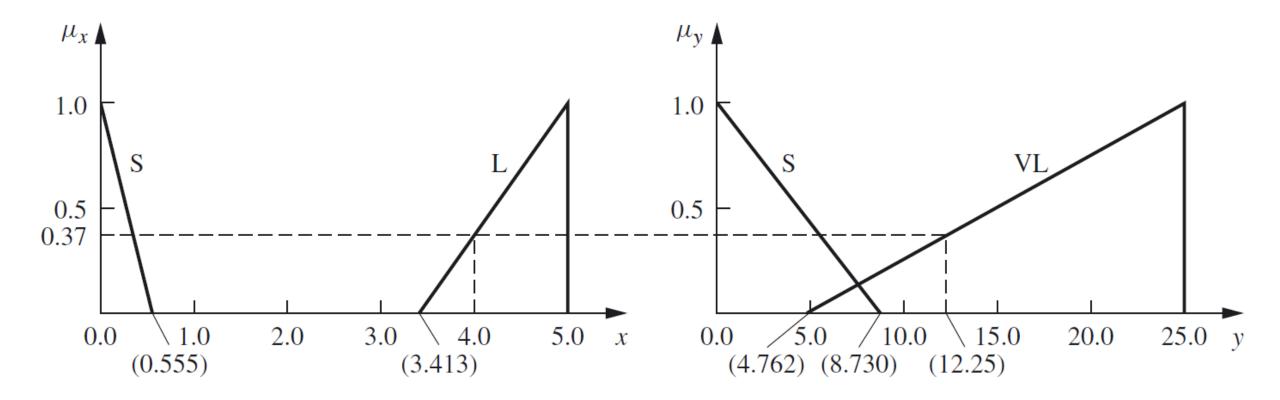
X	S	L
У	S	VL

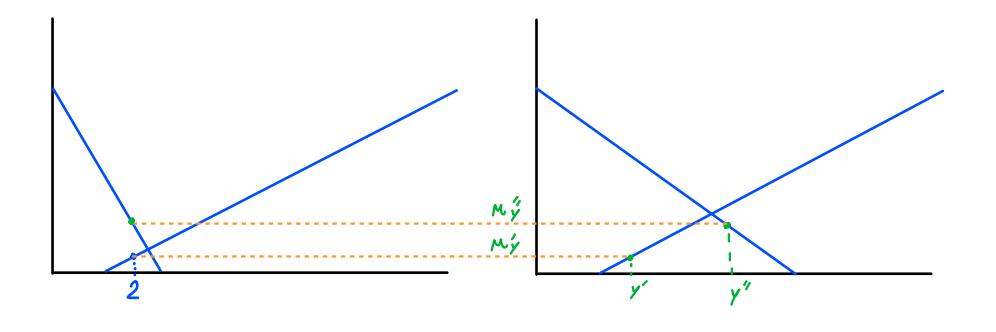
- We assume that the range of the variable x is [0, 5] and that of y is [0, 25].
- Membership function:



Hembership لأنه إله أقل عدد parameters من بين كل إل (Right Functions من بين كل إل المعادة الوحير هو القاعدة

String number		(2) Base 1 (binary)	(3) Base 2 (binary)	(4) Base 3 (binary)	(5) Base 4 (binary)		(7) 1 Base 2	(8) Base 3	(9) Base 4		(11) y' $(x = 2)$	(12) y' $(x = 3)$	(13) y' $(x = 4)$	(14) y' (x = 5)	(15) 1000- $\Sigma(y_i - y'_i)^2$	(16) Expected $count = f/f_{av}$	
1	000111 010100 010110 110011	7	20	22	51	0.56	1.59	8.73	20.24	0	0	0	12.25	25	887.94	1.24	1
2	010010 001100 101100 100110	18	12	44	38	1.43	0.95	17.46	15.08	12.22	0	0	0	25	521.11	0.73	0
3	010101 101010 001101 101000	21	42	13	40	1.67	3.33	5.16	15.87	3.1	10.72	15.48	20.24	25	890.46	1.25	2
4	100100 001001 101100 100011	36	9	44	35	2.86	0.71	17.46	13.89	6.98	12.22	0	0	25 Sum Average Maximum	559.67 2859.18 714.80 890.46	0.78	1
in the Ger	: at least 300 solutions netic Algorithm but in this : defined only 4 just to d the idea					> Min	$+\frac{b}{2^{L}-1}($ $+\frac{7}{2^{6}-1}($	max-Min 5-0) =() 0.56				Gen Algo	etic Nov rithm N of it	نې کل erations بې وصل لل erations	بیر بالواقع انه نوصل لار chion	یلي بم قبل ما





weighted بأي طريقة من اللا يلي درسناهم و عادي لو أخدنا أسهل طريقة يلي هي الا Average با معادي لو أخدنا أسهل طريقة يلي هي الا Average

(1) Selected strings	(2) New Strings			(5) Base 3 (binary)			(8) Base 2	(9) 2 Base 3	(10) Base 4	-	(12) y' $(x = 2)$	(13) y' $(x = 3)$	(14) y' $(x = 4)$	(15) y' (x = 5)	(16) 1000- $\Sigma(y_i - y'_i)^2$	(17) Expected count = f/f_{av}	
000111 0101 00 010110 110011 00 010101 1010 10 001101 101000 01 010101 101010 001101 101000 01 100100 001001 101100 100011 10	10101 101000 010110 110011 0101 101010 001101 10 0011	21 21	22 40 42 9	13 22 13 44	40 51 35 40	0.56 1.67 1.67 2.86	1.75 3.17 3.33 0.71	5.16 8.73 5.16 17.46	20.24 13.89	0 5.24 3.1 6.11	0 5.85 12.51 12.22	0 12.23 16.68 0	15.93 18.62 20.84 0	25	902.00 961.30 840.78 569.32 3 273.40 818.35 961.30	1.10 1.18 1.03 0.70	1 2 1 0

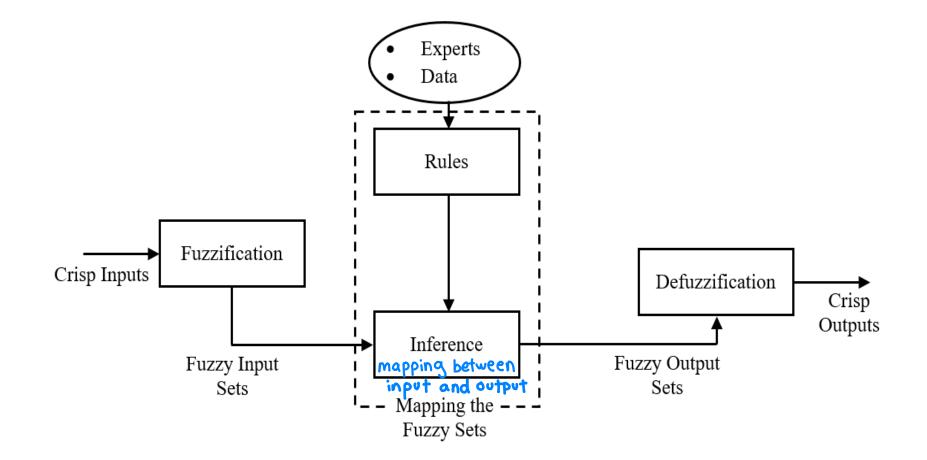
(chapter 7) Type-1 Fuzzy Logic System (T1FLS)

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This Chapter is included in another book)

Type-1 Fuzzy Logic System (T1FLS)



T1FLS: Fuzzification

- Fuzzification step represents the process of mapping the crisp inputs $(x_1, x_2 \dots x_n)$ to the fuzzy input sets (A_j^i) , where A_j^i is the ith fuzzy set for the jth variable.
- The fuzzy sets are usually defined by membership functions. The most commonly used membership function is the Gaussian one:

$$\mu_j^i(x_j) = \exp\left[-\frac{1}{2}\left(\frac{x_j - m^i}{\sigma^i}\right)\right]$$

(6) Guassian
is better than
(3) triangular
Depending on the
Degree of Freedom

TIFLS: Rules Data given extraction by Clusturing

- The rules can be provided by experts or can be extracted from a collected data set.
- Both types can be presented as a collection of IF-THEN statements, as follows:

Rule^{*i*}: IF
$$x_1$$
 is A_1^i ... and x_n is A_n^i , THEN y is B^i .

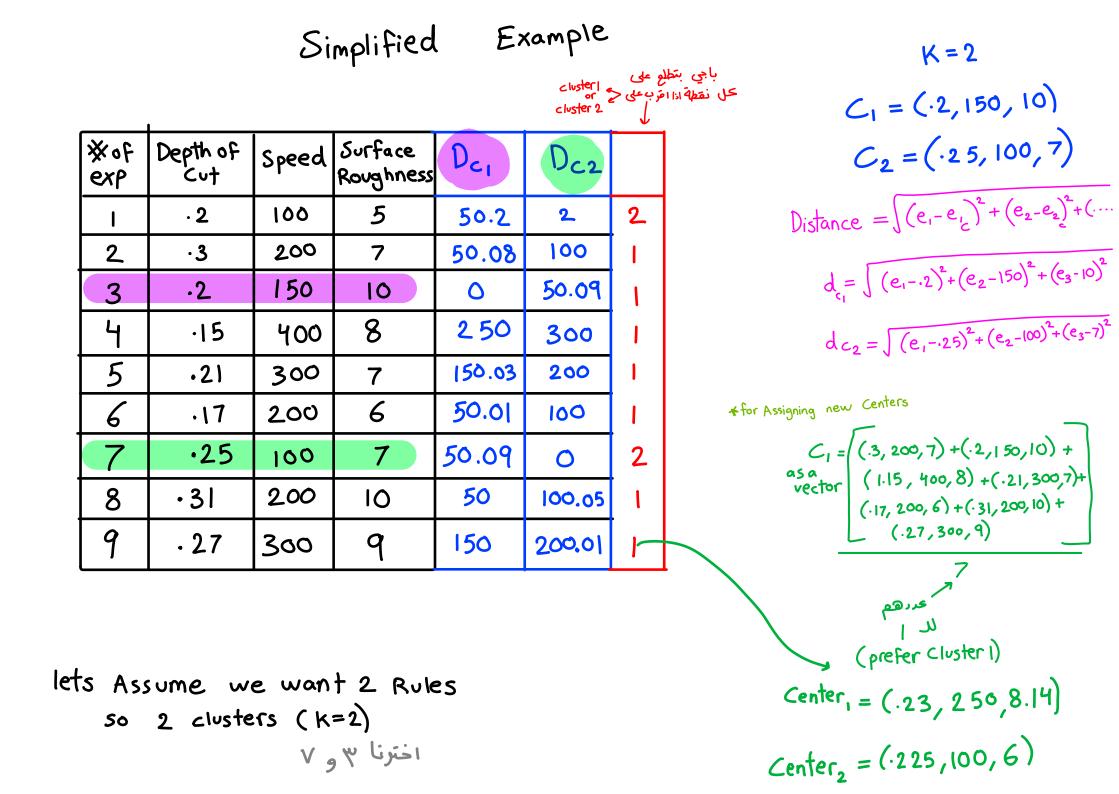
Clustering/classification can be utilized to initialize the system parameters. it is unsupervised (there is no target to compare with) (it is the initialilization for parameters in Fuzzy System)

Dr. Wafa' H. AlAlaween

- Clustering/classification is a data mining technique used to predict group membership for data instances.
- K-means clustering: clustering N data points into K disjoint subsets.
 - How: Specify k, the number of clusters to be generated $\rightarrow (K)$ (K) Known in advance
 - Choose k points at random as cluster centers
 - Assign each instance to its closest cluster center using Euclidean distance
 - Calculate the centroid (mean) for each cluster, use it as a new cluster center
 - Reassign all instances to the closest cluster center
 - Iterate until the cluster centers don't change anymore \longrightarrow المرحلة المرحلة المرحلة المرحلة في المرحلة م

• Example:

Subject	А	B
1	1.0	1.0
2	1.5	2.0
3	3.0	4.0
4	5.0	7.0
5	3.5	5.0
6	4.5	5.0
7	3.5	4.5



(Clustering Method)

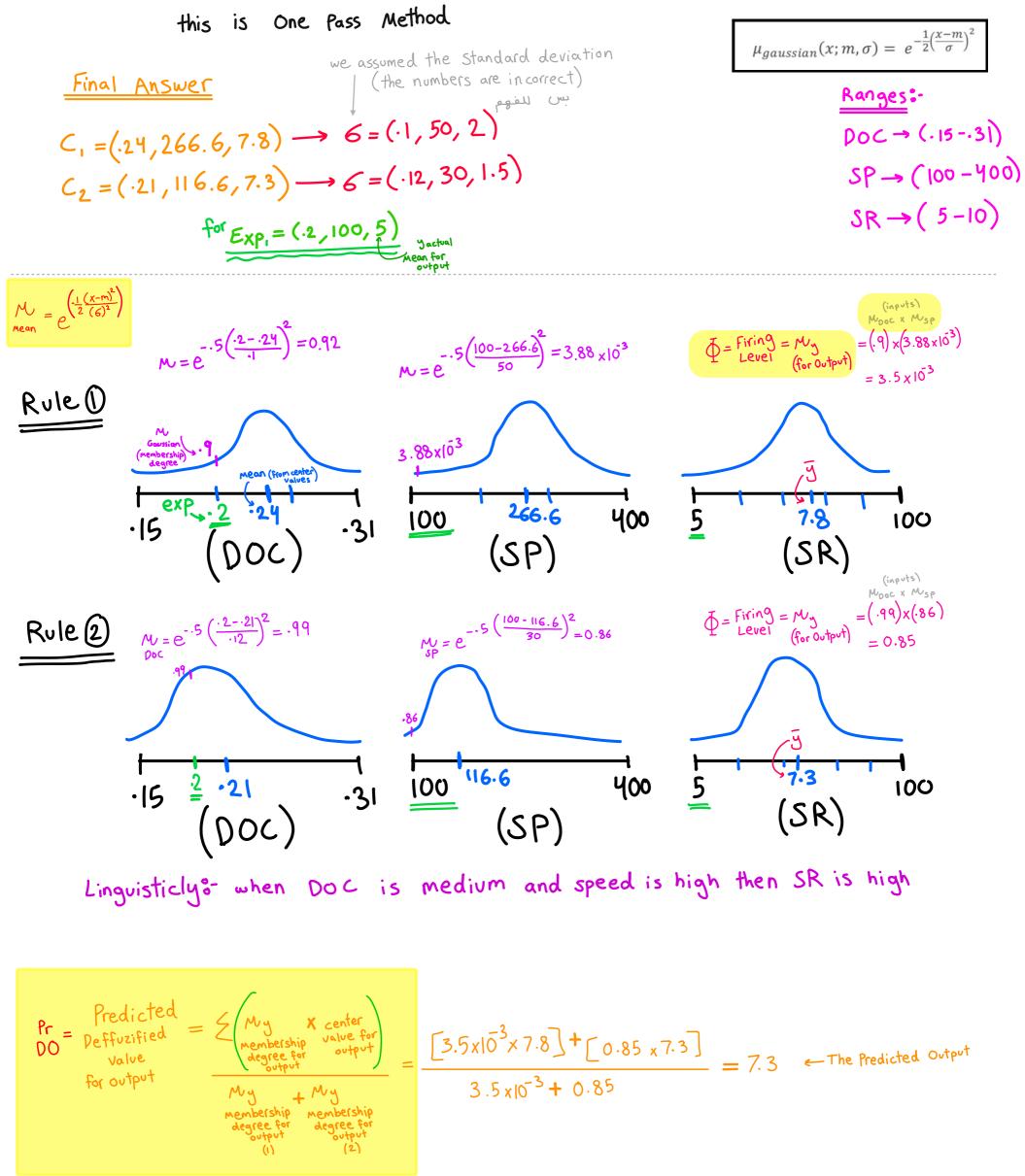
Continue (until the Cluster centers doesn't change)

×∘F exp	Depth of Cut	Speed	Surface Roughness	Dc1	D _{c2}	choose cluster	Dci	Dc2	choose cluster	Dci	D _{c2}	choose cluster
I	· 2	100	5	50.2	2	2	150.03	l	2	166.6	16.7	2
2	• 3	200	7	50.08	100	1	50.01	100	I	66.6	83.4	1
3	•2	150	10	0	50.09	1	00.01	50.15	2	116.6	33.5	2
4	·15	400	8	2 50	300	I	150	300	1	133.4	283	l
5	•21	300	7	150.03	200	1	50.01	200	1	33.41	183	1
6	.17	200	6	50.01	100	1	50.04	100	I	66.6	83.4	۱.
7	•25	100	7	50.09	0	2	150	l	2	166.6	16.6	2
8	•31	200	10	50	100.05	1	50.03	80.00	1	66.6	84.4	1
9	• 27	300	9	150	200.01	1	50	200	I	33.Y	183	١

 $C_1 = (.2, |50, 10)$ $C_2 = (.25, 100, 7)$ C1=(.23,250,8.14) C2=(.225,100,6)

 $C_{1} = (.235, 266.6, 7.83) \qquad C_{1} = (.235, 266.6, 7.83) \\ C_{2} = (.22, 116.6, 7.33) \qquad C_{2} = (.22, 116.6, 7.33) \\ C_{3} = (.22, 116.6, 7.33) \qquad C_{4} = (.22, 116.6, 7.33) \\ C_{5} = (.22$

The centers didn't change so we stop



$$C_{n} = (4, 100, 5) = (-4, 100)$$

$$R_{n} = (2, 100, 5) = (-4, 100)$$

$$R_{n} = (-4, 100, 5) = (-4, 100, 5)$$

$$R_{n} = (-4, 100, 5) = (-4, 100, 5)$$

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$$R_{n} = (-4, 100, 5)$$

(•3, 200, 7) Exp for practice Point 2 (Julie Julie)

3 Stopping criteria 9251 (1) 2) Error < .05 (3) validation less 70% of data





Steepest Deepest Algorithm
$$\longrightarrow$$
 takes error as a function
and minimize it
 $Error = \frac{1}{2} [pred - out]^2$

في ال Fuzzy ما في داعي نعل Normalization

Inference and Defuzzification

- The inference process combines the defined rules to map the input fuzzy sets to the output fuzzy sets.
- The output fuzzy set is then <u>defuzzified</u> to get a crisp one.
- By using centre average defuzzification method, such a mapping can be represented as follows:

$$f(x|\theta) = \frac{\sum_{i=1}^{R} b_i \prod_{j=1}^{n} \exp\left[-\frac{1}{2} \left(\frac{x_j - c_j^i}{\sigma_j^i}\right)^2\right]}{\sum_{i=1}^{R} \prod_{j=1}^{n} \exp\left[-\frac{1}{2} \left(\frac{x_j - c_j^i}{\sigma_j^i}\right)^2\right]},$$

- The model parameters need to be optimized by employing an adaptive back-propagation network.
- Assignment: Steepest descent method.

Chapter 9 Decision Making with Fuzzy Information

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Introduction

- The decisions may be binary, however, there should be no restrictions on the usefulness of fuzzy information in the decision making process.
- Being able to make consistent and correct choices is the essence of any decision process imbued with uncertainty.
- The information affecting an issue is likely incomplete or uncertain; hence, the outcomes are uncertain, irrespective of the decision made or the alternative chosen.
- There is a distinct difference between a good decision and a good outcome!

- Engineers are primarily concerned with two types of decisions:
 - 1. Operational decisions: an optimal action is sought to avoid a specific set of hazards;
 - 2. Strategic decisions: preparation for or anticipation of events in the future.
- Various paradigms for making decisions within a fuzzy environment.

right decision doesn't mean right outcome

Fuzzy Synthetic Evaluation

- Numerical evaluation is often too complex, too unacceptable, and too transient.
- Therefore, the evaluation can be described by natural language (e.g. excellent, good, etc.)
- A fuzzy relation can be found, followed by numerical evaluation.

Example

Suppose we want to measure the value of a microprocessor to a potential client. In conducting this evaluation, the client suggests that certain criteria are important. They can include performance (MIPS), cost (\$), availability (AV), and software (SW). Performance is measured by millions of instructions per second (MIPS); a minimum requirement is 10 MIPS. Cost is the cost of the microprocessor, and a cost requirement of "not to exceed" 500 has been set. Availability relates to how much time after the placement of an order the microprocessor vendor can deliver the part; a maximum of eight weeks has been set. Software represents the availability of operating systems, languages, compilers, and tools to be used with this microprocessor. Suppose further that the client is only able to specify a subjective criterion of having "sufficient" software.

A particular microprocessor (CPU) has been introduced into the market. It is measured against these criteria and given ratings categorized as excellent (e), superior (s), adequate (a), and inferior (i).

Using the similarity methods presented in Chapter 3, the relation matrix is as follows:

$$w = \left[\frac{.4}{P}, \frac{.3}{.2}, \frac{.2}{.A}, \frac{.1}{.5}\right] \qquad R = \begin{cases} e & s & a & i \\ MIPS \\ AV \\ SW \end{cases} \begin{bmatrix} 0.1 & 0.3 & 0.4 & 0.2 \\ 0 & 0.1 & 0.8 & 0.1 \\ 0.1 & 0.6 & 0.2 & 0.1 \\ 0.1 & 0.4 & 0.3 & 0.2 \end{bmatrix}$$

If the evaluation team applies a scoring factor of 0.4 for performance, 0.3 for cost, 0.2 for availability, and 0.1 for software, then evaluate such a microprocessor?

by (Max-Min)
composition

$$\mathbf{e} = \mathbf{w} \circ \mathbf{R} = \{0.1, 0.3, 0.4, 0.2\}$$

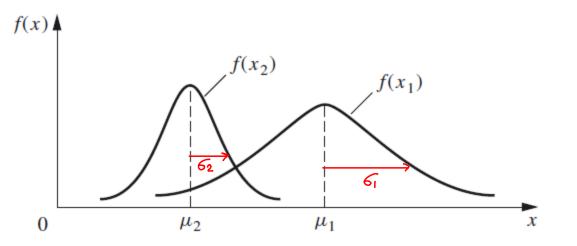
 $\mathbf{w} \circ \mathbf{R} = \{0.1, 0.3, 0.4, 0.2\}$
 $\mathbf{w} \circ \mathbf{R} = \{0.1, 0.3, 0.4, 0.2\}$
 $\mathbf{w} \circ \mathbf{R} = \{0.1, 0.3, 0.4, 0.2\}$

composit

Fuzzy Ordering

- Decisions are sometimes made on the basis of rank, or ordinal ranking: which issue is best, which is second best, and so forth.
- Issues or actions are associated with randomness of fuzziness uncertainty, therefore, rank ordering may be ambiguous.
- If the uncertainty in rank is random, we can use probability density functions (PDF).

- Example: Suppose we have one random variable, x_1 , whose uncertainty is characterized by a Gaussian PDF with a mean of μ_1 and a standard deviation of σ_1 , and another random variable, x_2 , also Gaussian with a mean of μ_2 and standard deviation of σ_2 . Suppose that $\sigma_1 > \sigma_2$ and $\mu_1 > \mu_2$.
- The question of which variable is greater is not clear.



• We can assess this by frequency,

$$P(x_1 \ge x_2) = \int_{-\infty}^{\infty} F_{x_2}(x_1) \, \mathrm{d}x_1$$

F is the cumulative function

• If the uncertainty in rank is because of ambiguity, then the ranking is very subjective and not reducible to the elegant form available for some random variables.

- If the uncertainty in rank is because of imprecision, then the truth value can be used.
- Suppose we have k fuzzy sets I_1, I_2, \ldots, I_k . Then, the truth value of a specified ordinal ranking is given as

 $T(\underline{I} \ge \underline{I}_1, \underline{I}_2, \dots, \underline{I}_k) = T(\underline{I} \ge \underline{I}_1)$ and $T(\underline{I} \ge \underline{I}_2)$ and \dots and $T(\underline{I} \ge \underline{I}_k)$

• Example: Suppose we have three fuzzy sets:

 $I_{1} = \left\{ \frac{1}{3} + \frac{0.8}{7} \right\}, \quad I_{2} = \left\{ \frac{0.7}{4} + \frac{1.0}{6} \right\}, \quad \text{and} \quad I_{3} = \left\{ \frac{0.8}{2} + \frac{1}{4} + \frac{0.5}{8} \right\}$ We can assess the truth value of the inequality, $I_{1} \ge I_{2}$, as follows: $I_{1} = I_{2}$

 $\underline{T(\underline{I}_{1} \geq \underline{I}_{2})}_{in \mathbf{I}_{2} \text{ in } \mathbf{I}_{2}} = \max_{x_{1} \geq x_{2}} \{ \min(\mu_{\underline{I}_{1}}(x_{1}), \mu_{\underline{I}_{2}}(x_{2})) \}$ $= \max_{x_{1} \geq x_{2}} \{ \min(\mu_{\underline{I}_{1}}(x_{1}), \mu_{\underline{I}_{2}}(x_{2})) \}$ $= \max_{x_{1} \geq x_{2}} \{ \min(\mu_{\underline{I}_{1}}(x_{1}), \mu_{\underline{I}_{2}}(x_{2})), \min(\mu_{\underline{I}_{1}}(x_{1}), \mu_{\underline{I}_{2}}(x_{2})) \}$ $= \max_{x_{1} \geq x_{2}} \{ \min(\mu_{\underline{I}_{1}}(x_{1}), \mu_{\underline{I}_{2}}(x_{2})), \min(\mu_{\underline{I}_{1}}(x_{1}), \mu_{\underline{I}_{2}}(x_{2})) \}$ $= \max_{x_{1} \geq x_{2}} \{ \min(\mu_{\underline{I}_{1}}(x_{1}), \mu_{\underline{I}_{2}}(x_{2})), \min(\mu_{\underline{I}_{1}}(x_{1}), \mu_{\underline{I}_{2}}(x_{2})) \}$

 $= \max\{\min(0.8, 0.7), \min(0.8, 1.0)\} \longrightarrow \max(.7, .8)$

$$= 0.8.$$
Truth value that $(I_1 7 I_2)$

بناخر کل ال possibilities سے I2 و T

I2gI1

II gIz

 $T_{39}I_{1}$

Izg Iz

 $I_{39}I_2$

و هکذا

Similarly,

$$\begin{split} T(\underline{\mathbf{I}}_1 \geq \underline{\mathbf{I}}_3) &= 0.8, \quad T(\underline{\mathbf{I}}_2 \geq \underline{\mathbf{I}}_1) = \underline{\mathbf{1.0}}, \\ T(\underline{\mathbf{I}}_2 \geq \underline{\mathbf{I}}_3) &= 1.0, \quad T(\underline{\mathbf{I}}_3 \geq \underline{\mathbf{I}}_1) = 1.0, \\ T(\underline{\mathbf{I}}_3 \geq \underline{\mathbf{I}}_2) &= 0.7. \end{split}$$

Then,

Truth value that
$$I_1 \rightarrow T(I_1 \ge I_2, I_3) = 0.8, \rightarrow \min(...8, ...8)$$

 $T(I_2 \ge I_1, I_3) = 1.0, \rightarrow \min(...1, ...8)$
 $T(I_3 \ge I_1, I_2) = 0.7, \rightarrow \min(...8, ...8)$
verall ordering is

Then the overall ordering is \dots I_2, I_1, I_3

Nontransitive Ranking

- When we compare objects that are fuzzy, ambiguous, or vague, we may well encounter a situation where there is a contradiction in the classical notions of ordinal ranking and transitivity in the ranking.
- Example: When comparing red to blue, we prefer red; when comparing blue to yellow, we prefer blue; but when comparing red and yellow we might prefer yellow.
- For nontransitive ranking, the relativity function is introduced.

• Let x and y be variables defined on the same universe, and let's define pairwise functions

 $f_y(x)$ as the membership value of x with respect to y

 $f_x(y)$ as the membership value of y with respect to x

• Then, the relativity function can be written as follows:

Preference
$$f(x \mid y) = \frac{f_y(x)}{\max[f_y(x), f_x(y)]}$$
A measurement of the membership
value of choosing x over y.

• For more than two variables, the relativity function is given as follows:

$$f(x_i \mid A') = f(x_i \mid \{x_1, x_2, \dots, x_{i-1}, x_{i+1}, \dots, x_n\})$$

= min{f(x_i \mid x_1), f(x_i \mid x_2), \dots, f(x_i \mid x_{i-1}), f(x_i \mid x_{i+1}), \dots, f(x_i \mid x_n)}

A fuzzy measurement of choosing x_i over all the other elements

• Question: By including x_i in the equation above, what is the output?

• Example: In manufacturing, we often try to compare the capabilities of various microprocessors for their appropriateness to certain applications. For instance, suppose we are trying to select from among four microprocessors the one that is best suited for image processing applications. Since many factors, including performance, cost, availability, and software, can affect this decision, coming up with a crisp mathematical model for all these attributes is complicated. Another consideration is that it is much easier to compare these microprocessors subjectively in pairs rather than all four at one time. Suppose the design team is polled to determine which of the four microprocessors, labeled x_1 , x_2 , x_3 , and x_4 , is the most preferred when considered as a group rather than when considered as pairs. First, pairwise membership functions are determined. These represent the subjective measurement of the appropriateness of each microprocessor when compared only to one another. The following pairwise functions are determined:

 $f_{x_1}(x_1) = 1, \quad f_{x_1}(x_2) = 0.5, \quad f_{x_1}(x_3) = 0.3, \quad \frac{f_{x_1}(x_4)}{f_{x_1}(x_4)} = 0.2.$ $f_{x_2}(x_1) = 0.7, \quad f_{x_2}(x_2) = 1, \quad f_{x_2}(x_3) = 0.8, \quad f_{x_2}(x_4) = 0.9.$ $f_{x_3}(x_1) = 0.5, \quad f_{x_3}(x_2) = 0.3, \quad f_{x_3}(x_3) = 1, \quad f_{x_3}(x_4) = 0.7.$ $f_{x_4}(x_1) = 0.3, \quad f_{x_4}(x_2) = 0.1, \quad f_{x_4}(x_3) = 0.3, \quad f_{x_4}(x_4) = 1.$

• Then, the relativity values are:

To determine the overall ranking, we need to find the smallest value in each of the rows of the C matrix.

The order from best to worst is x_1 , x_4 , x_3 , and x_2 .

$$f(x_{2}/x_{3}) = \frac{f_{x_{3}}(x_{2})}{\max(f_{x_{3}}(x_{2})_{3}f_{x_{2}}(x_{3})} = \frac{.3}{\max(.3,8)} = \frac{.3}{.3} = .375$$

$$f(x_{i} \mid x_{j}) = f(ith \text{ row } \mid jth \text{ column})$$

$$x_{1} \quad x_{2} \quad x_{3} \quad x_{4}$$

$$x_{1} \quad x_{2} \quad x_{3} \quad x_{4}$$

$$x_{1} \quad x_{2} \quad x_{3} \quad x_{4}$$

$$0.71 \quad 1 \quad 0.38 \quad 0.11$$

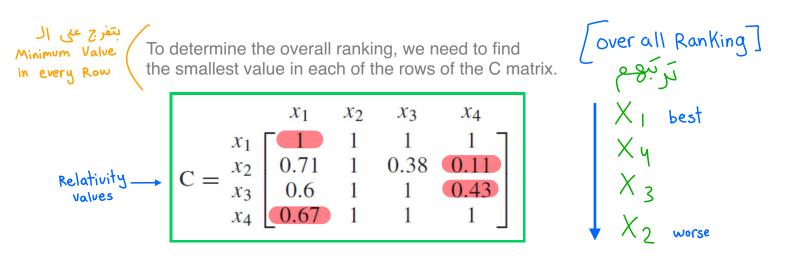
$$0.6 \quad 1 \quad 1 \quad 0.43$$

$$0.67 \quad 1 \quad 1 \quad 1$$

$$(Diagonal \ J)$$

$$f(x/y) = \frac{f_y(x)}{\max(f_y(x)_{,j}f_x(y))}$$

$$\frac{f(x_1/x_1)}{f_{x_1}(x_1)} = \frac{f_{x_2}(x_1)}{\max(f_{x_2}(x_1)_{,j}f_{x_1}(x_2))} = \frac{.7}{\max(.7,.5)} = 1$$
Prefrence of x_1 over x_2



> في أجماع وكايوجر أنثي مح وأنثي غلط

Self Study (contains things from Linear) [from book]

Preference and Consensus

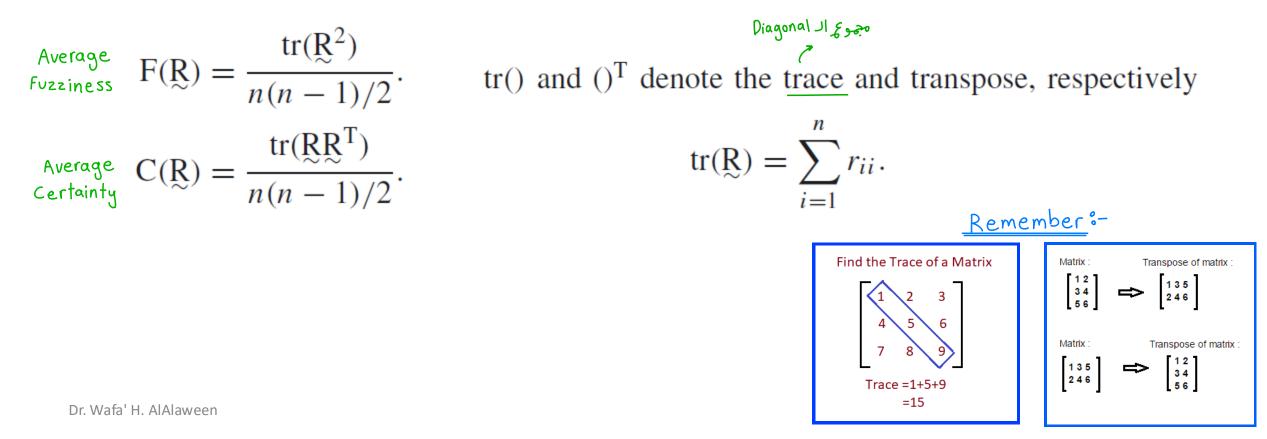
- The goal of group decision making typically is to arrive at a consensus concerning a desired action or alternative from among those considered in the decision process.
- The individual preferences of those in the decision group are collected to form a group metric whose properties are used to produce a scalar measure of "degree of consensus."
- First, we need to define a reciprocal relation as a fuzzy relation:

$$\begin{array}{cccc} & & & & & & \\ A_1 & A_2 & A_3 & & & option & \\ A_1 & & & & \\ A_2 & & & & \\ A_2 & & & & \\ A_3 & & & & \\ A_3 & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & \\ A_3 & & & & \\ \end{array}} \xrightarrow{} \begin{array}{c} & & & & & & \\ o & & & & \\ A_3 & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & \\ A_3 & & & & \\ \end{array}} \xrightarrow{} \begin{array}{c} & & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ o & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} & & & & & \\ \end{array} \xrightarrow{} \begin{array}{c} &$$

ما يقدر السوعي matrix تربيع إلا إذا كانت Square

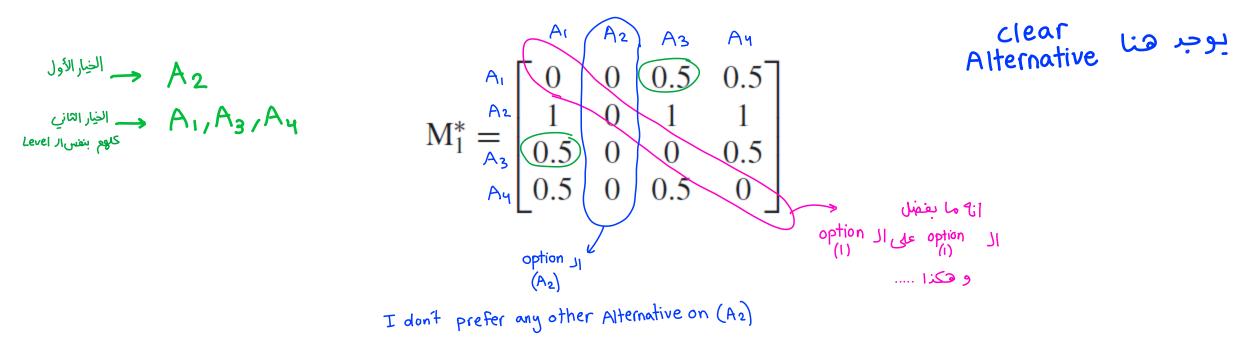
Continue...

• Two common measures of preference are defined here as average fuzziness and average certainty:



• Three types of consensus:

1. Type I consensus: is a consensus in which there is one clear choice, and the remaining alternatives all have equal secondary preference.

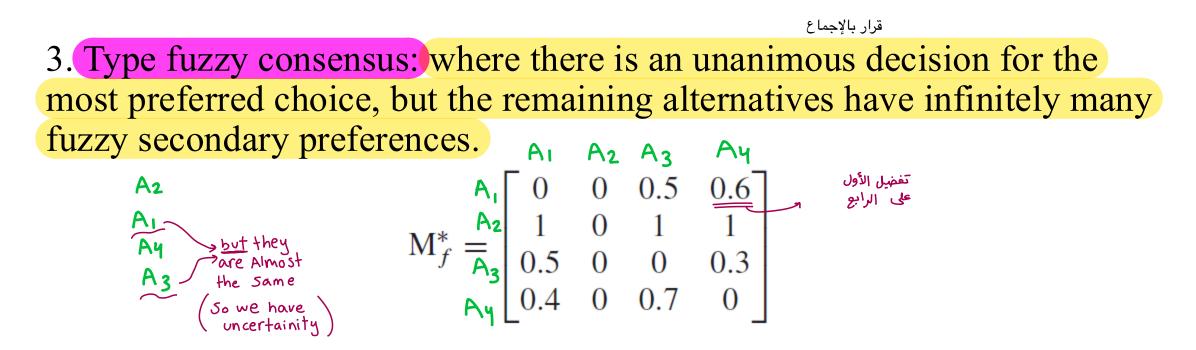


There is a clear choice and then we don't Know the order

2. Type II consensus: there is one clear choice, but the remaining alternatives all have definite secondary preference.

e my prefered choice		_			_
my prefered choice من مع الأكيد A2 هو خياري الأول على الأكيد		$\begin{bmatrix} 0 \end{bmatrix}$	0	1	0
Relation I prefer Alon A3	$M_{2}^{*} =$	1	0	1	1
I prefer Azon Ay	$\mathbf{w}_2 =$	0	0	0	1
I prefer Ay on Ai		1	0	0	0

where alternative 2 has a clear consensus, but where there is no clear ordering after the first choice because alternative 1 is preferred to alternative 3, 3 to 4, but alternative 4 is preferred to alternative 1.



The matrix shown here has a clear choice for alternative 2, but the other secondary preferences are fuzzy to various degrees.

• Think about the cardinalities of these matrices.

$$\begin{vmatrix} \mathbf{M}_1^* \end{vmatrix} = n & \text{(Type I)} \\ \begin{vmatrix} \mathbf{M}_2^* \end{vmatrix} = \left(2^{(n^2 - 3n + 2)/2} \right) (n) & \text{(Type II)} \\ \begin{vmatrix} \mathbf{M}_f^* \end{vmatrix} = \infty & \text{(Type fuzzy)} \end{aligned}$$

• Distance to consensus metric can be defined as follows:

$$m(\underline{R}) = 1 - (2C(\underline{R}) - 1)^{1/2}$$

 $m(\underline{R}) = 1 - (2/n)^{1/2}$ for a Type I (M^{*}₁) consensus relation $m(\underline{\tilde{R}}) = 0$ for a Type II (M^{*}₂) consensus relation.

• Question: when does $m(M_1^*)$ equal $m(M_2^*)$? when the (ardinality is $2 \rightarrow (n=2)$

example AI A2 AI O A2 I do prefer A2 on AI A2 I do prefer A2 on AI A2 I do prefer A2 on AI

Multi-Objective Decision Making



- Decisions are, more often than not, made in an environment where many objectives need to be considered.
- Two primary issues in multi-objective decision making are to acquire meaningful information regarding the satisfaction of the objectives by the various choices and to rank the relative importance of each of the objectives.
- To evaluate the alternatives, the objectives are usually combined. This process requires subjective information from the decision authority concerning the importance of each objective.

- Definitions:
- n alternatives: $A = \{a_1, a_2, \dots, a_n\}$, r objectives: $O = \{O_1, O_2, \dots, O_r\}$
- Then the degree of membership of alternative a in O_i, denoted $\mu_{Oi}(a)$, is the degree to which alternative a satisfies the criteria specified for this objective.
- We seek a decision function that simultaneously satisfies all of the decision objectives; hence, the decision function, D, is given by the intersection of all the objective sets:

 $\mathbf{D} = \mathbf{O}_1 \cap \mathbf{O}_2 \cap \cdots \cap \mathbf{O}_r$

• The grade of membership that the decision function, D, has for each alternative a is given as:

for a specific Alternative we take the Minimum value for this Alternative with respect to different objectives

$$\mu_{\rm D}(a) = \min[\mu_{\rm O_1}(a), \, \mu_{\rm O_2}(a), \, \dots, \, \mu_{\rm O_r}(a)]$$

• The optimum decision will then be the alternative that satisfies:

Now we will have one value for each Alternative and we will choose the (Max) Membership Degree

$$\mu_{\mathrm{D}}(a^*) = \max_{a \in \mathrm{A}}(\mu_{\mathrm{D}}(a))$$

• When each objective is associated with a weight expressing its importance, the decision can be given as follows:

 $\mathbf{D} = \mathbf{M}(\mathbf{O}_1, b_1) \cap \mathbf{M}(\mathbf{O}_2, b_2) \cap \dots \cap \mathbf{M}(\mathbf{O}_r, b_r)$

• Implication is the operation that relates the objective and its importance:

$$M(O_{i}(a), b_{i}) = b_{i} \longrightarrow O_{i}(a) = \overline{b_{i}} \bigvee_{j \in \mathbb{I}} O_{i}(a)$$

$$D = \bigcap_{i=1}^{r} (\overline{b_{i}} \cup O_{i})$$

$$C_{i} = \overline{b_{i}} \cup O_{i},$$

$$\mu_{C_{i}}(a) = \max_{i=1}^{r} [\mu_{\overline{b_{i}}}(a), \mu_{O_{i}}(a)]$$

Example: A geotechnical engineer on a construction project must prevent a large mass of soil from sliding into a building site during construction and must retain this mass of soil indefinitely after construction to maintain stability of the area around a new facility to be constructed on the site. The engineer therefore must decide which type of retaining wall design to select for the project. Among the many alternative designs available, the engineer reduces the list of candidate retaining wall designs to three: (1) a mechanically stabilized embankment (MSE) wall, (2) a mass concrete spread wall (Conc), and (3) a gabion (Gab) wall. The owner of the facility (the decision maker) has defined four objectives that impact the decision: (1) the cost of the wall (Cost), (2) the maintainability (Main) of the wall, (3) whether the design is a standard one (SD), and (4) the environmental (Env) impact of the wall. Moreover, the owner also decides to rank the preferences for these objectives on the unit interval. Hence, the engineer sets up the problem as follows:

A = {MSE, Conc, Gab} = { a_1, a_2, a_3 }. O = {Cost, Main, SD, Env} = {O₁, O₂, O₃, O₄}. P = { b_1, b_2, b_3, b_4 } \rightarrow [0, 1]. Every objective the Range for the weight the weights

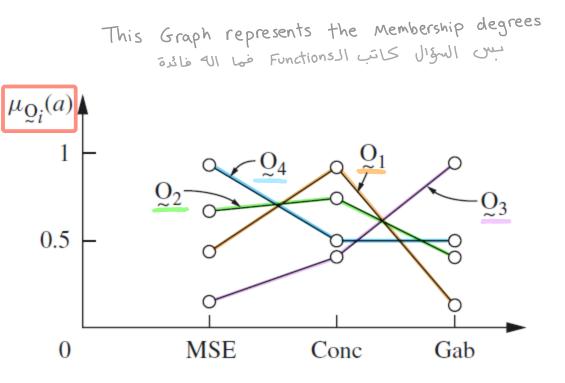
• From previous experience with various wall designs, the engineer first rates the retaining walls with respect to the objectives, given here. These ratings are fuzzy sets expressed as follows:

$$\sum_{\substack{\text{Degree}\\\text{Degree}\\\text{Degree}}}^{\text{Membership}} \underbrace{Q_1} = \left\{ \frac{0.4}{\text{MSE}} + \frac{1}{\text{Conc}} + \frac{0.1}{\text{Gab}} \right\}.$$

$$M_{\text{aintainability}} \underbrace{Q_2}_{\text{Objective}} = \left\{ \frac{0.7}{\text{MSE}} + \frac{0.8}{\text{Conc}} + \frac{0.4}{\text{Gab}} \right\}.$$

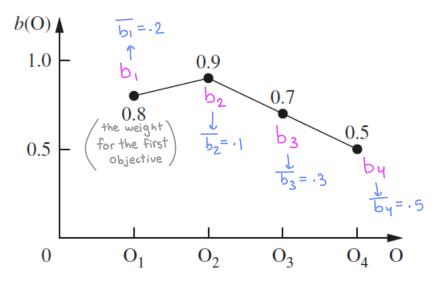
$$S_{\text{tandard}} \underbrace{Q_3}_{\text{objective}} = \left\{ \frac{0.2}{\text{MSE}} + \frac{0.4}{\text{Conc}} + \frac{1}{\text{Gab}} \right\}.$$

$$E_{\text{nviromental}} \underbrace{Q_4}_{\text{objective}} = \left\{ \frac{1}{\text{MSE}} + \frac{0.5}{\text{Conc}} + \frac{0.5}{\text{Gab}} \right\}.$$



Continue... Our Goal is to Choose the best Alternative

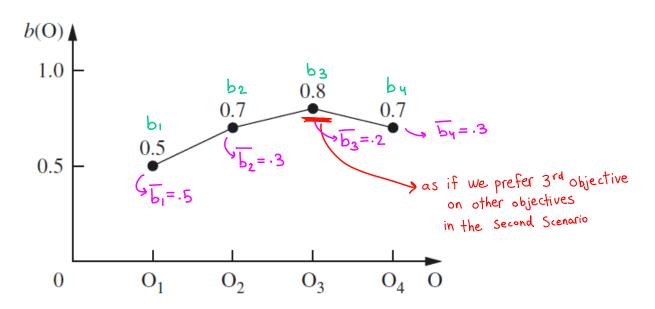
• The engineer wishes to investigate two decision scenarios. Each scenario propagates a different set of preferences from the owner, who wishes to determine the sensitivity of the optimum solutions to the preference ratings. In the first scenario, the owner lists the preferences for each of the four objectives:



• Let's evaluate the three alternatives:

 $D(a_1) = D(MSE) = (\overline{b}_1 \cup O_1) \cap (\overline{b}_2 \cup O_2) \cap (\overline{b}_3 \cup O_3) \cap (\overline{b}_4 \cup O_4)$ $M_{\text{ex}} \rightarrow = (0.2 \lor 0.4) \land (0.1 \lor 0.7) \land (0.3 \lor 0.2) \land (0.5 \lor 1)$ then $\rightarrow = 0.4 \land 0.7 \land 0.3 \land 1 = 0.3$ Membership Value for the first Alternative (MSE) with respect to All objectives $D(a_2) = D(Conc) = (0.2 \lor 1) \land (0.1 \lor 0.8) \land (0.3 \lor 0.4) \land (0.5 \lor 0.5)$ $= 1 \land 0.8 \land 0.4 \land 0.5 = 0.4$, we will select the second Alternative because it have the highest Membership Degree $D(a_3) = D(Gab) = (0.2 \lor 0.1) \land (0.1 \lor 0.4) \land (0.3 \lor 1) \land (0.5 \lor 0.5)$ $= 0.2 \land 0.4 \land 1 \land 0.5 = 0.2.$ $D^* = \max\{D(a_1), D(a_2), D(a_3)\} = \max\{0.3, 0.4, 0.2\} = 0.4.$

 In the second scenario the engineer was given a different set of preferences by the owner as follows:
 في هذه الحالة تم تغير الـ etites المحالة من الحالة من الحالة على المحالة المحالية المحالية



$$D(a_1) = D(MSE) = (\overline{b}_1 \cup O_1) \bigcap_{\text{Min}} (\overline{b}_2 \cup O_2) \bigcap_{\text{Min}} (\overline{b}_3 \cup O_3) \bigcap_{\text{Min}} (\overline{b}_4 \cup O_4)$$
$$= (0.5 \lor 0.4) \land (0.3 \lor 0.7) \land (0.2 \lor 0.2) \land (0.3 \lor 1)$$
$$= 0.5 \land 0.7 \land 0.2 \land 1 = 0.2.$$

 $D(a_2) = D(Conc) = (0.5 \lor 1) \land (0.3 \lor 0.8) \land (0.2 \lor 0.4) \land (0.3 \lor 0.5)$ = 1 \land 0.8 \land 0.4 \land 0.5 = 0.4. $D(a_3) = D(Gab) = (0.5 \lor 0.1) \land (0.3 \lor 0.4) \land (0.2 \lor 1) \land (0.3 \lor 0.5)$ = 0.5 \land 0.4 \land 1 \land 0.5 = 0.4.

There is a tie between alternative a₂ and a₃, what should we do in such a case? to break this Tie → Remove the Minimum Value from both of them and take the Second Minimum
 Dr. Wafa' H. AlAlaween

-> between 2nd and 3rd Alternative

• <u>Tie-breaking</u> procedure:

$$\hat{D}(x) = \min_{i \neq k} [C_i(x)]$$
 and $\hat{D}(y) = \min_{i \neq g} [C_i(y)]$

• If it persists:

$$\hat{\hat{D}}(x) = \min_{i \neq k, j} [C_i(x)]$$
 and $\hat{\hat{D}}(y) = \min_{i \neq g, h} [C_i(y)]$

• The tie-breaking procedure continues until an unambiguous optimum alternative emerges or all of the alternatives have been exhausted. In the latter case, some other tie-breaking procedure can be used.

• Step 1: $\hat{D}(a_2) = \hat{D}(\text{Conc}) = (0.5 \lor 1) \land (0.3 \lor 0.8) \land (0.3 \lor 0.5)$ $= 1 \land 0.8 \land 0.5 = 0.5.$ $\hat{D}(a_3) = \hat{D}(\text{Gab}) = (0.5 \lor 0.1) \land (0.2 \lor 1) \land (0.3 \lor 0.5)$ $= 0.5 \land 1 \land 0.5 = 0.5.$

• Step 2:
$$\hat{\hat{D}}(a_2) = \hat{\hat{D}}(\text{Conc}) = (0.5 \lor 1) \land (0.3 \lor 0.8) = 0.8.$$

 $\hat{\hat{D}}(a_3) = \hat{\hat{D}}(\text{Gab}) = (0.2 \lor 1) = 1.$

Fuzzy Bayesian Decision Method

it depends on the Probability of something taking place in the future

- Classical statistical decision making involves uncertainties in the future can be characterized probabilistically.
- The choice is predicated on information about the future, which is normally discretized into various "states of nature."
- Classical Bayesian decision methods presume that future states of nature can be characterized as probability events.
- Example: Consider the prediction of the annual demand of a product: it could be low, medium or high. These are vague.

For Example the State of Nature it will Rain Tomorrow it will Not Rain Tomorrow it will Not Rain Tomorrow ويدة و بحسب الر probability لكل وحدة

Continue...

• Let $S = \{s_1, s_2, ..., s_n\}$ be a set of possible states of nature, and the probabilities (prior probabilities) of these states:

$$\mathbf{P} = \{ p(s_1), p(s_2), \dots, p(s_n) \},$$
 where

$$($$
 مجوع ال probabilities يساوي $e^{|c_i|}$ p $(s_i) = 1$

- Assume that there are(m)<u>alternatives</u>, $A = \{a_1, a_2, \ldots, a_m\}$, and for each alternative a_j , a <u>utility value</u> (u_{ji}) is assigned when the future state of nature turns out to be state s_i .
- The expected utility associated with the jth alternative would be:

$$E(u_j) = \sum_{\substack{i=1\\ \text{visitive}}}^n u_{ji} p(s_i)$$
solution with ach Alternative value va

• The expected utility associated with the jth alternative would be:

$$E(u_j) = \sum_{i=1}^n u_{ji} p(s_i)$$

• The best alternative is the one with the maximum expected utility among all the alternatives, as follows:

$$E(u^*) = \max_{j} E(u_j)$$

Example: A geological engineer who has been asked by the chief executive officer (CEO) of a large oil firm to help make a decision about whether to drill for natural gas in a particular geographic region of north western New Mexico. There are only two states of nature regarding the existence of natural gas in the region:

States of \rightarrow s_1 = there is natural gas and s_2 = there is no natural gas From previous drilling information, the prior probabilities for each of these states is

Probabilities
$$\longrightarrow$$
 $p(s_1) = 0.5$ and $p(s_2) = 0.5$.

There are two alternatives in this decision:

Alternatives \longrightarrow $a_1 = drill$ for gas and $a_2 = do not drill for gas$

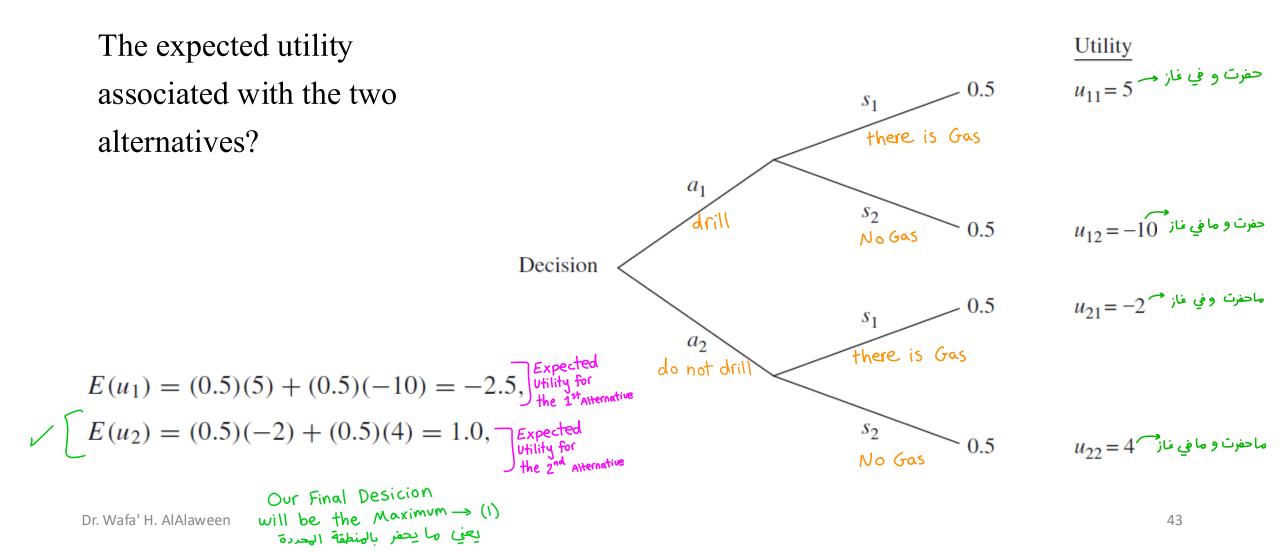
The CEO tells you that the best situation for the firm is to decide to drill for gas, and subsequently find that gas, indeed, was in the geologic formation. The CEO assesses this value (u_{11}) as +5 in nondimensional units; in this case, the CEO would have gambled (drilling costs big money) and won. Moreover, the CEO feels that the worst possible situation would be to drill for gas, and subsequently find that there was no gas in the area. Since this would cost time and money, the CEO determines that the value for this would be $u_{12} = -10$ units; the CEO would have gambled and lost-big. The other two utilities are assessed by the decision maker in nondimensional units as u_{21} =-2 and u_{22} =4. Hence, the utility matrix for this situation is given as

زي كأنا^وعم نتوقع الربح والخسارة المستقبل بس مش كأرقام) يعني زعي Utility

Utility

Values

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- Suppose some new information regarding the true states of nature S is available from r experiments or other observations and is collected in a data vector, X={x₁, x₂, ..., x_r}. This information can be used to update the prior probabilities.
- Thus, given that the piece of new information x_k is true, the probability that the true state of nature is s_i is $p(s_i|x_k)$. The updated probabilities are determined by Bayes's rule:

$$p(s_i \mid x_k) = \frac{p(x_k \mid s_i)}{p(x_k)} p(s_i)$$

• $p(x_k)$: is the marginal probability, given as follows:

$$p(x_k) = \sum_{i=1}^n p(x_k \mid s_i) \cdot p(s_i)$$

• Now the expected utility for the jth alternative, given the data x_k , is determined from the posterior probabilities:

$$E(u_{j} | x_{k}) = \sum_{i=1}^{n} u_{ji} p(s_{i} | x_{k})$$

• The maximum expected utility: $E(u^* | x_k) = \max_j E(u_j | x_k)$

• To determine the unconditional maximum expected utility, we need to weight each of the r conditional expected utilities by the respective marginal probabilities for each datum x_k , that is given as:

$$E(u_x^*) = \sum_{k=1}^r E(u^* | x_k) \cdot p(x_k)$$

• If there is some uncertainty about the new information, we call the information imperfect information. The value of this imperfect information, V(x), can be given as follows:

$$V(x) = E(u_x^*) - E(u^*)$$

• Perfect information is represented by posterior probabilities of 0 or 1:

$$p(s_i \mid x_k) = \begin{cases} 1\\ 0 \end{cases}$$

• For perfect information, the maximum expected utility is presented as:

$$E(u_{x_p}^*) = \sum_{k=1}^r E(u_{x_p}^* | x_k) p(x_k)$$

• The value of perfect information is: $V(x_p) = E(u_{x_p}^*) - E(u^*)$

• Continuation of the previous example: the CEO provides the utility matrix as follows:

u _{ji}	<i>s</i> ₁	<i>s</i> ₂
a_1	4	-2
<i>a</i> ₂	-1	2

• The CEO has asked you to collect new information by taking eight geological boring samples from the region being considered for drilling. You have a natural gas expert examine the results of these eight tests, and get the expert's opinions about the conditional probabilities in the form of a matrix:

<i>x</i> ₁	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅	x_6	<i>x</i> ₇	<i>x</i> ₈	
								Σ row = 1 Σ row = 1

• Moreover, you ask the natural gas expert for an assessment about how the conditional probabilities might change if they were perfect tests capable of providing perfect information. The expert gives you the matrix:

x_1	<i>x</i> ₂	<i>x</i> ₃	x_4	<i>x</i> ₅	x_6	<i>x</i> ₇	<i>x</i> ₈	
								Σ row = 1 Σ row = 1

• The expected utilities and maximum expected utility based just on prior probabilities are

$$E(a_1) = (4)(0.5) + (-2)(0.5) = 1.0.$$

 $E(a_1) = (-1)(0.5) + (2)(0.5) = 0.5.$
 $E(u^*) = 1;$ hence, you choose alternative a_1 , drill of natural gas.

• The marginal probabilities are calculated as follows:

 $p(x_1) = (0)(0.5) + (0.05)(0.5) = 0.025$ $p(x_k) = \sum_{i=1}^{n} p(x_k | s_i) \cdot p(s_i)$

	<i>x</i> ₁	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅	x_6	<i>x</i> ₇	<i>x</i> ₈	
$p(x_k \mid s_1) \\ p(x_k \mid s_2)$									Σ row = 1 Σ row = 1
$p(x_k)$	0.025	0.075	0.25	0.15	0.15	0.25	0.075	0.025	

• The posterior probabilities are calculated as follows:

$$p(s_1 \mid x_2) = \frac{0.05(0.5)}{0.075} = \frac{1}{3}, \qquad p(s_2 \mid x_2) = \frac{0.1(0.5)}{0.075} = \frac{2}{3}, \qquad p(s_i \mid x_k) = \frac{p(x_k \mid s_i)}{p(x_k)}p(s_i)$$
$$p(s_1 \mid x_6) = \frac{0.4(0.5)}{0.25} = \frac{4}{5}, \qquad p(s_2 \mid x_6) = \frac{0.1(0.5)}{0.25} = \frac{1}{5},$$

	x_1	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅	<i>x</i> ₆	<i>x</i> ₇	<i>x</i> ₈
$p(s_1 \mid x_k)$	0	$\frac{1}{3}$	$\frac{1}{5}$	$\frac{1}{3}$	$\frac{2}{3}$	$\frac{4}{5}$	$\frac{2}{3}$	1
$p(s_2 \mid x_k)$	1	$\frac{2}{3}$	$\frac{4}{5}$	$\frac{2}{3}$	$\frac{1}{3}$	$\frac{1}{5}$	$\frac{1}{3}$	0

• The conditional expected utilities are calculated as follows:

 $E(u_1 \mid x_3) = (\frac{1}{5})(4) + (\frac{4}{5})(-2) = -\frac{4}{5} \text{ and } E(u_2 \mid x_3) = (\frac{1}{5})(-1) + (\frac{4}{5})(2) = \frac{7}{5} \quad E(u_j \mid x_k) = \sum_{i=1}^{n} u_{ji} p(s_i \mid x_k)$ $E(u^* \mid x_k) = \max_j E(u_j \mid x_k)$

	x_1	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅	<i>x</i> ₆	<i>x</i> ₇	<i>x</i> ₈
$p(s_1 \mid x_k)$	0	$\frac{1}{3}$	$\frac{1}{5}$	$\frac{1}{3}$	$\frac{2}{3}$	$\frac{4}{5}$	$\frac{2}{3}$	1
$p(s_2 \mid x_k)$	1	$\frac{2}{3}$	$\frac{4}{5}$	$\frac{2}{3}$	$\frac{1}{3}$	$\frac{1}{5}$	$\frac{1}{3}$	0
$p(x_k)$	0.025	0.075	0.25	0.15	0.15	0.25	0.075	0.025
$E(u^* x_k)$	2	1	$\frac{7}{5}$	1	2	$\frac{14}{5}$	2	4
$a_j \mid x_k$	a_2	a_2	a_2	a_2	a_1	a_1	a_1	a_1

• The overall unconditional expected utility for imperfect information is:

 $E(u_x^*) = (0.025)(2) + (0.075)(1) + \dots + (0.025)(4) = 1.875$

 $E(u_x^*) = \sum_{k=1}^{r} E(u^* | x_k) \cdot p(x_k)$

• The value of the new imperfect information is:

$$V(x) = E(u_x^*) - E(u^*) = 1.875 - 1 = 0.875.$$

• Finally, which alternative?

• For perfect information:

	x_1	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅	<i>x</i> ₆	<i>x</i> ₇	<i>x</i> ₈
$p(s_1 \mid x_k)$	0	0	0	0	1	1	1	1
$p(s_2 \mid x_k)$	1	1	1	1	0	0	0	0
$p(x_k)$	0.05	0.1	0.25	0.1	0.1	0.25	0.1	0.05
$E(u^* \mid x_k)$	2	2	2	2	4	4	4	4
$a_j \mid x_k$	a_2	a_2	a_2	a_2	a_1	a_1	a_1	a_1

 $E(u_{x_p}^*) = (0.05)(2) + (0.1)(2) + \dots + (0.05)(4)$

$$V(x_p) = E(u_{x_p}^*) - E(u^*) = 3 - 1 = 2.0.$$

- What about fuzzy information!
- Suppose the new information, $X = \{x_1, x_2, ..., x_r\}$, is a universe of discourse in the units appropriate for the new information.
- Let's define fuzzy set (\underline{M}) on the information (e.g. "good", "moderate" information).
- Thus, it has a membership function $(\mu_{M}(x_{k}))$.
- The probability of a fuzzy set:

$$P(\underline{\mathbf{M}}) = \sum_{k=1}^{r} \mu_{\underline{\mathbf{M}}}(x_k) p(x_k)$$

• The posterior probability of s_i given fuzzy information \underbrace{M}_{r} can be written as:

$$P(s_i \mid \underline{\mathsf{M}}) = \frac{\sum_{k=1}^{r} p(x_k \mid s_i) \mu_{\underline{\mathsf{M}}}(x_k) p(s_i)}{P(\underline{\mathsf{M}})} = \frac{P(\underline{\mathsf{M}} \mid s_i) p(s_i)}{P(\underline{\mathsf{M}})},$$
$$p(\underline{\mathsf{M}} \mid s_i) = \sum_{k=1}^{r} p(x_k \mid s_i) \mu_{\underline{\mathsf{M}}}(x_k)$$

• If the fuzzy events on the new information universe are orthogonal, the Bayesian approach can be extended to consider fuzzy information:

$$E(u_j \mid \underline{M}_t) = \sum_{i=1}^n u_{ij} \cdot p(s_i \mid \underline{M}_t).$$
$$E(u^* \mid \underline{M}_t) = \max_j E(u_j \mid \underline{M}_t).$$
$$E(u^*_{\Phi}) = \sum_{t=1}^g E(u^* \mid \underline{M}_t) \cdot p(\underline{M}_t).$$

• The value of the fuzzy information: $V(\Phi) = E(u_{\Phi}^*) - E(u^*)$

• Continuation of the example: Suppose the eight data samples are from overlapping, ill-defined parcels within the drilling property. The orthogonal fuzzy information system:

 $\Phi = \{ \underbrace{M_1, M_2, M_3}_{} \} = \{ fuzzy \text{ parcel } 1, fuzzy \text{ parcel } 2, fuzzy \text{ parcel } 3 \}$

• The membership functions:

	x_1	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	x_5	x_6	<i>x</i> ₇	x_8
$\mu_{\mathbf{M}_1}(x_k)$	1	1	0.5	0	0	0	0	0
$\mu_{\mathbf{M}_2}(x_k)$	0	0	0.5	1	1	0.5	0	0
$\mu_{M_3}^{\sim}(x_k)$	0	0	0	0	0	0.5	1	1
$P(x_k)$	0.025	0.075	0.25	0.15	0.15	0.25	0.075	0.025

• The marginal probabilities for the fuzzy events:

$$P(\underline{M}) = \sum_{k=1}^{r} \mu_{\underline{M}}(x_k) p(x_k) \qquad p(\underline{M}_1) = 0.225, \qquad p(\underline{M}_2) = 0.55, \qquad p(\underline{M}_3) = 0.225$$

• The fuzzy conditional probabilities:

$r(\mathbf{M} \mid \mathbf{z}) = \sum_{r=1}^{r} r(r \mid \mathbf{z}) r(r)$	$p(\mathbf{M}_1 s_1) = 0.1,$	$p(\mathbf{\underline{M}}_2 s_1) = 0.55,$	$p(\mathbf{M}_3 s_1) = 0.35;$
$p(\mathbf{M} \mid s_i) = \sum_{k=1}^{\infty} p(x_k \mid s_i) \mu_{\mathbf{M}}(x_k)$	$p(\underset{\sim}{\mathbf{M}}_1 s_2) = 0.35,$	$p(\underset{\sim}{\mathbf{M}_2} \mid s_2) = 0.55,$	$p(\underset{\sim}{\mathbf{M}}_3 s_2) = 0.1;$

<i>x</i> ₁	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅	x_6	<i>x</i> ₇	<i>x</i> ₈	
								Σ row = 1 Σ row = 1

• The fuzzy posterior probabilities:

 $P(s_i \mid \underline{M}) = \frac{\sum_{k=1}^{r} p(x_k \mid s_i) \mu_{\underline{M}}(x_k) p(s_i)}{P(\underline{M})} = \frac{P(\underline{M} \mid s_i) p(s_i)}{P(\underline{M})},$ $p(s_1 \mid \underline{M}_1) = 0.222, \qquad p(s_1 \mid \underline{M}_2) = 0.5, \qquad p(s_1 \mid \underline{M}_3) = 0.778;$ $p(s_2 \mid \underline{M}_1) = 0.778, \qquad p(s_2 \mid \underline{M}_2) = 0.5, \qquad p(s_2 \mid \underline{M}_3) = 0.222.$

• The conditional fuzzy expected utilities:

$$\underbrace{M_1:}_{E(u_1 \mid M_1) = (4)(0.222) + (-2)(0.778) = -0.668}_{E(u_2 \mid M_1) = (-1)(0.222) + (2)(0.778) = 1.334;}$$

$$\begin{split} \mathbf{M}_2: & E(u_1 \mid \mathbf{M}_2) = (4) \ (0.5) + (-2) \ (0.5) = 1.0 \\ & E(u_2 \mid \mathbf{M}_2) = (-1) \ (0.5) + (2) \ (0.5) = 0.5; \\ \mathbf{M}_3: & E(u_1 \mid \mathbf{M}_3) = (4) (0.778) + (-2) (0.222) = 2.668 \end{split}$$

$$E(u_2 | \mathbf{M}_3) = (-1)(0.778) + (2)(0.222) = -0.334;$$

• The maximum expected utility and the value of the fuzzy information:

$$E(u_{\Phi}^*) = (0.225)(1.334) + (0.55)(1) + (0.225)(2.668) = 1.45;$$

$$V(\Phi) = 1.45 - 1 = 0.45$$

Decision Making Under Fuzzy States and Fuzzy Actions

- The Bayesian method can be further extended to include the possibility that the states of nature are fuzzy and the decision makers' alternatives are also fuzzy.
- Example: Building dike to prevent flooding:
 - 1. build a permanent dike (A_1)
 - 2. build a temporary dike (A_2)
 - 3. do not build a dike (A_3) .

• The expected utility of fuzzy alternative A_j :

$$E(u_j) = \sum_{s=1}^n \mu_{js} p(\underline{\mathbf{F}}_s), \qquad p(\underline{\mathbf{F}}_s) = \sum_{i=1}^n \mu_{\underline{\mathbf{F}}_s}(s_i) p(s_i)$$

- The maximum utility: $E(u^*) = \max_i E(u_j)$.
- The posterior probabilities of fuzzy states *E*_s given probabilistic information:

$$p(\underline{\mathbb{F}}_s \mid x_k) = \frac{\sum_{i=1}^n \mu_{\underline{\mathbb{F}}_s}(s_i) p(x_k \mid s_i) p(s_i)}{p(x_k)}.$$

• The expected utility given probabilistic information:

$$E(u_j \mid x_k) = \sum_{s=1}^n u_{js} p(\underline{F}_s \mid x_k),$$

• The posterior probabilities of fuzzy states \mathbb{E}_s given probabilistic information:

$$p(\mathbf{E}_{s} | \mathbf{M}_{t}) = \frac{\sum_{i=1}^{n} \sum_{i=1}^{r} \mu_{\mathbf{E}_{s}}(s_{i}) \mu_{\mathbf{M}_{t}}(x_{k}) p(x_{k} | s_{i}) p(s_{i})}{\sum_{k=1}^{r} \mu_{\mathbf{M}_{t}}(x_{k}) p(x_{k})}.$$

• The expected utility given fuzzy information:

$$E(u_j \mid \underline{\mathbf{M}}_t) = \sum_{s=1}^n u_{js} \, p(\underline{\mathbf{F}}_s \mid \underline{\mathbf{M}}_t)$$

• The maximum conditional expected utility for probabilistic and fuzzy information:

$$E(u_{x_k}^*) = \max_j E(u_j \mid x_k).$$
$$E(u_{\underline{M}_t}^*) = \max_j E(u_j \mid \underline{M}_t).$$

• The unconditional expected utility for fuzzy states and probabilistic information or fuzzy information:

$$E(u_x^*) = \sum_{k=1}' E(u_{x_k}^*) p(x_k).$$

$$E(u_{\Phi}^*) = \sum_{t=1}^{\circ} E(u_{\mathbf{M}_t}^*) p(\mathbf{M}_t).$$

• The value of the fuzzy information:

$$V(x) = E(u_x^*) - E(u^*)$$
$$V(\Phi) = E(u_{\Phi}^*) - E(u^*).$$

Example

One of the decisions your project team faces with each new computer product is what type of printed circuit board (PCB) will be required for the unit. Depending on the density of tracks (metal interconnect traces on the PCB that act like wire to connect components together), which is related to the density of the components, we may use a single-layer PCB, a double-layer PCB, a four-layer PCB, or a six-layer PCB. A PCB layer is a two-dimensional plane of interconnecting tracks. The number of layers on a PCB is the number of parallel interconnection layers in the PCB. The greater the density of the interconnections in the design, the greater the number of layers required to fit the design onto a PCB of given size. One measure of board track density is the number of nodes required in the design. A node is created at a location in the circuit where two or more lines (wires, tracks) meet. The decision process will comprise the following steps.

1. Define the fuzzy states of nature: The density of the PCB is defined as three fuzzy sets on the singleton states $S=(s_1, s_2, s_3, s_4, s_5)=(s_i)$, i = 1, 2, ..., 5, where i defines the states in terms of a percentage of our most dense (in terms of components and interconnections) PCB. So, your team defines $s_1=20\%$, $s_2=40\%$, $s_3=60\%$, $s_4=80\%$ and $s_5=100\%$ of the density of the densest PCB; these are singletons on the universe of relative densities. Further, you define the following three fuzzy states that are defined on the universe of relative density states S: $E_1 = \text{low-density PCB}$

 \underline{F}_2 = medium-density PCB

 \underline{F}_3 = high-density PCB.

2. Define fuzzy alternatives: Your decision alternative will represent the type of the PCB we decide to use as follows (these actions are admittedly not very fuzzy, but in general they can be):

 $A_1 =$ use a 2-layer PCB for the new design $A_2 =$ use a 4-layer PCB for the new design $A_3 =$ use a 6-layer PCB for the new design.

3. Define new data samples (information): The universe $X=(x_1, x_2, ..., x_5)$ represents the "measured number of nodes in the PCB schematic"; that is, the additional information is the measured number of nodes of the schematic, which can be calculated by a schematic capture system. You propose the following discrete values for number of nodes:

$$x_1 = 100 \text{ nodes}$$

$$x_2 = 200 \text{ nodes}$$

- $x_3 = 300$ nodes
- $x_4 = 400$ nodes
- $x_5 = 500$ nodes.

4. Define orthogonal fuzzy information system: You determine that the ambiguity in defining the density of nodes can be characterized by three linguistic information sets as (M_1, M_2, M_3) , where

$$\begin{split} & \underbrace{M_1} = \text{low number of nodes on PCB [generally < 300 nodes]} \\ & \underbrace{M_2} = \text{average (medium) number of nodes on PCB [about 300 nodes]} \\ & \underbrace{M_3} = \text{high number of nodes on PCB [generally > 300 nodes]}. \end{split}$$

5. Define the prior probabilities: The prior probabilities of the singleton densities (states) are as follows:

 $p(s_1) = 0.2$ $p(s_2) = 0.3$ $p(s_3) = 0.3$ $p(s_4) = 0.1$ $p(s_5) = 0.1.$

The preceding numbers indicate that moderately dense boards are the most probable, followed by low-density boards, and high- to very high-density boards are the least probable.

6. Identify the utility values: You propose the nondimensional utility values shown in the table below to represent the fuzzy alternative-fuzzy state relationships.

Utilities	for	fuzzy	states	and	alternatives.
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	₽ 1	₽ 2	₽ 3
A_1	10	3	0
A_2	4	9	6
$\begin{array}{c} A_1\\ \widetilde{A}_2\\ \widetilde{A}_3\\ \end{array}$	1	7	10

7. Define membership values for each orthogonal fuzzy state.

	<i>s</i> ₁	<i>s</i> ₂	<i>s</i> ₃	<i>s</i> ₄	<i>s</i> ₅
$\underset{\sim}{E_1}$	1	0.5	0	0	0
$\underset{\sim}{E_2}$	0	0.5	1	0.5	0
\widetilde{E}_3	0	0	0	0.5	1

Orthogonal fuzzy sets for fuzzy states.

8. Define membership values for each orthogonal fuzzy set on the fuzzy information system:

	x_1	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅
\underline{M}_1	1	0.4	0	0	0
\widetilde{M}_2	0	0.6	1	0.6	0
\widetilde{M}_3	0	0	0	0.4	1

Orthogonal fuzzy sets for fuzzy information.

9. Define the conditional probabilities (likelihood values) for the uncertain information. The table below shows the conditional probabilities for uncertain (probabilistic) information.

	x_1	x_2	<i>x</i> ₃	x_4	<i>x</i> ₅
$p(x_k \mid s_1)$	0.44	0.35	0.17	0.04	0
$p(x_k \mid s_2)$	0.26	0.32	0.26	0.13	0.03
$p(x_k \mid s_3)$	0.12	0.23	0.30	0.23	0.12
$p(x_k \mid s_4)$	0.03	0.13	0.26	0.32	0.26
$p(x_k \mid s_5)$	0	0.04	0.17	0.35	0.44

Conditional probabilities $p(x_k | s_i)$ for uncertain information.

10. Define the conditional probabilities (likelihood values) for the probabilistic perfect information. The table below shows the conditional probabilities for probabilistic perfect information.

	x_1	<i>x</i> ₂	<i>x</i> ₃	x_4	<i>x</i> ₅
$p(x_k \mid s_1)$	1	0	0	0	0
$p(x_k \mid s_2)$	0	1	0	0	0
$p(x_k \mid s_3)$	0	0	1	0	0
$p(x_k \mid s_4)$	0	0	0	1	0
$p(x_k \mid s_5)$	0	0	0	0	1

Conditional probabilities $p(x_k | s_i)$ for fuzzy perfect information.

Calculation: Crisp states and actions

(i) Utility and optimum decision given no information.

The nondimensional utility values for this nonfuzzy state situation are given as follows:

	<i>s</i> ₁	<i>s</i> ₂	<i>s</i> ₃	<i>s</i> ₄	\$5
$\mathop{\mathrm{A}}_{pprox 1}$	10	8	6	2	0
\widetilde{A}_2	4	6	9	6	4
A_3	1	2	6	8	10

Utility values for crisp states.

 $E(u_1) = 6.4$

 $E(u_2) = 6.3$

 $E(u_3) = 4.4$

(ii) Utility and optimal decision given uncertain and perfect information.(a) Probabilistic (uncertain) information:

Calculate the unconditional		r.	x_2	<i>x</i> ₃	x_4	<i>x</i> ₅
expected utility?		x_1	x 2	л 3	~4	_
	$p(x_k)$	0.205	0.252	0.245	0.183	0.115
7.37	$p(s_1 \mid x_k)$	0.429	0.278	0.139	0.044	0.0
The value of the uncertain	$p(s_2 \mid x_k)$	0.380	0.381	0.318	0.213	0.078
	$p(s_3 \mid x_k)$	0.176	0.274	0.367	0.377	0.313
information?	$p(s_4 \mid x_k)$	0.015	0.052	0.106	0.175	0.226
V(x) = 7.37 - 6.4 = 0.97.	$p(s_5 \mid x_k)$	0.0	0.016	0.069	0.191	0.383
V(x) = 7.57 - 0.4 = 0.97.	$E(u^* \mid x_k)$	8.42	7.47	6.68	6.66	7.67
	$a_j \mid a_k$	1	1	2	2	3

(ii) Utility and optimal decision given uncertain and perfect information.(b) Probabilistic perfect information:

Calculate the unconditiona	al	<i>x</i> ₁	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅
expected utility?			_	_	-	
2 O	$p(x_k)$	0.20	0.30	0.30	0.10	0.10
8.9	$p(s_1 \mid x_k)$	1.0	0.0	0.0	0.0	0.0
The value of uncertain	$p(s_2 \mid x_k)$	0.0	1.0	0.0	0.0	0.0
	$p(s_3 \mid x_k)$	0.0	0.0	1.0	0.0	0.0
Information?	$p(s_4 \mid x_k)$	0.0	0.0	0.0	1.0	0.0
	$p(s_5 \mid x_k)$	0.0	0.0	0.0	0.0	1.0
$V(x_p) = 8.9 - 6.4 = 2.5$	$E(u^* \mid x_k)$	10.0	8.0	9.0	8.0	10.0
	$a_j \mid a_k$	1	1	2	3	3

Calculation: Fuzzy states and actions

(i) Utility and optimum decision given no information.

 $p(\mathbf{E}_1) = (1)(0.2) + (0.5)(0.3) + (0)(0.3) + (0)(0.1) + (0)(0.1)$ = 0.35.

$$p(\mathbf{F}_s) = \sum_{i=1}^n \mu_{\mathbf{F}_s}(s_i) p(s_i)$$

 $p(E_2) = 0.5$ and $p(E_3) = 0.15$

Orthogonal fuzzy sets for fuzzy states.

	<i>s</i> ₁	<i>s</i> ₂	<i>s</i> ₃	<i>s</i> ₄	<i>s</i> ₅
$\underset{\sim}{E}_{1}$	1	0.5	0	0	0
\widetilde{F}_2	0	0.5	1	0.5	0
\widetilde{E}_3	0	0	0	0.5	1

Calculation: Fuzzy states and actions

(i) Utility and optimum decision given no information.The expected utility:

$$E(u_{j}) = \sum_{s=1}^{n} \mu_{js} p(\underline{F}_{s}), \qquad E(u_{j}) = \begin{bmatrix} 5\\ 6.8\\ 5.35 \end{bmatrix}$$

The optimum expected utility of the fuzzy alternatives for the case of no information is 6.8, thus alternative 2 is the optimum.

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(a) Probabilistic (uncertain) information:

$$p(\mathbf{E}_{s} | x_{k}) = \frac{\sum_{i=1}^{n} \mu_{\mathbf{E}_{s}}(s_{i}) p(x_{k} | s_{i}) p(s_{i})}{p(x_{k})} \qquad p(\mathbf{E}_{1} | x_{1}) = \frac{(1)(0.44)(0.2) + (0.5)(0.26)(0.3)}{0.205} = 0.620.$$

$p(s_1) = 0.2$	Ortho	Orthogonal fuzzy sets for fuzzy states.			Conditional	probabilitie	es $p(x_k \mid s_i)$) for uncert	ain inform	ation.		
$p(s_1) = 0.2$ $p(s_2) = 0.3$		<i>s</i> ₁	<i>s</i> ₂	<i>s</i> ₃	<i>s</i> ₄	<i>s</i> ₅		<i>x</i> ₁	x_2	<i>x</i> ₃	<i>x</i> ₄	x_5
$p(s_3) = 0.3$		1	0.5	0	0	0	$p(x_k \mid s_1)$	0.44	0.35	0.17	0.04	0
•	$\sum_{i=1}^{n}$	1	0.5	0	0	0	$p(x_k \mid s_2)$	0.26	0.32	0.26	0.13	0.03
$p(s_4) = 0.1$	E_2	0	0.5	1	0.5	0	$p(x_k \mid s_3)$	0.12	0.23	0.30	0.23	0.12
$p(s_5) = 0.1.$	F_3	0	0	0	0.5	1	$p(x_k \mid s_4)$	0.03	0.13	0.26	0.32	0.26
-	~*						$p(x_k \mid s_5)$	0	0.04	0.17	0.35	0.44

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(a) Probabilistic (uncertain) information:

	F ₁	\mathbf{F}_{2}	F ₃
x_1	0.620	0.373	0.007
x_2	0.468	0.49	0.042
<i>x</i> ₃	0.298	0.58	0.122
<i>x</i> ₄	0.15	0.571	0.279
<i>x</i> ₅	0.039	0.465	0.496

Posterior probabilities for probabilistic information with fuzzy states.

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information. (a) Probabilistic (uncertain) information: The expected utility values for each of the x_k can be calculated:

$$E(u_j \mid x_k) = \sum_{s=1}^n u_{js} p(\underline{F}_s \mid x_k),$$

Expected utilities for fuzzy alternatives with probabilistic information.

	A₁	${\operatorname{A}}_2$	A ₃
x_1	7.315	5.880	3.305
x_2	6.153	6.534	4.315
x_3	4.718	7.143	5.58
<i>x</i> ₄	3.216	7.413	6.934
<i>x</i> ₅	1.787	7.317	8.252

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.

(a) Probabilistic (uncertain) information: The expected utility values for each of the x_k can be calculated:

The optimum expected utilities: $E(u_{x_k}^*) = \max_j E(u_j | x_k) = \{7.315, 6.534, 7.143, 7.413, 8.252\}$ The unconditional expected utilities:

 $E(u_{\Phi}^*) = \sum_{k=1}^{r} E(u_{x_k}^*) p(x_k)$ = (7.315)(0.205) + (6.534)(0.252) + (7.143)(0.245)

+(7.413)(0.183) + (8.252)(0.115) = 7.202.

The value of the probabilistic uncertain information

V(x) = 7.202 - 6.8 = 0.402

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(b) Probabilistic perfect information:

$$p(\mathbf{E}_{s} \mid x_{k}) = \frac{\sum_{i=1}^{n} \mu_{\mathbf{E}_{s}}(s_{i}) p(x_{k} \mid s_{i}) p(s_{i})}{p(x_{k})} \qquad p(\mathbf{E}_{1} \mid x_{1}) = [(1)(1)(0.2) + (0.5)(0)(0.3]/(0.2) = 1.0$$

Conditional probabilities $p(x_{k} \mid s_{i})$ for fuzzy perfect information.

$p(s_1) = 0.2$	Ortho	ogonal f	uzzy sets	for fuzz	zy states.			x_1	x_2	<i>x</i> ₃	x_4	<i>x</i> ₅
$p(s_2) = 0.3$		<i>s</i> ₁	<i>s</i> ₂	<i>s</i> ₃	<i>s</i> ₄	\$5	$p(x_k \mid s_1)$	1	0	0	0	0
$p(s_3) = 0.3$	F.	1	0.5	0	0	0	$p(x_k \mid s_2)$	0	1	0	0	0
$p(s_4) = 0.1$	$\overset{F_1}{\sim}$	1		1		0	$p(x_k \mid s_3)$	0	0	1	0	0
-	$\underset{\mathbf{F}^2}{\overset{\mathbf{F}^2}}{\overset{\mathbf{F}^2}{\overset{\mathbf{F}^2}}{\overset{\mathbf{F}^2}}{\overset{\mathbf{F}^2}}{\overset{\mathbf{F}^2}}{\overset{\mathbf{F}^2}}{\overset{\mathbf{F}^2}}}{\overset{\mathbf{F}^2}{\overset{\mathbf{F}^2}}{\overset{\mathbf{F}^2}{\overset{\mathbf{F}^2}}{\overset{\mathbf{F}^2}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}$	0	0.5	1	0.5	0	$p(x_k \mid s_4)$	0	0	0	1	0
$p(s_5) = 0.1.$	\widetilde{E}_3	0	0	0	0.5	1	$p(x_k \mid s_5)$	0	0	0	0	1

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(b) Probabilistic perfect information:

Posterior probabilities for probabilistic *perfect* information with fuzzy states.

	\mathbf{E}_{1}	\mathbf{F}_2	F ₃
x_1	1.0	0.0	0.0
x_2	0.5	0.5	0.0
<i>x</i> ₃	0.0	1.0	0.0
<i>x</i> ₄	0.0	0.5	0.5
<i>x</i> ₅	0.0	0.0	1.0

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(b) Probabilistic perfect information:

The optimum expected utilities:

$$E(u_{x_k}^*) = \max_j E(u_j \mid x_k) = \{10.0, 6.5, 9.0, 8.5, 10.0\}$$

The unconditional expected utilities:

$$E(u_{x_p}^*) = \sum_{k=1}^{n} E(u_{x_p}^* | x_k) p(x_k)$$

$$= (10.0)(0.2) + (6.5)(0.3) + (9.0)(0.3) + (8.5)(0.1) + (10.0)(0.1)$$

Expected utilities for fuzzy alternatives with probabilistic *perfect* information.

	\mathbf{A}_1	\mathbf{A}_2	A₃
x_1	10.0	4.0	1.0
x_2	6.5	6.5	4.0
x_3	3.0	9.0	7.0
x_4	1.5	7.5	8.5
<i>x</i> ₅	0.0	6.0	10.0

= 8.5.

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.
(c) Fuzzy information:

$$p(\mathbf{F}_{s} \mid \mathbf{M}_{t}) = \frac{\sum_{i=1}^{n} \sum_{i=1}^{r} \mu_{\mathbf{F}_{s}}(s_{i}) \mu_{\mathbf{M}_{t}}(x_{k}) p(x_{k} \mid s_{i}) p(s_{i})}{\sum_{k=1}^{r} \mu_{\mathbf{M}_{t}}(x_{k}) p(x_{k})}.$$

 $p(\mathbf{F}_1 \mid \mathbf{M}_1) = [(1)(1)(0.44)(0.2) + (1)(0.4)(0.35)(0.2) + (0.5)(1)(0.26)(0.3)$ $+ (0.5)(0.4)(0.32)(0.3)] \div [(1)(0.205) + (0.4)(0.252)] = 0.57$

$p(s_1) = 0.2$	Ortho	Orthogonal fuzzy sets for fuzzy states.				Ortho	gonal fu	izzy sets	for fuzz	y inform	ation.	
$p(s_2) = 0.3$		<i>s</i> ₁	<i>s</i> ₂	<i>s</i> ₃	<i>s</i> ₄	<i>s</i> ₅		<i>x</i> ₁	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅
$p(s_3) = 0.3$	$\overline{F_1}$	1	0.5	0	0	0	$\underset{\sim}{M_{1}}$	1	0.4	0	0	0
$p(s_4) = 0.1$	\widetilde{F}_2	0	0.5	1	0.5	0	$\underset{\sim}{M_2}$	0	0.6	1	0.6	0
$p(s_5)=0.1.$	\widetilde{E}_3	0	0	0	0.5	1	M ₃	0	0	0	0.4	1

Conditional probabilities	$p(x_k \mid s_i)$	for uncertain	information.
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	<i>x</i> ₁	<i>x</i> ₂	<i>x</i> ₃	x_4	<i>x</i> ₅
$p(x_k \mid s_1)$	0.44	0.35	0.17	0.04	0
$p(x_k \mid s_2)$	0.26	0.32	0.26	0.13	0.03
$p(x_k \mid s_3)$	0.12	0.23	0.30	0.23	0.12
$p(x_k \mid s_4)$	0.03	0.13	0.26	0.32	0.26
$p(x_k \mid s_5)$	0	0.04	0.17	0.35	0.44

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(c) Fuzzy information:

Posterior probabilities for fuzzy information with fuzzy states.

	M_1	$\underset{\sim}{\mathbf{M}}_{2}$	M ₃
$\underset{\mathbf{F}}{\overset{\mathbf{F}_{1}}{\overset{\mathbf{F}_{2}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}{\overset{\mathbf{F}_{3}}{\overset{\mathbf{F}_{3}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}{\overset{\mathbf{F}_{3}}}}}}}}}}}}}}}}}}}}}}}}}}}}}}$	0.570	0.317	0.082
$\begin{array}{c} F_2\\ \widetilde{F}_3\\ \end{array}$	0.412 0.019	0.551 0.132	0.506 0.411

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(c) Fuzzy information:

The expected utilities: $n = \frac{n}{2}$

 $E(u_j | \underline{M}_t) = \sum_{s=1}^{n} u_{js} p(\underline{F}_s | \underline{M}_t)$ the optimum expected utility Posterior probabilities for fuzzy alternatives with fuzzy information.

	M_1	\widetilde{M}_2	M ₃
\mathbf{A}_1	6.932	4.821	2.343
A_2	6.096	7.019	7.354
$A_{\approx}3$	3.638	5.496	7.740

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(c) Fuzzy information:

The optimum expected utility: $E(u_{M_t}^*) = \max_j E(u_j | M_t) = \{6.932, 7.019, 7.740\}$ The marginal probabilities of the fuzzy information sets:

$$P(\mathbf{M}) = \sum_{k=1}^{r} \mu_{\mathbf{M}}(x_k) p(x_k)$$

Orthogonal fuzzy sets for fuzzy information.

	x_1	<i>x</i> ₂	<i>x</i> ₃	x_4	<i>x</i> ₅
M_1	1	0.4	0	0	0
$\widetilde{\mathrm{M}}_2$	0	0.6	1	0.6	0
\widetilde{M}_3	0	0	0	0.4	1

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(c) Fuzzy information:

The marginal probabilities of the fuzzy information sets: $P(\underline{M}) = \sum_{k=1}^{r} \mu_{\underline{M}}(x_k) p(x_k)$

Orthogonal fuzzy sets for fuzzy information.

	x_1	<i>x</i> ₂	<i>x</i> ₃	x_4	<i>x</i> ₅
$\mathop{\mathrm{M}}_{\simeq}$	1	0.4	0	0	0
M_2	0	0.6	1	0.6	0
M_3	0	0	0	0.4	1

	<i>x</i> ₁	<i>x</i> ₂	<i>x</i> ₃	<i>x</i> ₄	<i>x</i> ₅
$p(x_k)$	0.205	0.252	0.245	0.183	0.115

= 0.506

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.(c) Fuzzy information:

The unconditional expected utility:

 $p(\mathbf{M}_t) = \begin{bmatrix} 0.306\\ 0.506\\ 0.188 \end{bmatrix}$

$$E(u_{\Phi}^{*}) = \sum_{t=1}^{g} E(u_{M_{t}}^{*})p(M_{t}) = 7.128$$

$$V(\Phi) = 7.128 - 6.8 = 0.328$$

$$E(u_{\underline{M}_{t}}^{*}) = \max_{j} E(u_{j} \mid \underline{M}_{t}) = \{6.932, 7.019, 7.740\}$$

Calculation: Fuzzy states and actions

(ii) Utility and optimum decision given uncertain and perfect information.

(d) Fuzzy perfect information:

The optimum fuzzy action:

$$u(A_{E_s}^* \mid E_s) = \max_i u(A_i, E_s) = \{10.0, 9.0, 10.0\}$$

The unconditional expected utility:

$$E(u_{\Phi_p}^*) = \sum_{j=1}^{3} u(A_{\underline{F}_s}^* | \underline{F}_s) p(\underline{F}_s) = 10(0.35) + 9(0.5) + 10(0.15) = 9.5$$

The value of fuzzy perfect information is 2.7

 $u(\underset{\sim}{\mathbf{A}_i} | \underset{\sim}{\mathbf{F}_s}) = u(\underset{\sim}{\mathbf{A}_i}, \underset{\sim}{\mathbf{F}_s})$

Expected utilities for fuzzy alternatives with fuzzy perfect information.

	F ₁	\mathbf{F}_{2}	₽ ₃
$\mathop{A}\limits_{\approx 1}$	10.0	3.0	0.0
${\operatorname{A}}_2$	4.0	9.0	6.0
A_3	1.0	7.0	10.0

Summary:

Information	Expected utility	Value of information
No information	6.8	_
Probabilistic information, $V(x)$	7.20	0.40
Perfect information, $V(x_p)$	8.5	1.7
Fuzzy probabilistic information, $V(\Phi)$	7.13	0.33
Fuzzy perfect information, $V(\Phi_p)$	9.5	2.7

Summary of expected utility and value of information for fuzzy states and actions for the example.